

# Foundations of large-scale “doubly-sequential” experimentation

(KDD tutorial in Anchorage, on 4 Aug 2019)



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[www.stat.cmu.edu/~aramdas/kdd19/](http://www.stat.cmu.edu/~aramdas/kdd19/)

A/B-testing : tech :: clinical trials : pharma

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Much has been discussed about doing A/B testing the “right” way, both theoretically and practically in real-world systems.

Many companies contributing to this vast and growing literature.

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How many of you have read papers on A/B testing and know what it is, but want to know more?

How many have no idea what I'm talking about?

Users of app or website



50%

50%

A



B



Users of app or website



50%

50%

A



44 conversions

B



71 conversions

Users of app or website



50%

50%

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B wins!



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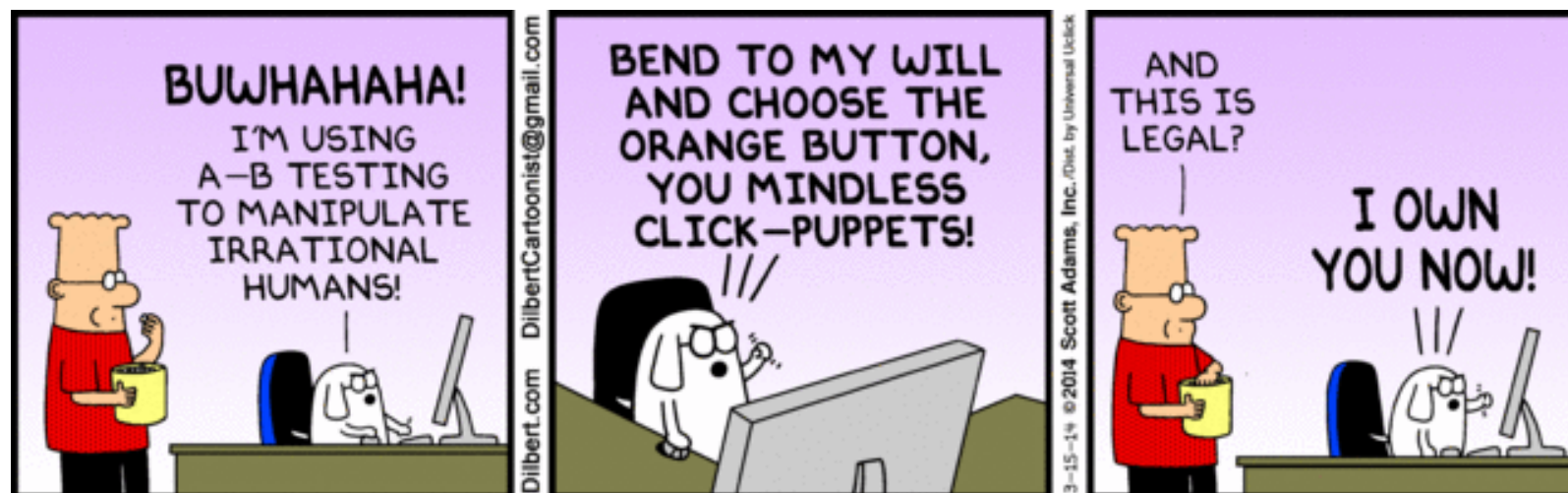
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# There are many resources for these topics

Yandex tutorial at The Web Conference '18

Microsoft tutorial at The Web Conference '19  
(+ ExP Platform webpage)

Blog posts by Evan Miller, Etsy, Optimizely, etc.

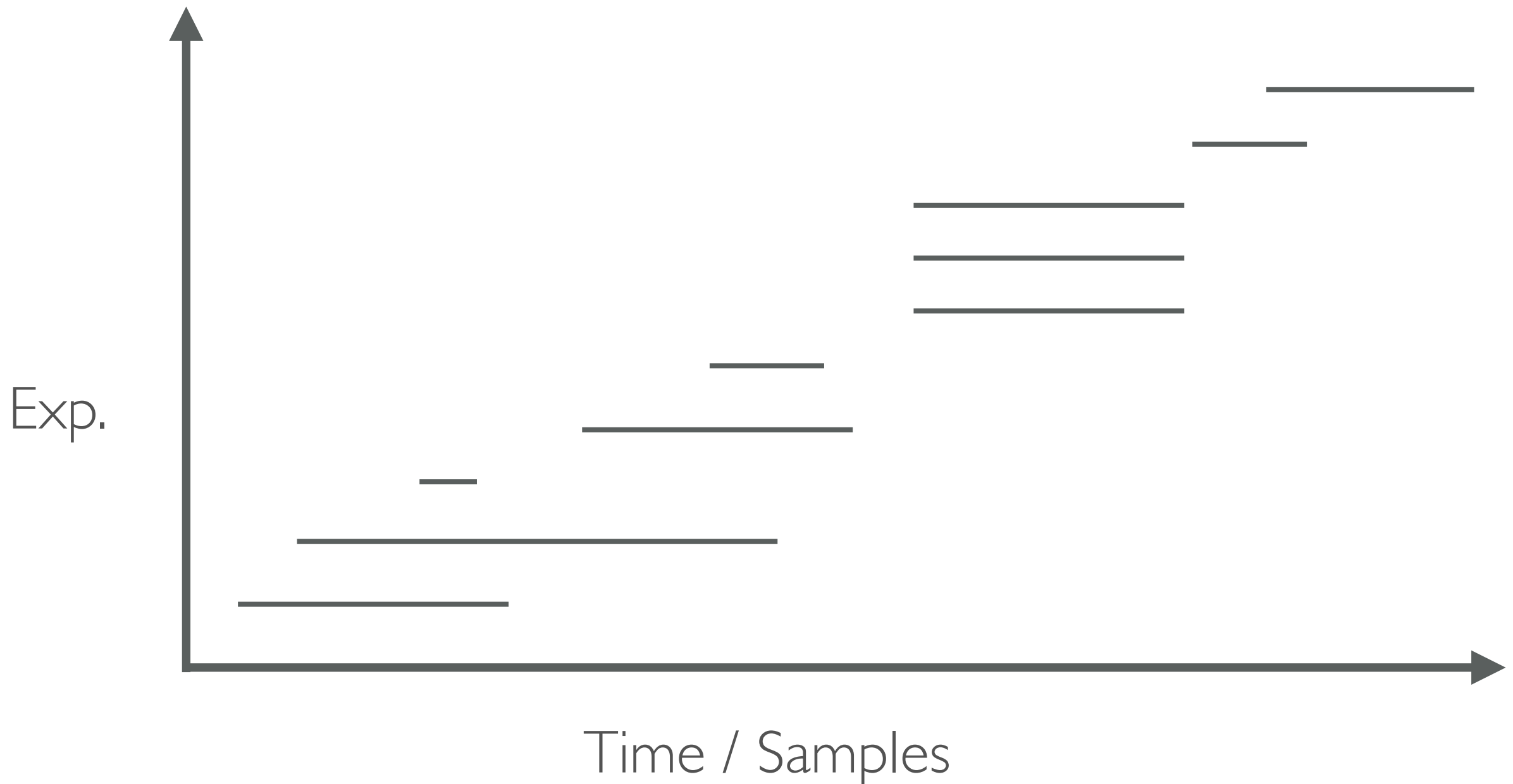
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**A new “doubly-sequential” perspective:  
a sequence of sequential experiments**

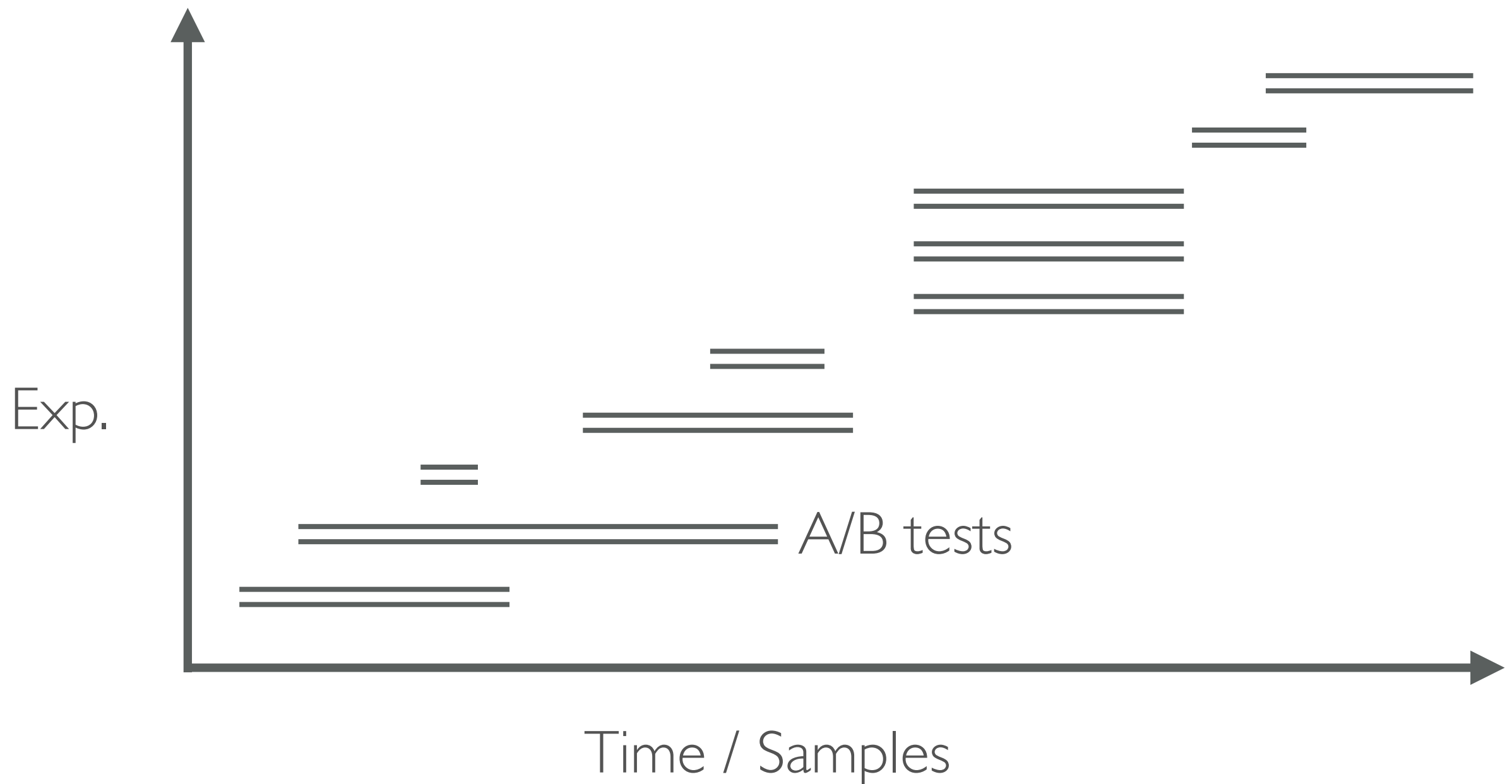
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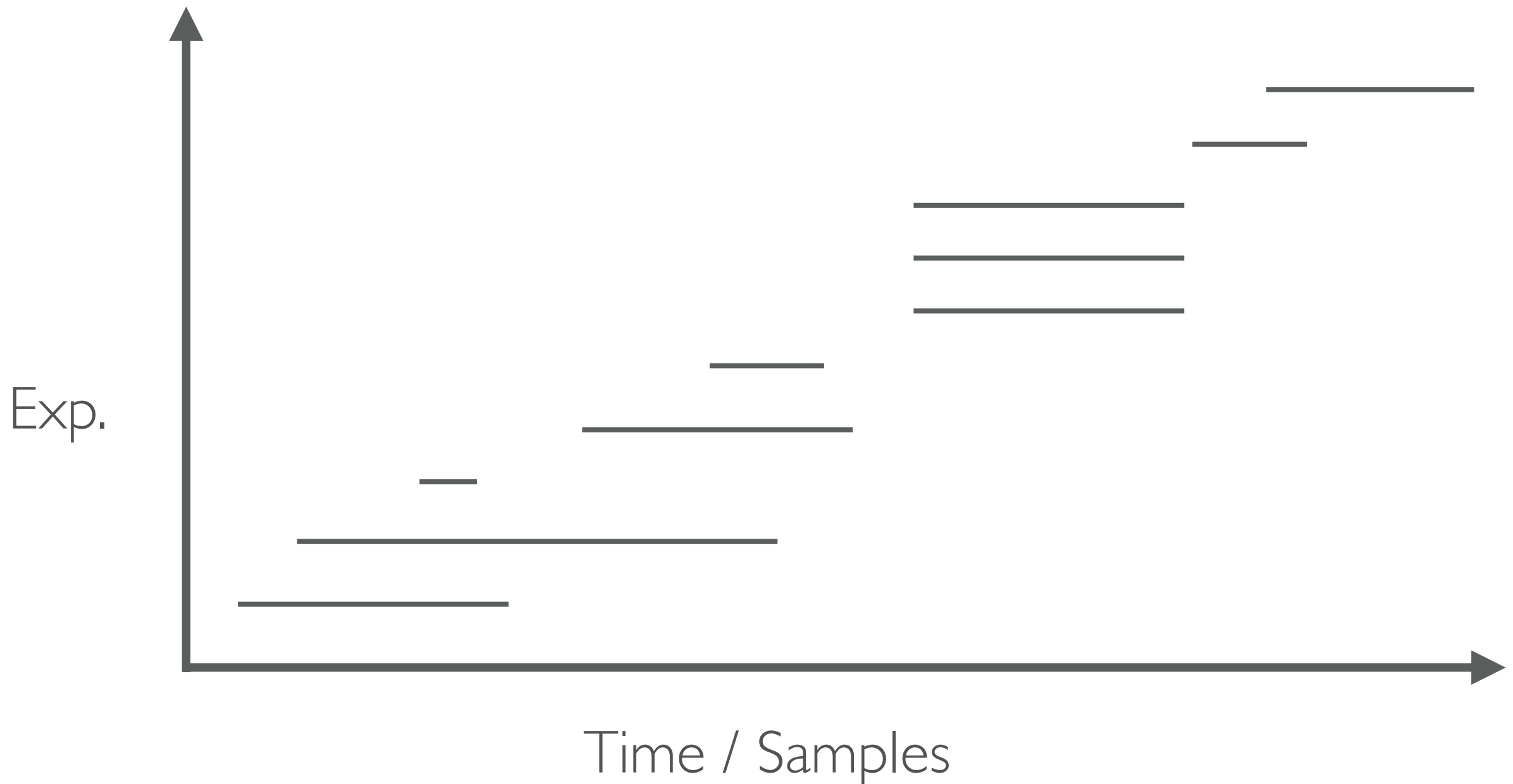
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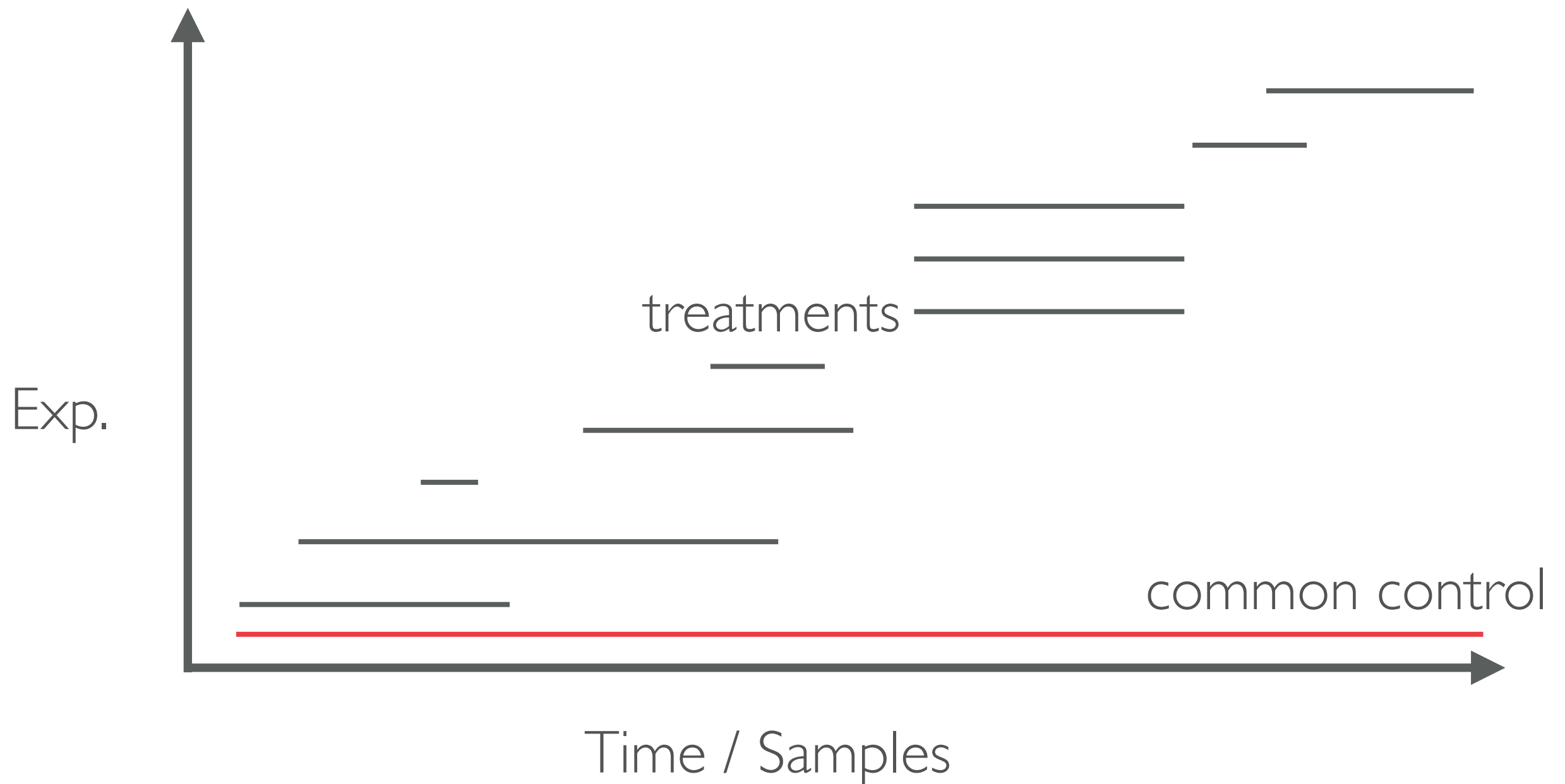


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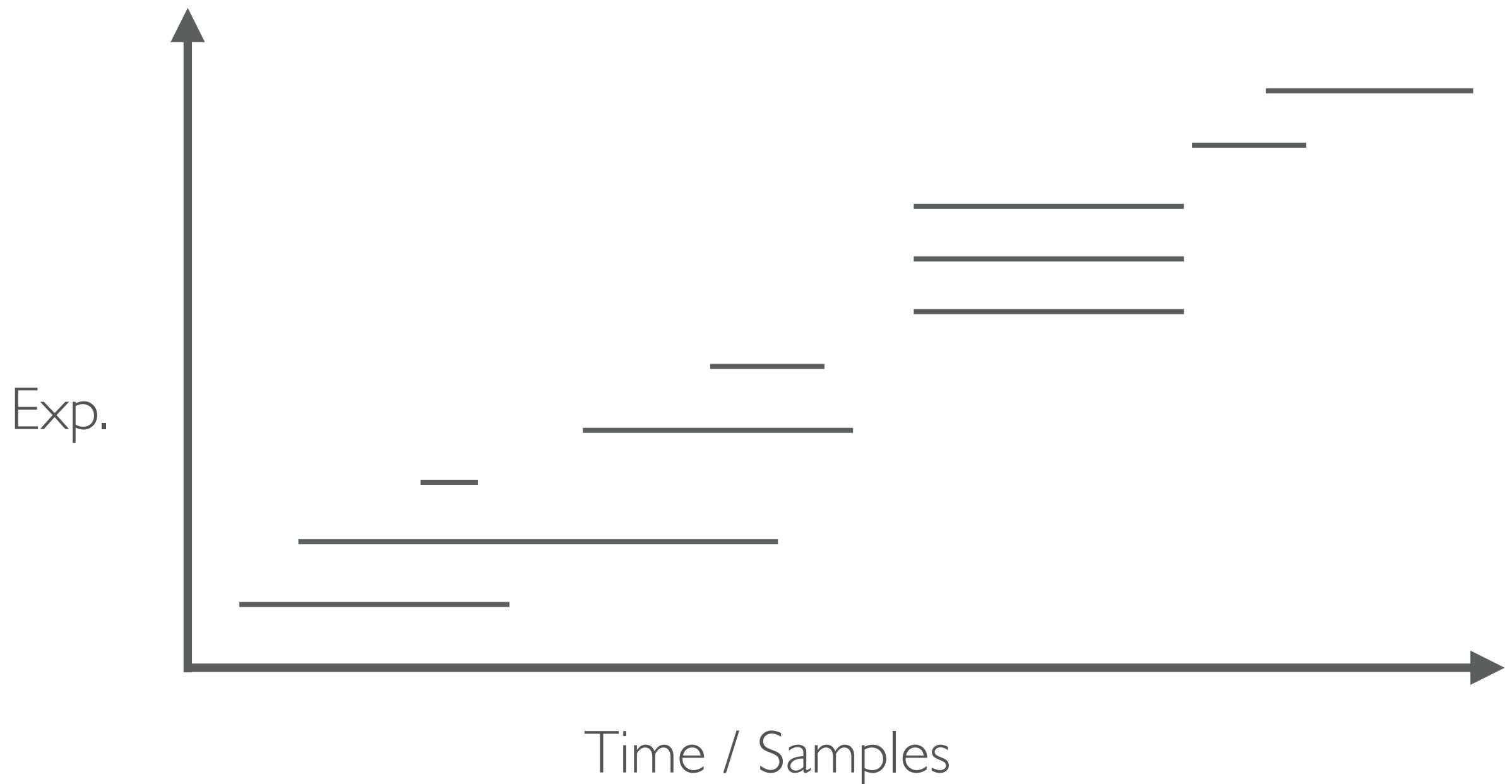




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Zrnic, Ramdas, Jordan '18  
Yang, Ramdas, Jamieson, Wainwright '17

*What kind of guarantees would we like  
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(a) ***inner sequential process (a single experiment)***

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(b) ***outer sequential process (multiple experiments)***

— less clear (is error control on inner process enough?!) )

**Some existing problems in practice**

**Some potential issues **within** each experiment**

**Some potential issues **across** experiments**

**Many other concerns as well**

**Some existing problems in practice**

**Some potential issues *within* each experiment**

- (a) *continuous monitoring*
- (b) *flexible experiment horizon*
- (c) *arbitrary stopping (or continuation) rules*

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# Some existing problems in practice

## Some potential issues **within** each experiment

- (a) *continuous monitoring*
- (b) *flexible experiment horizon*
- (c) *arbitrary stopping (or continuation) rules*

## Some potential issues **across** experiments

- (a) *selection bias (multiplicity)*
- (b) *dependence across experiments*
- (c) *don't know future outcomes*

**Many other concerns as well**



## Solutions for these issues

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Inner sequential process:

Part I

***“confidence sequence” for estimation***  
***also called “anytime confidence intervals”***  
***(correspondingly, “always valid  $p$ -values” for testing)***

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***“false coverage rate” for estimation***  
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Outer sequential process:

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**Modular solutions: fit well together**  
**Many extensions to each piece**

Part III

## Part I

# The INNER Sequential Process (a single experiment)

[1 hour]

The “duality” between  
confidence intervals and p-values

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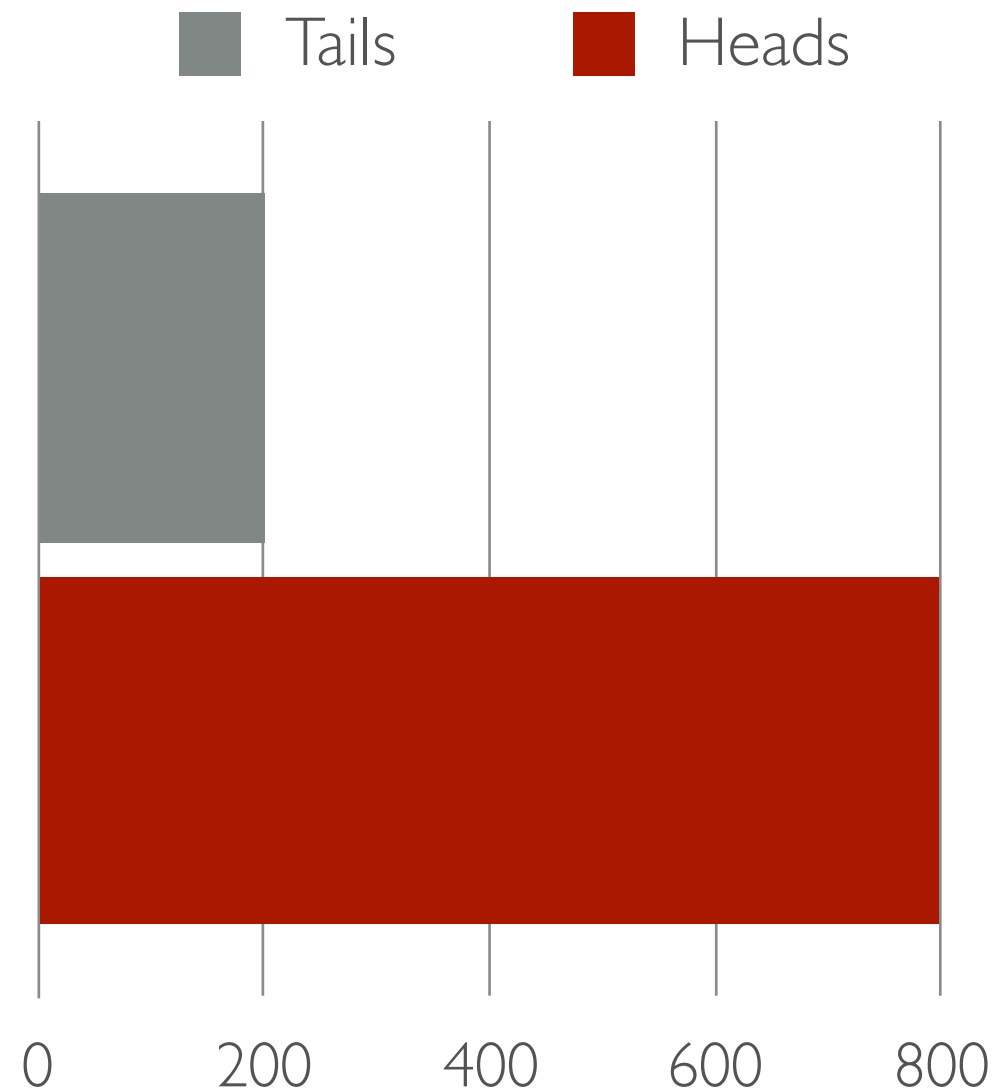
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The coin is fair (bias = 0)

Alternative:  
Coin is biased towards H

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1 000 tosses



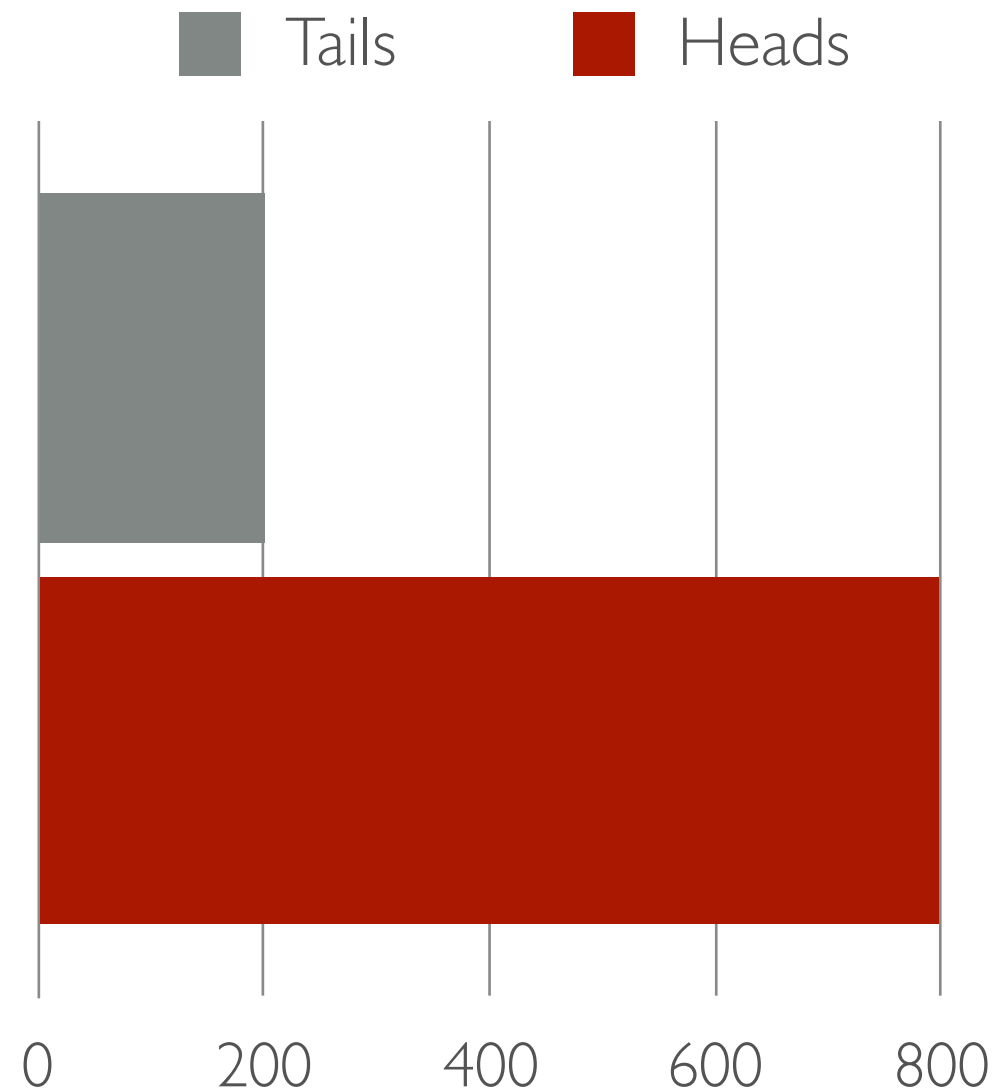
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Apparent contradiction!  
Should we reject the null hypothesis?

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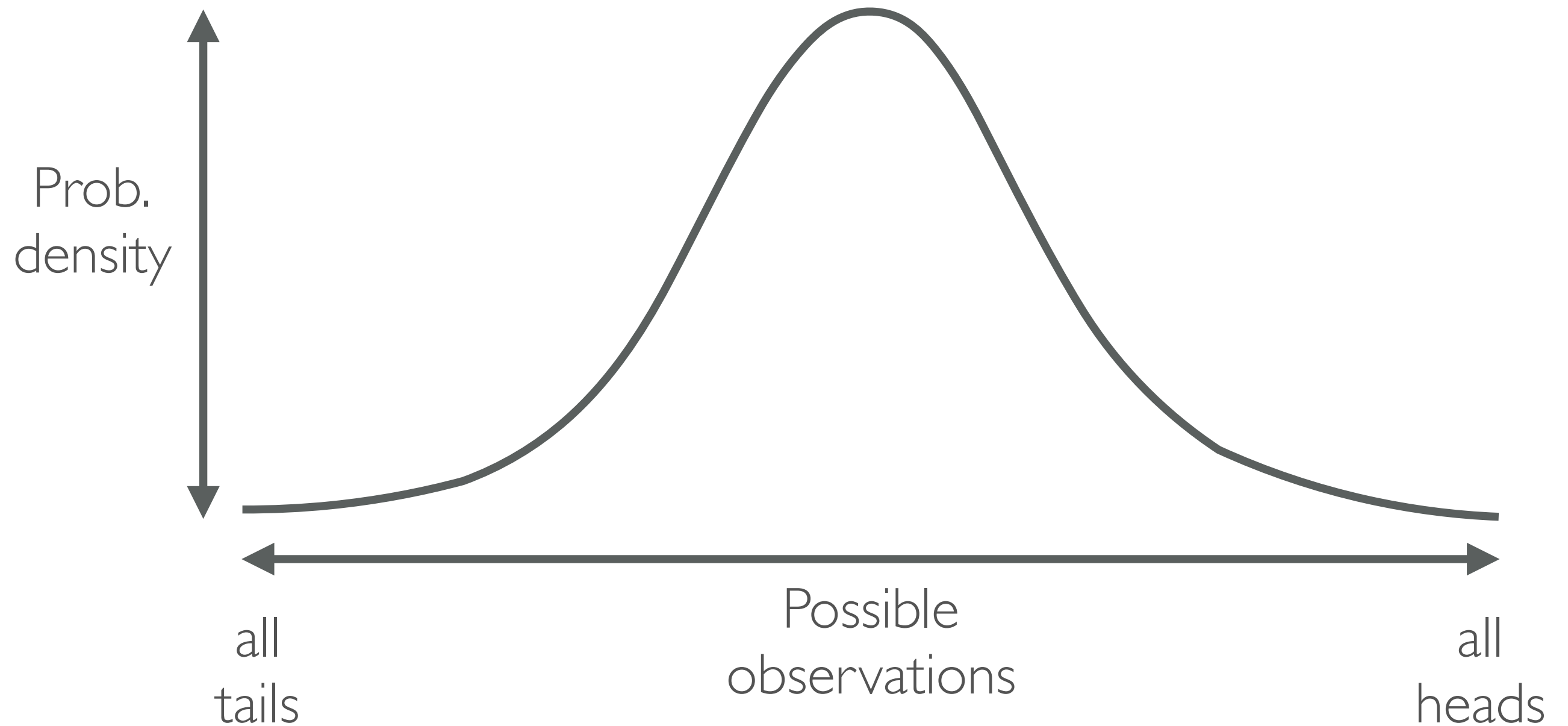


Possible  
observations

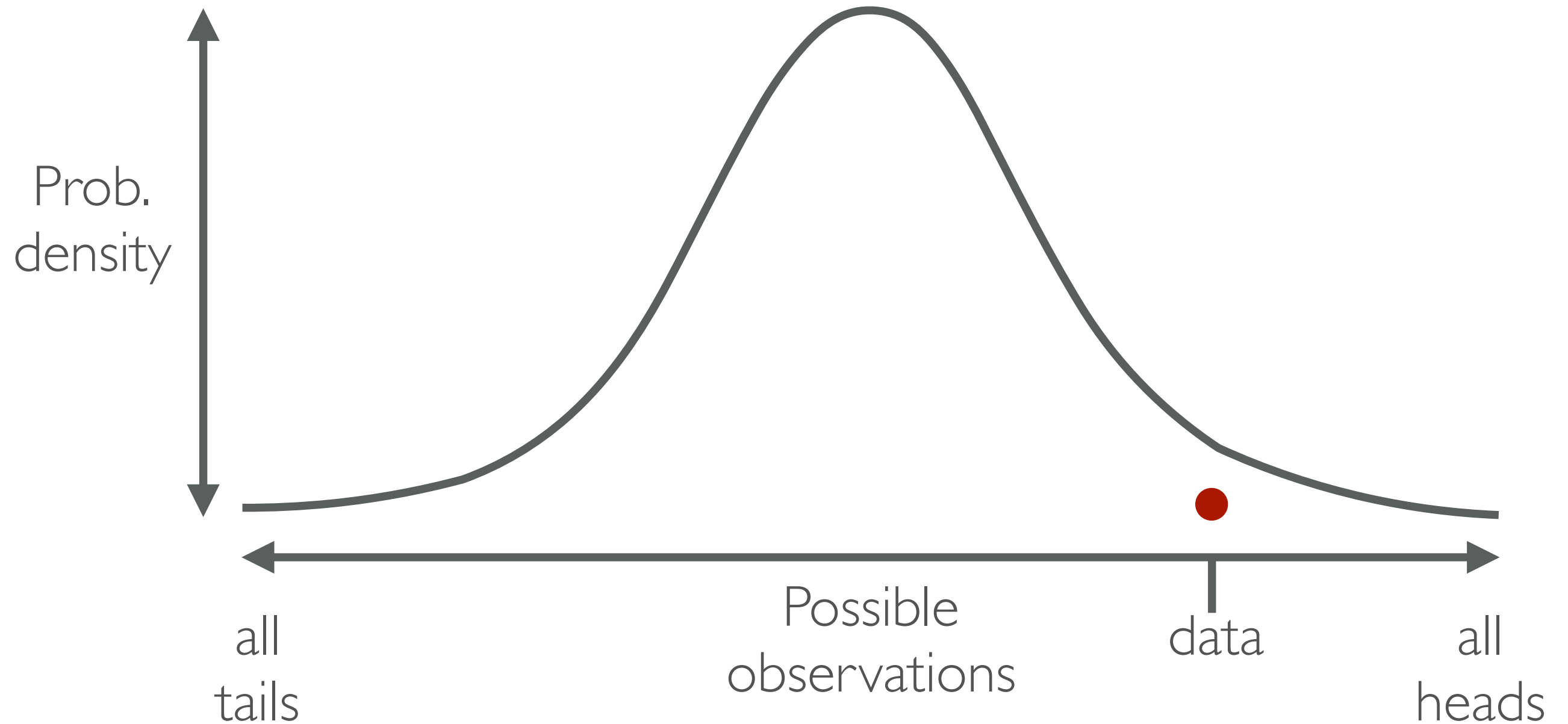
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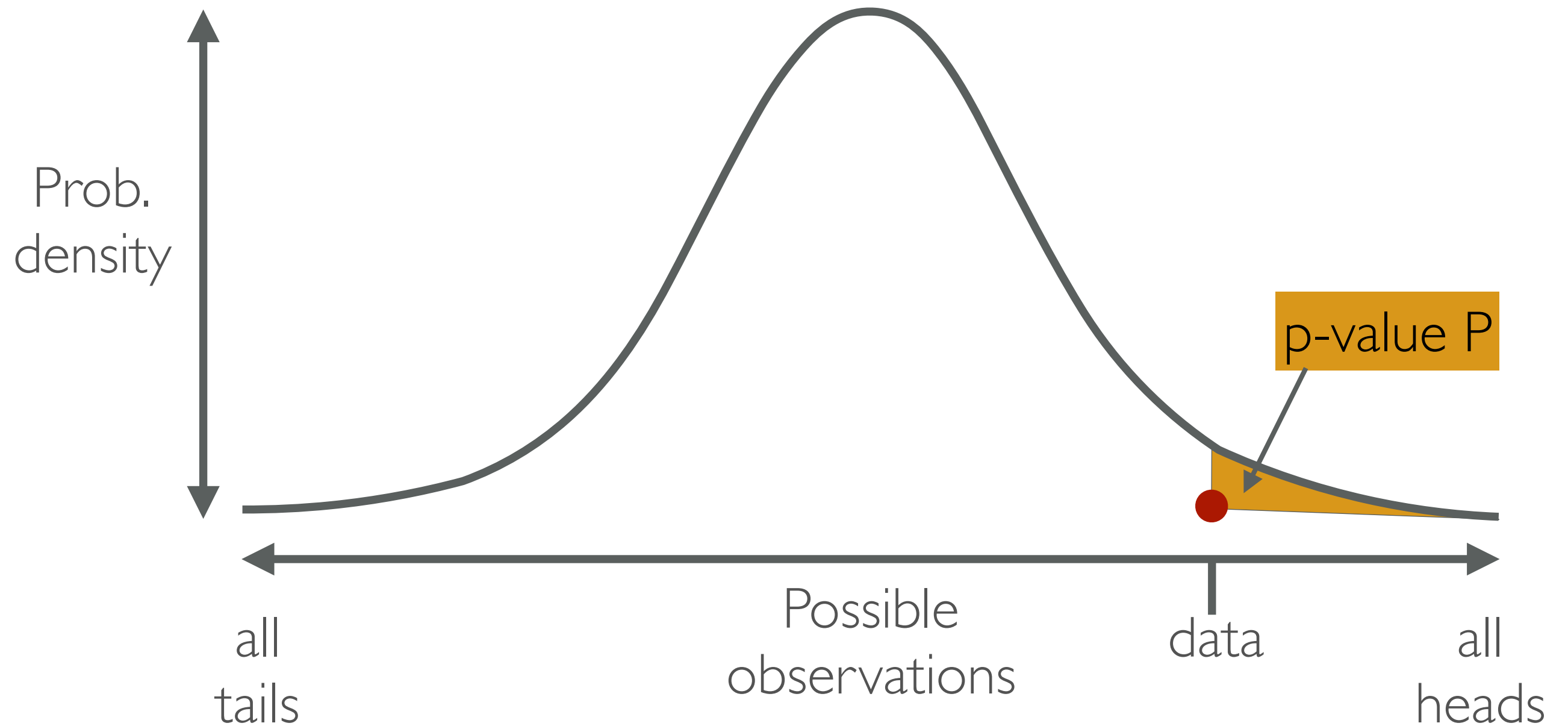


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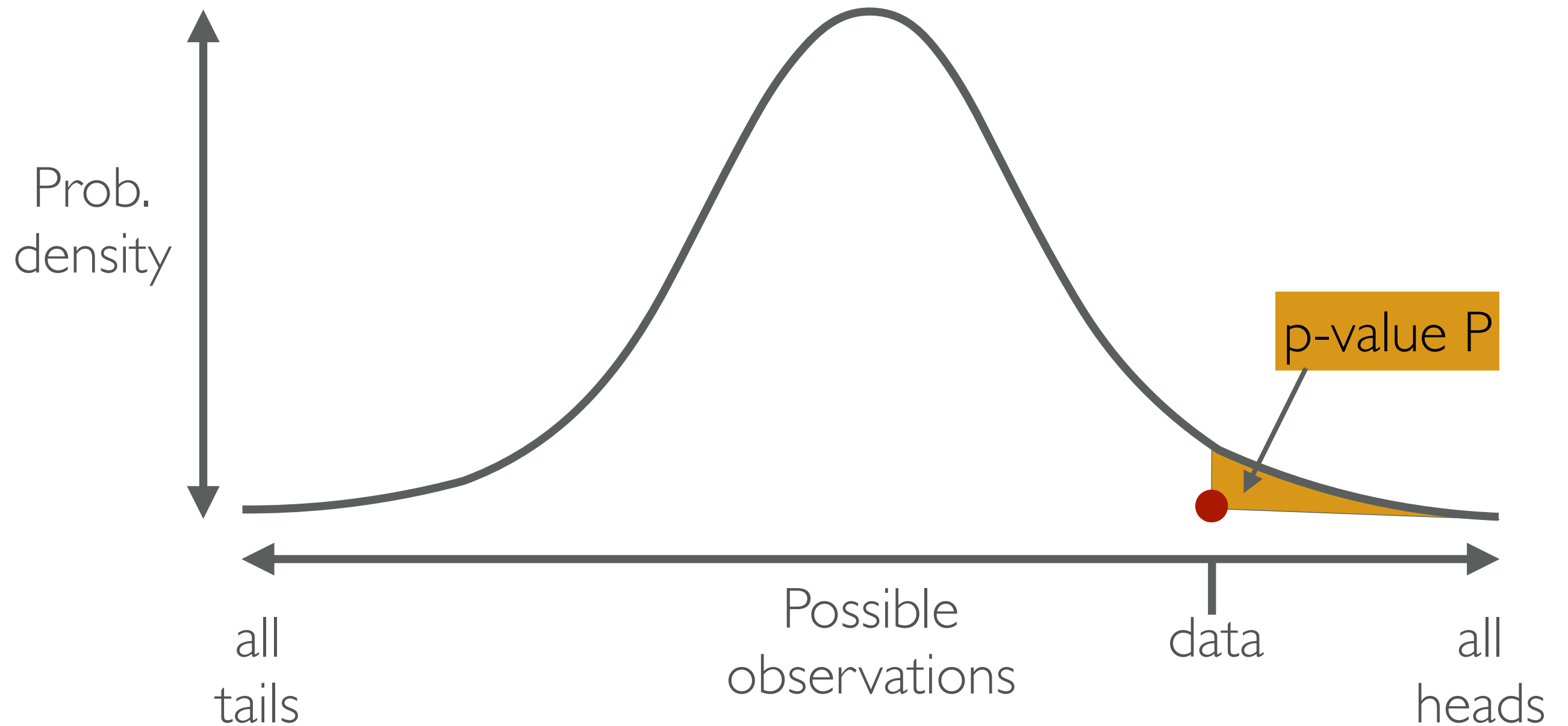




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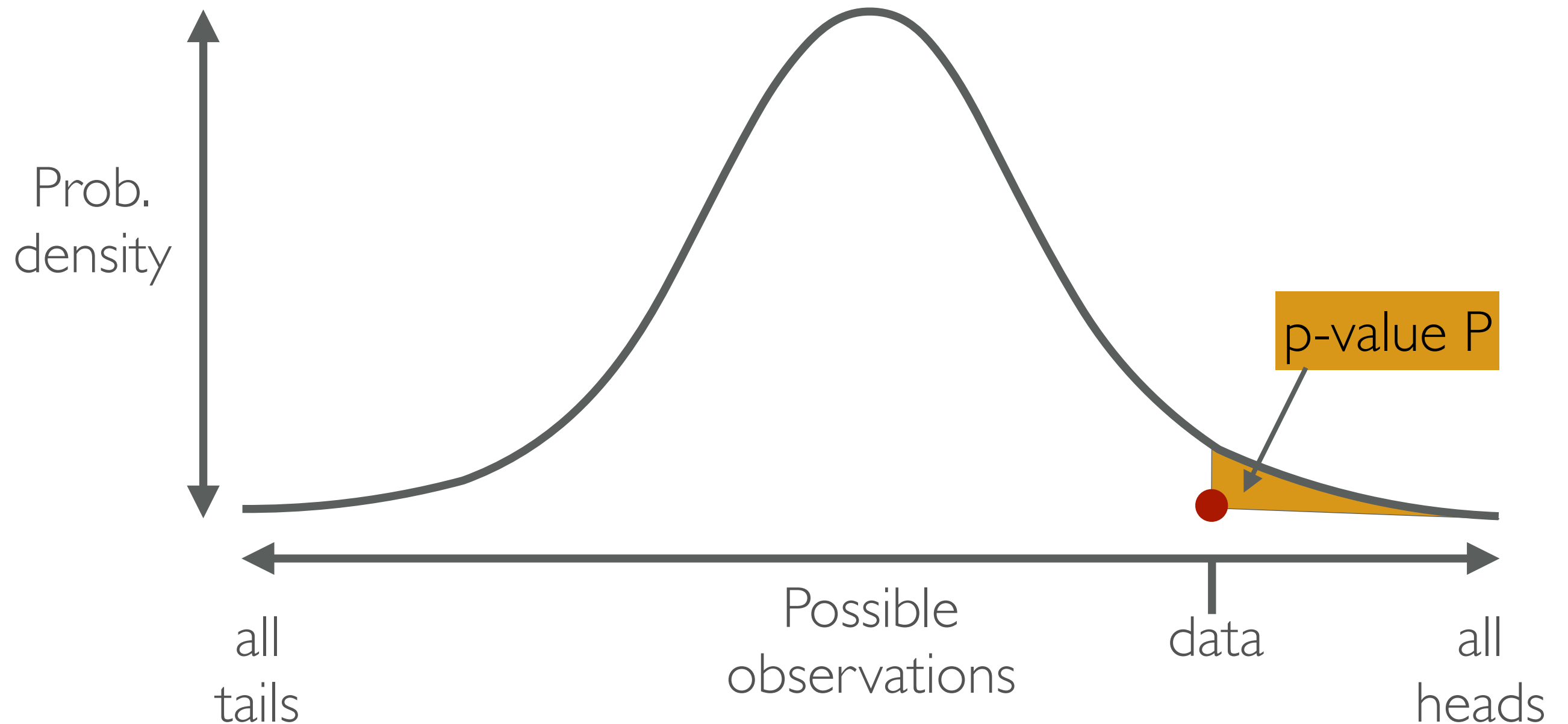


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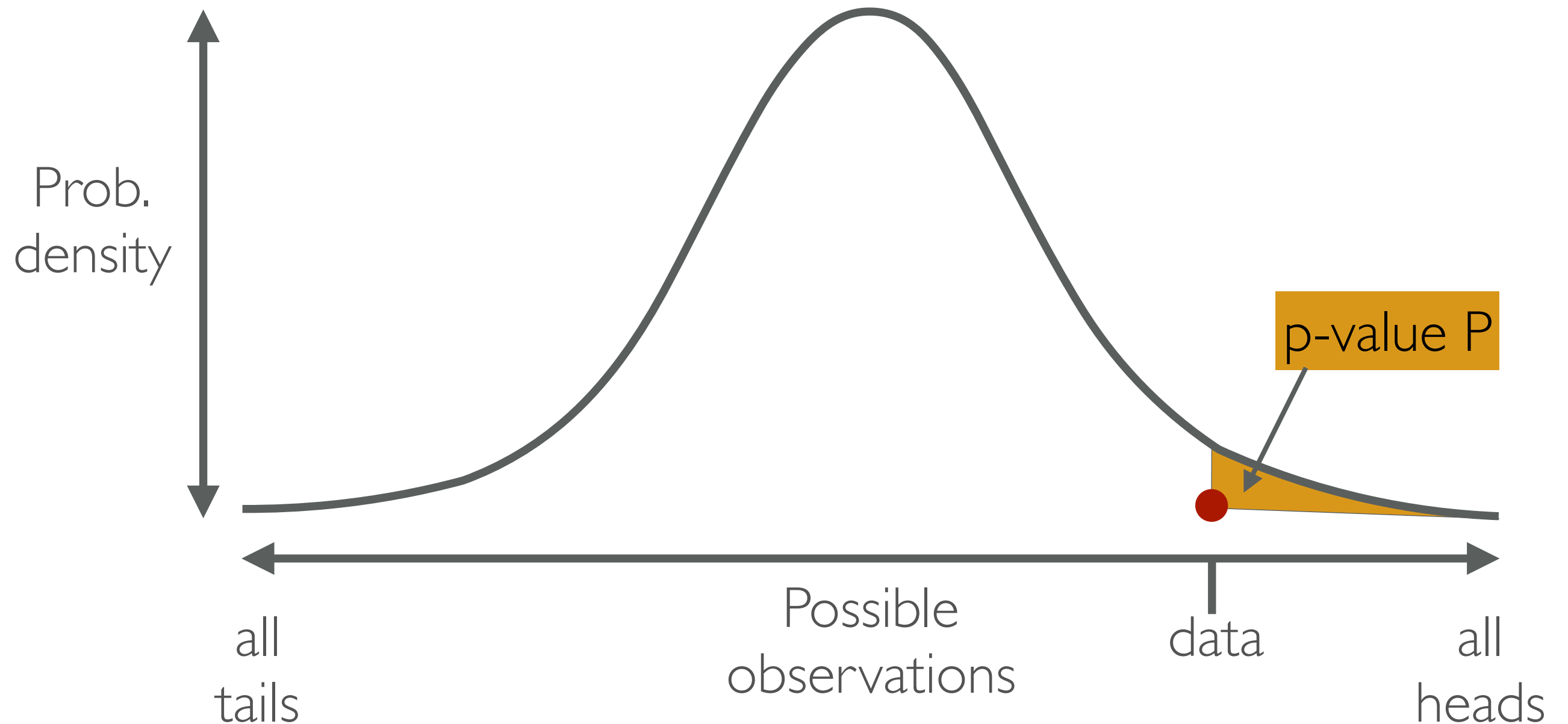
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Then,  $\Pr(\text{false positive}) \leq \alpha$ .

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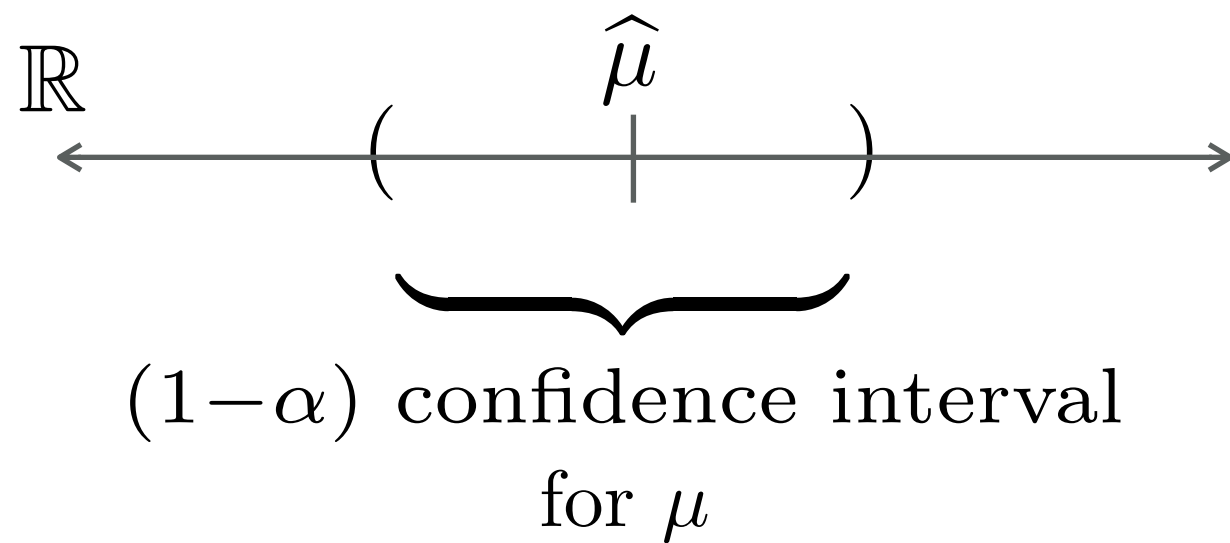
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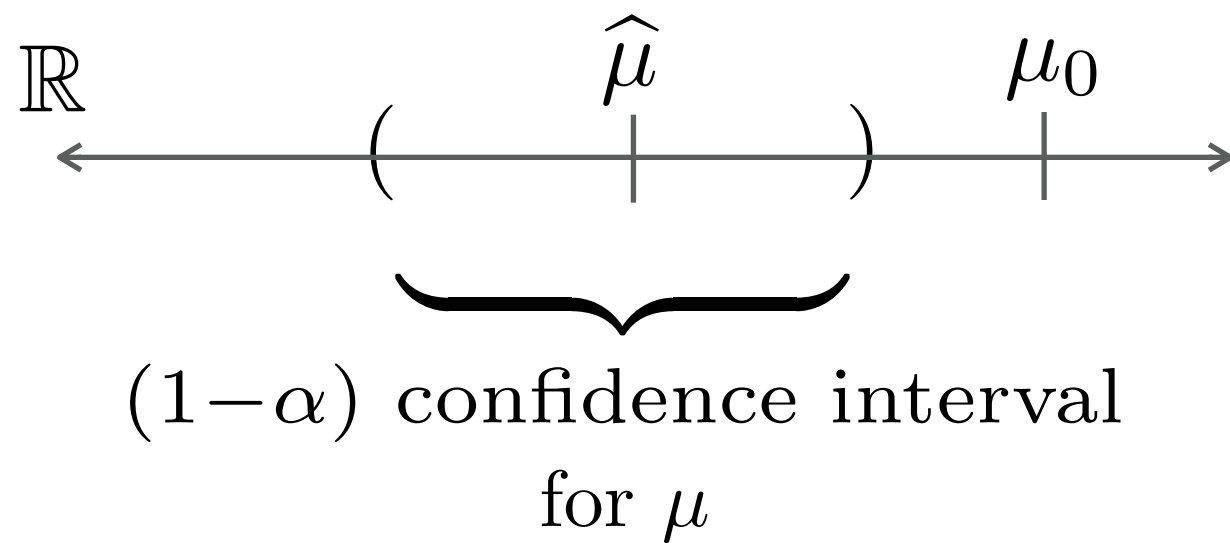
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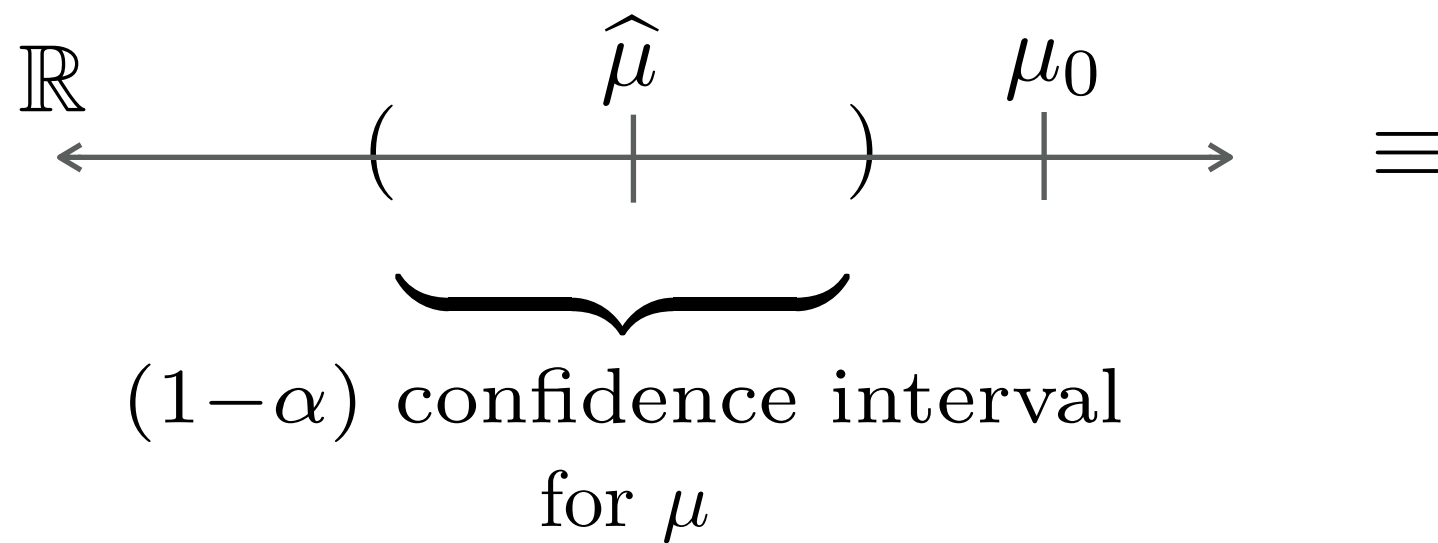
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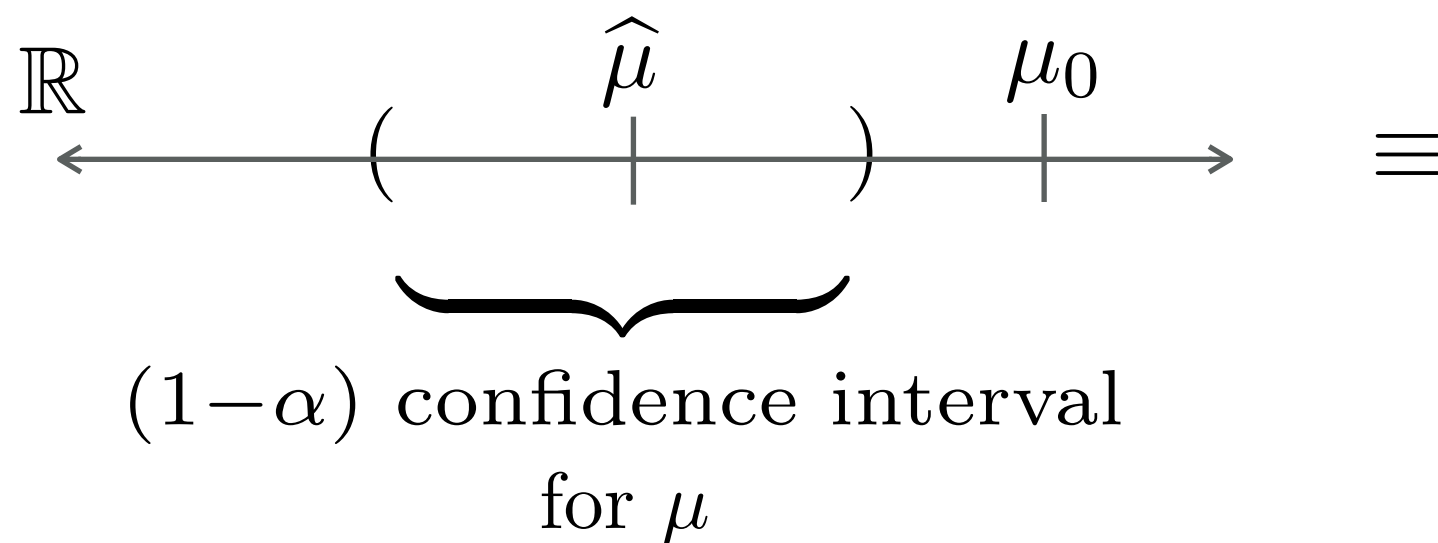
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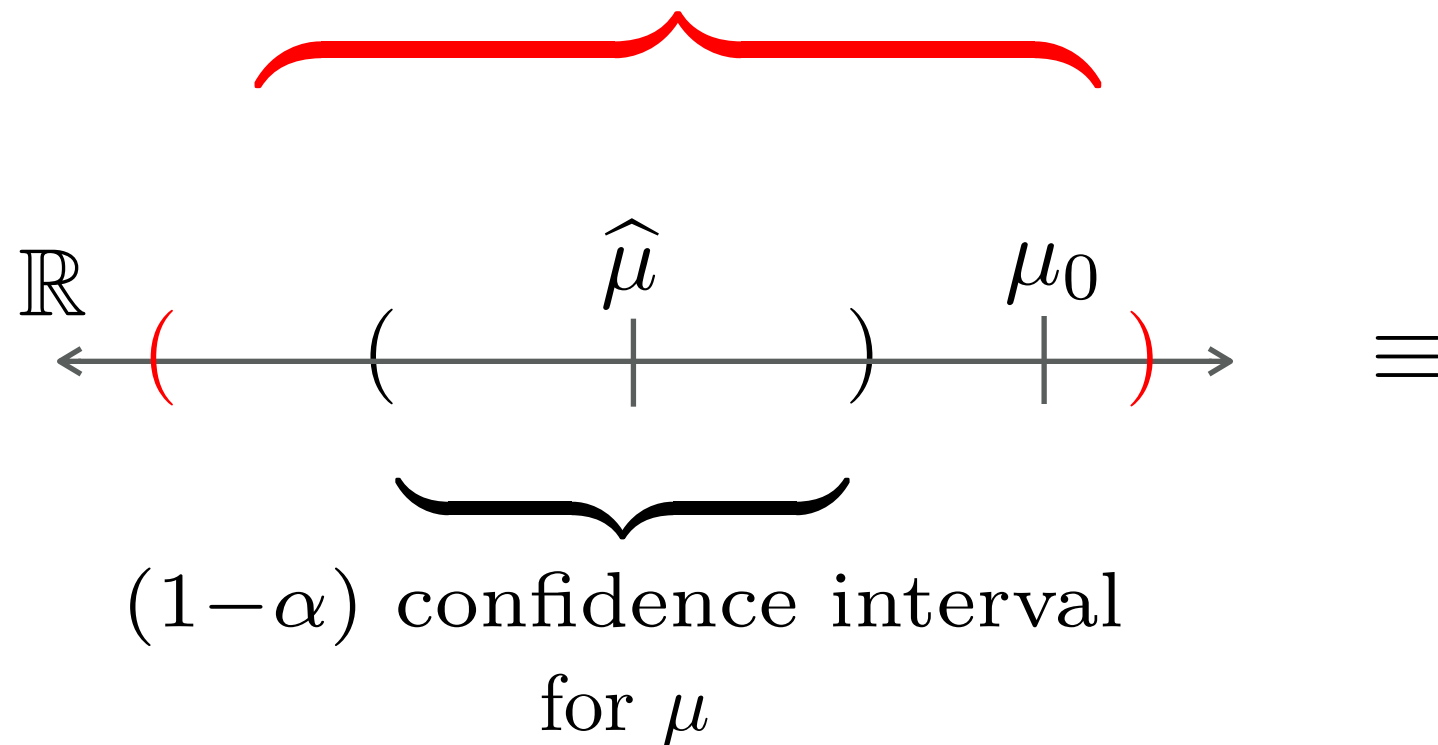


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$(1-\alpha/2)$  confidence interval



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Both of them are useful tools to estimate uncertainty, and like any other tool, they can be used well, or be misused.

However, commonly taught confidence intervals and p-values are only valid (correctly control error) if the sample size is fixed in advance.

# High-level caricature of an A/B-test

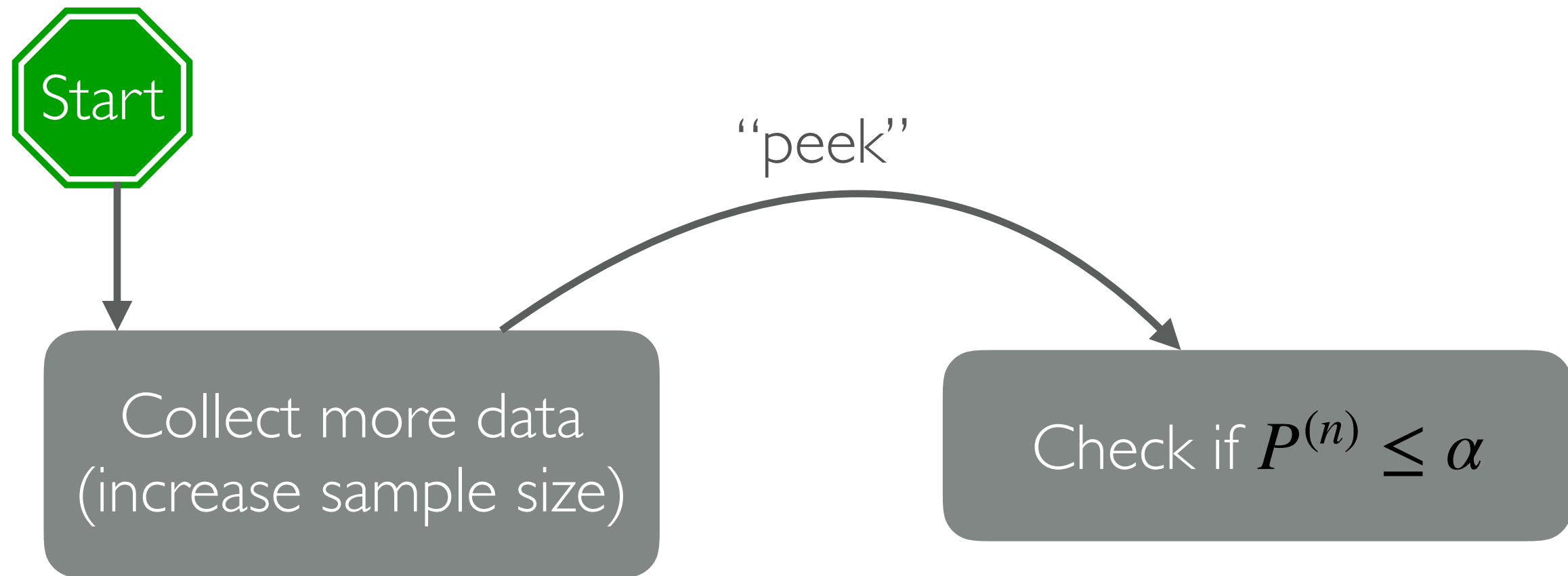


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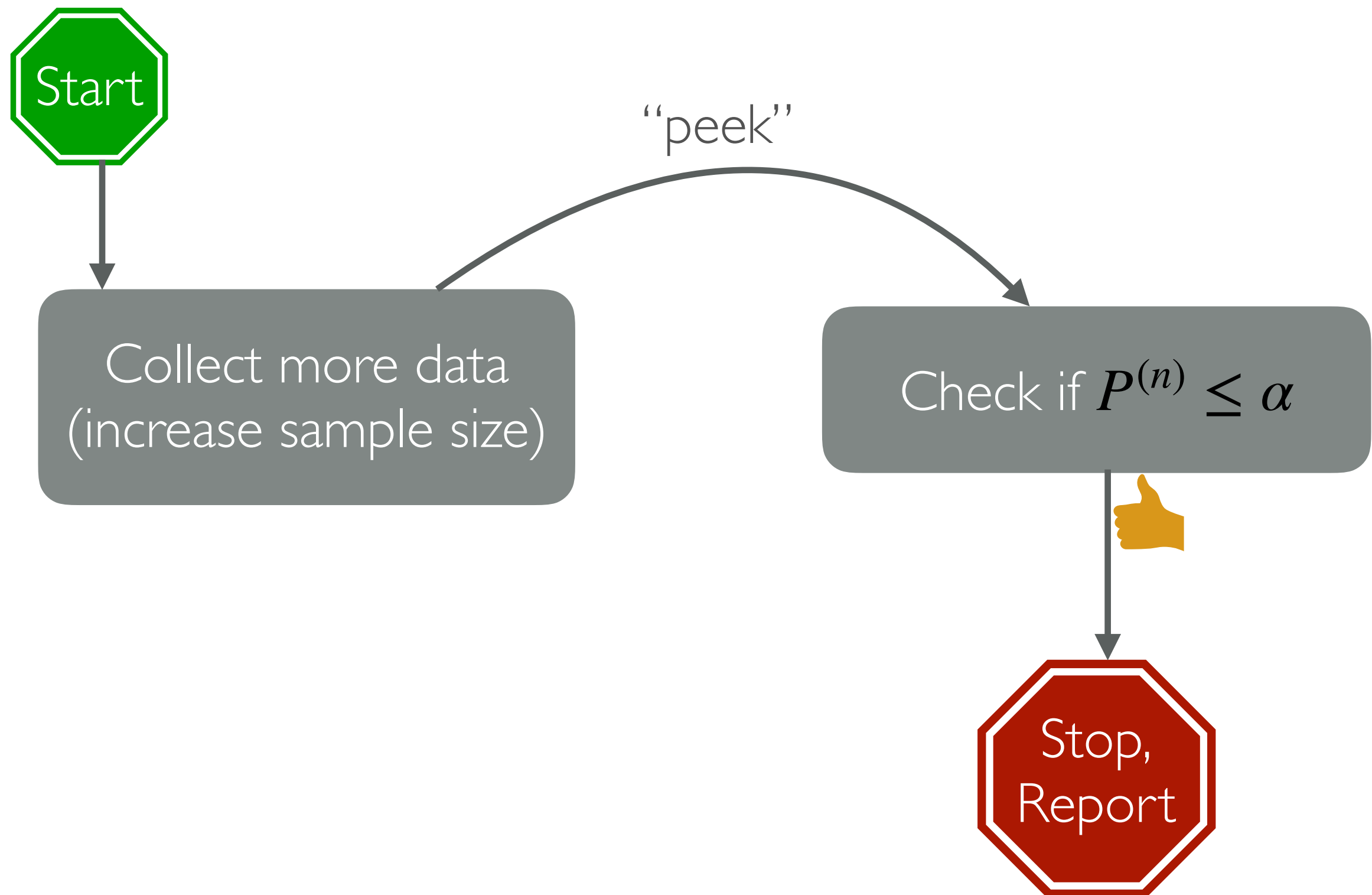


Collect more data  
(increase sample size)

# High-level caricature of an A/B-test

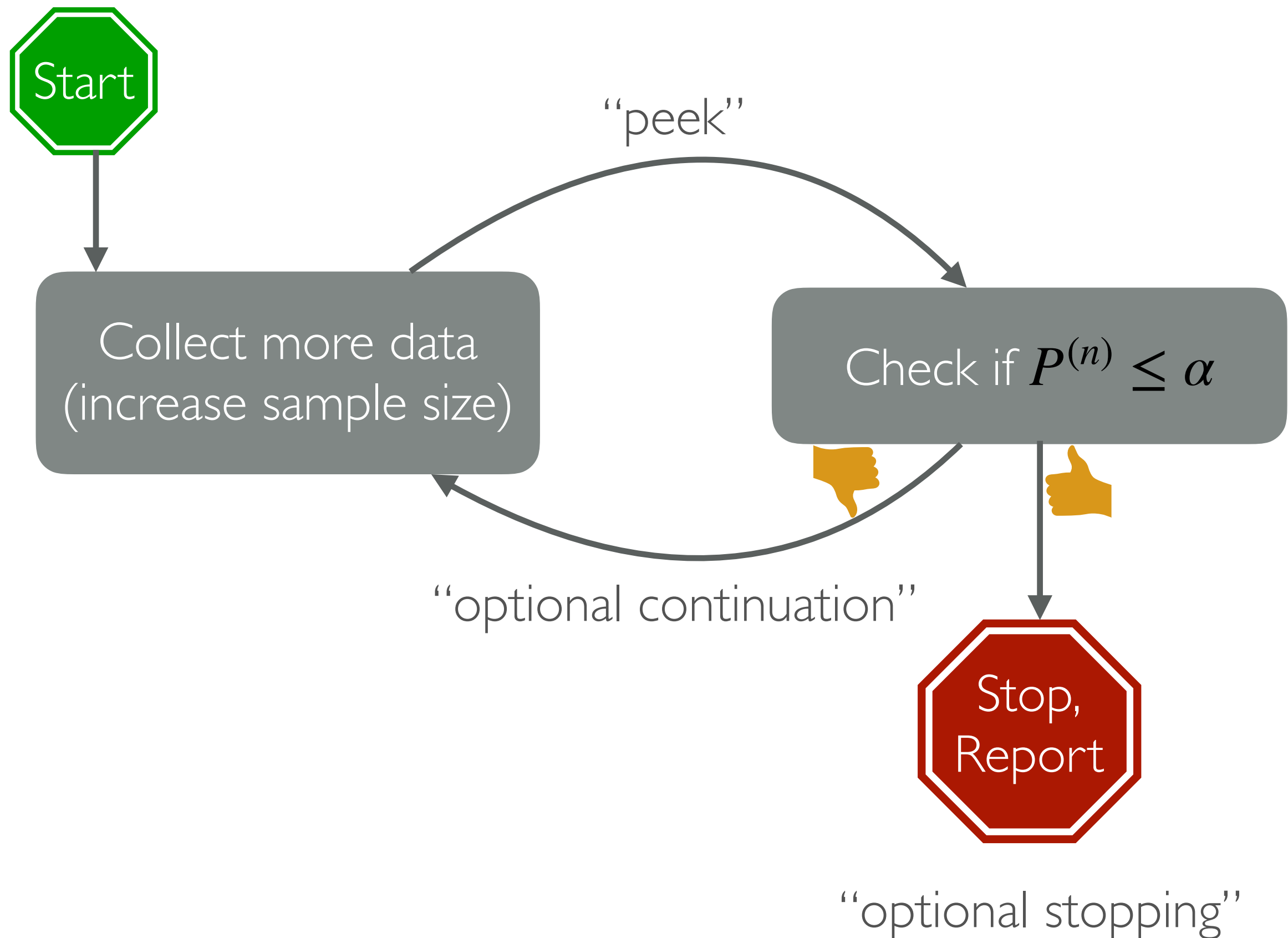


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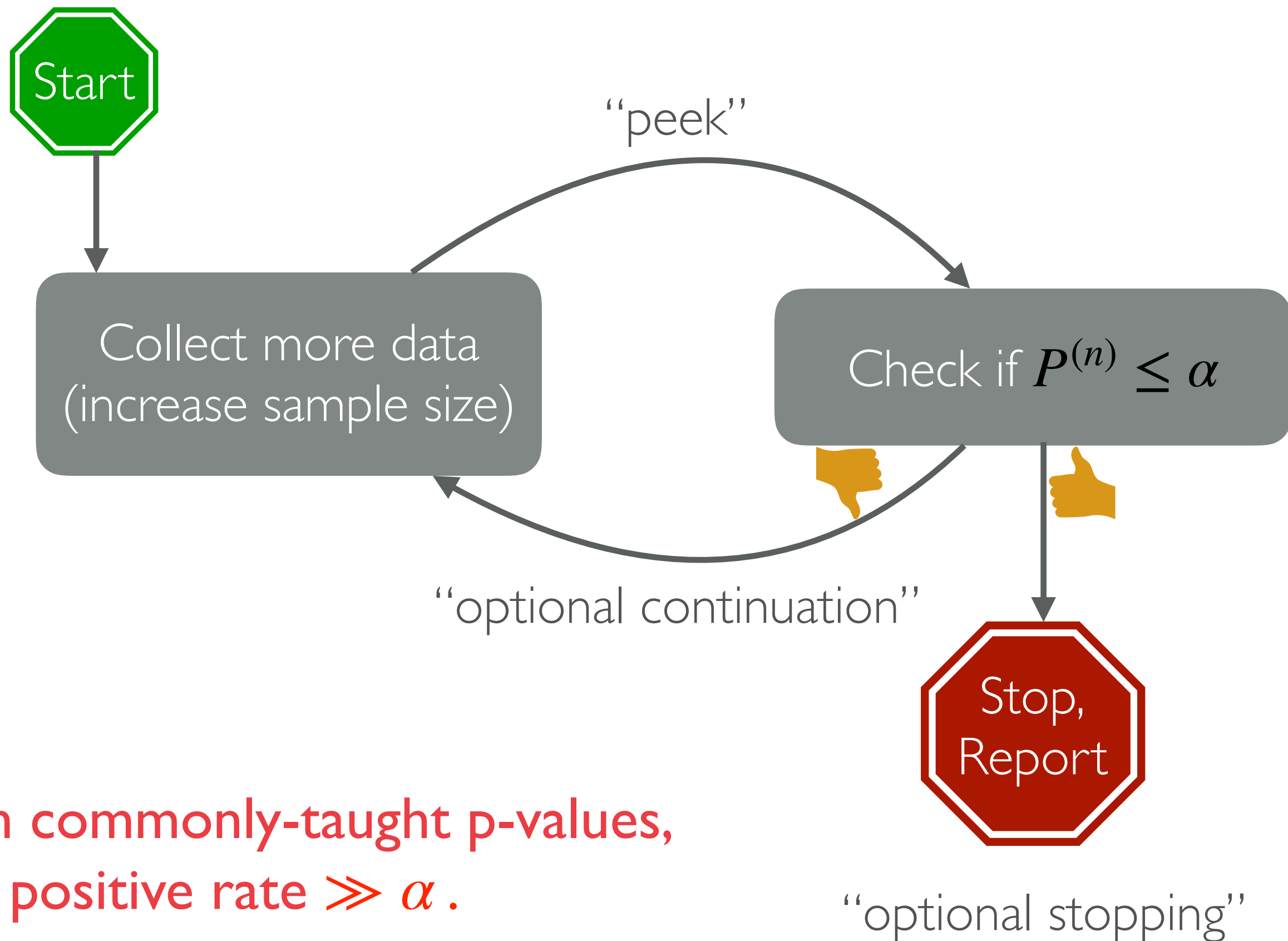


"optional stopping"

# High-level caricature of an A/B-test



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With commonly-taught p-values,  
false positive rate  $\gg \alpha$ .







After 10 people



~~$P < 0.05$~~

After 10 people



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After 10 people

After 284 people



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After 11,219 people, STOP!



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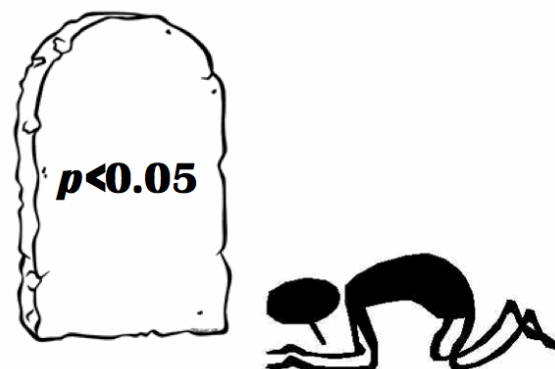
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Often,  $\tau$  depends on data, eg:  $\tau := \min\{n \in \mathbb{N} : P_n \leq \alpha\}$  .

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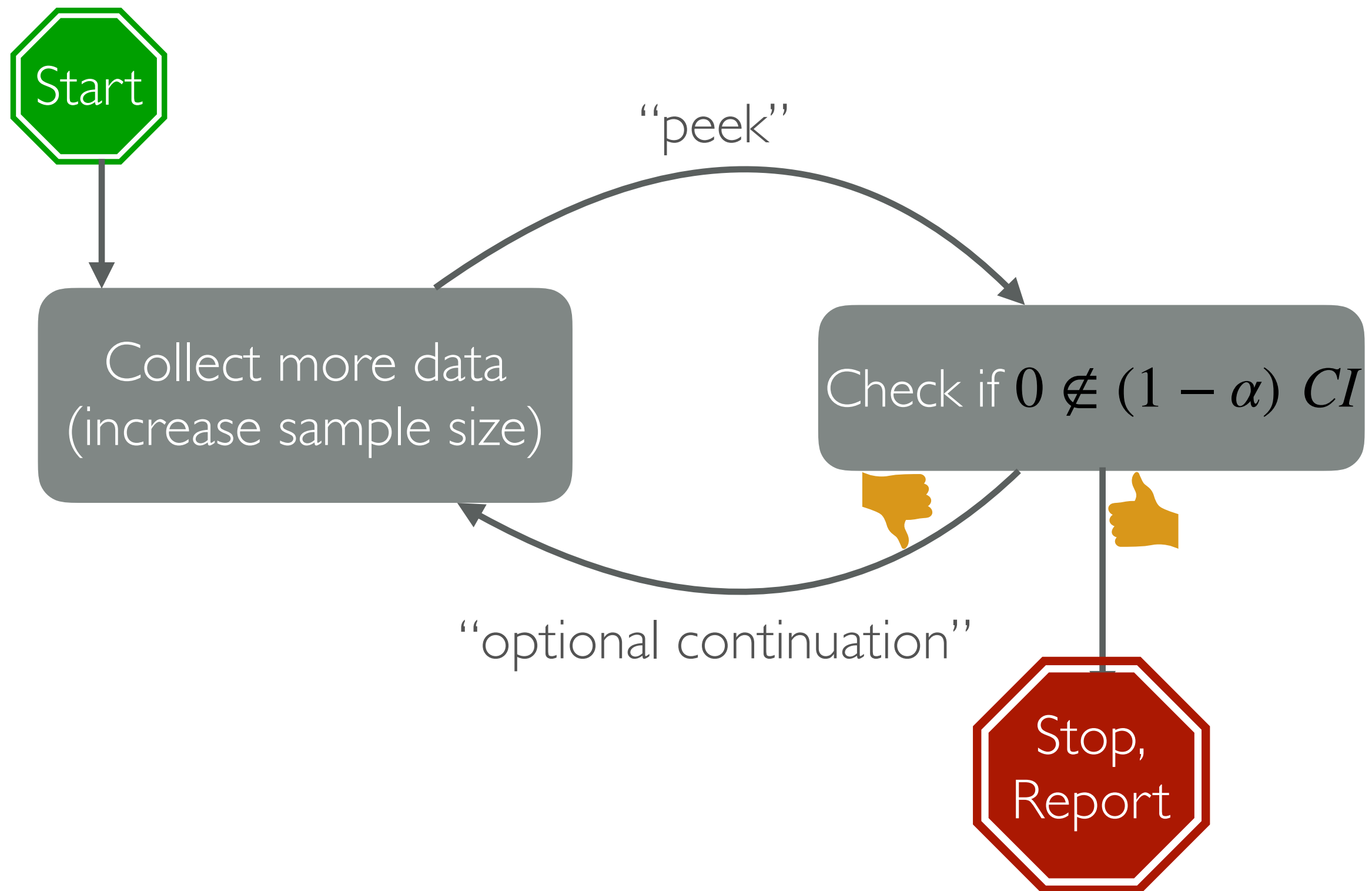
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Often,  $\tau$  depends on data, eg:  $\tau := \min\{n \in \mathbb{N} : P_n \leq \alpha\}$ .

Unfortunately,  $\Pr(P^{(\tau)} \leq \alpha) \not\leq \alpha$ .

In other words,  $\Pr(\exists n \in \mathbb{N} : P^{(n)} \leq \alpha) \gg \alpha$ .

# Same problem with confidence interval (CI)



Again, false positive rate  $\gg \alpha$ .

"optional stopping"

Let  $(L^{(n)}, U^{(n)})$  be any classical  $(1 - \alpha)$  CI,  
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In other words,  $\Pr(\forall n \geq 1 : \theta \in (L^{(n)}, U^{(n)})) \ll 1 - \alpha$ .  
usually = 0.

**Solution:** “confidence sequence”  
(aka “anytime confidence intervals”)

or “sequential p-values” for testing  
(aka “always-valid p-values”)



A “**confidence sequence**” for a parameter  $\theta$  is a sequence of confidence intervals  $(L_n, U_n)$  with a **uniform (simultaneous)** coverage guarantee.

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Darling, Robbins '67, '68  
Lai '76, '84  
Howard, Ramdas, McAuliffe, Sekhon '18

***Example:*** tracking the mean of a Gaussian or Bernoulli from i.i.d. observations.

$$X_1, X_2, \dots \sim N(\theta, 1) \text{ or } \textit{Ber}(\theta)$$

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Producing a confidence *interval* at a fixed time is elementary statistics ( $\sim 100$  years old).

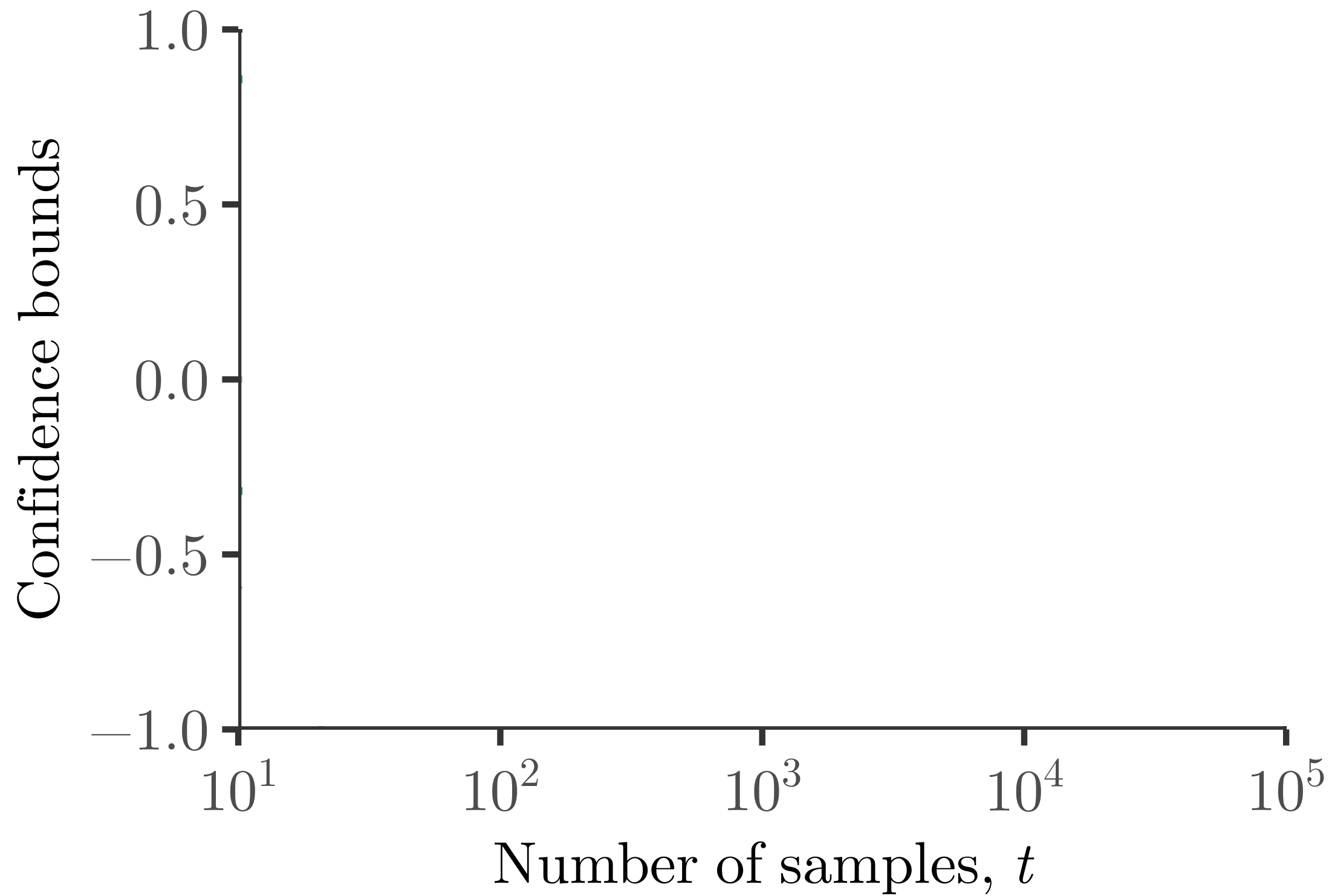
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How do we produce a confidence sequence?  
(which is like a confidence band over time)

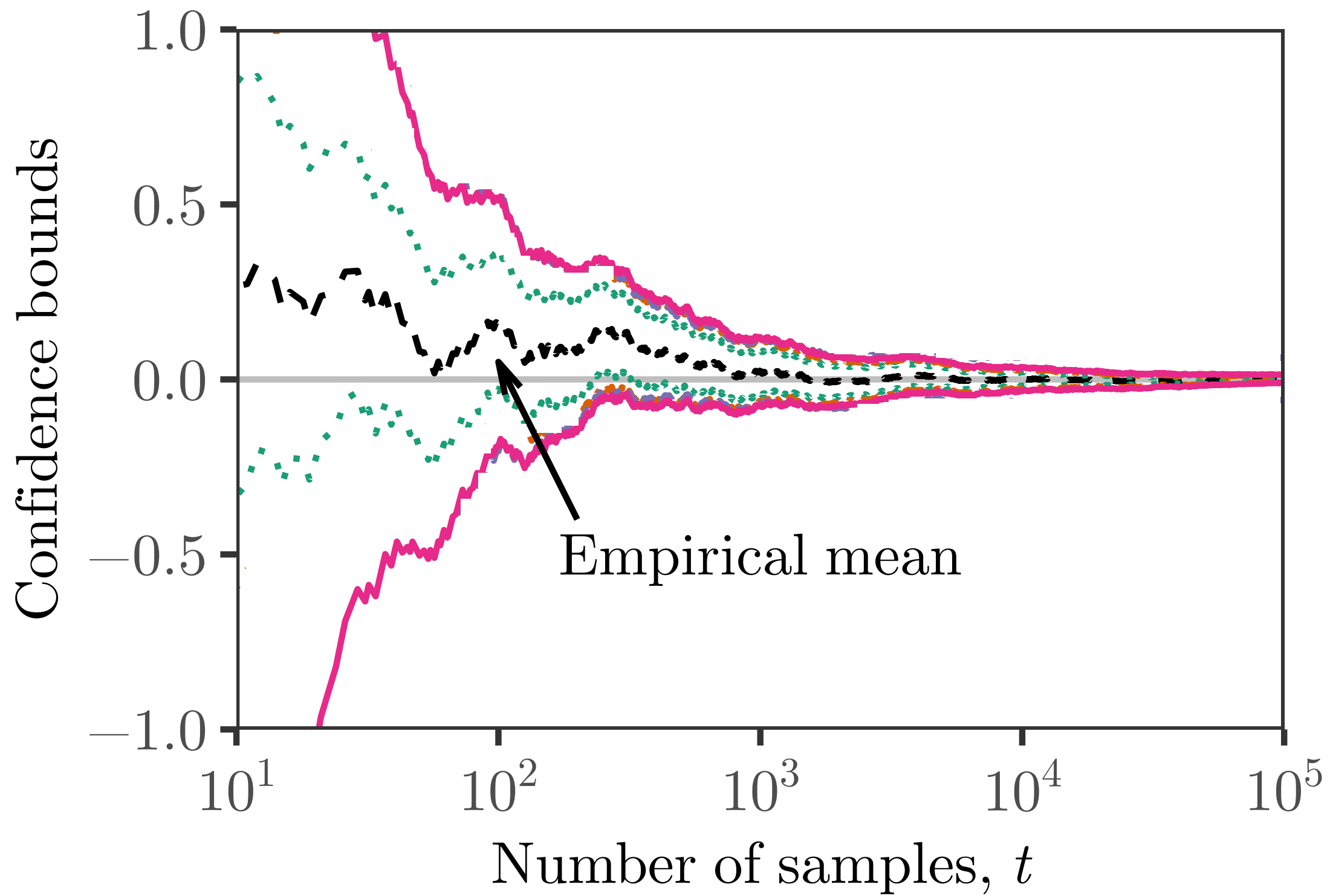
(Fair coin)



..... Pointwise CI (CLT)

———— Anytime CI

(Fair coin)



Pointwise CI (CLT)

Anytime CI

**Eg:** If  $X_i$  is 1-subGaussian, then

$$\frac{\sum_{i=1}^n X_i}{n} \pm 1.71 \sqrt{\frac{\log \log(2n) + 0.72 \log(5.19/\alpha)}{n}}$$

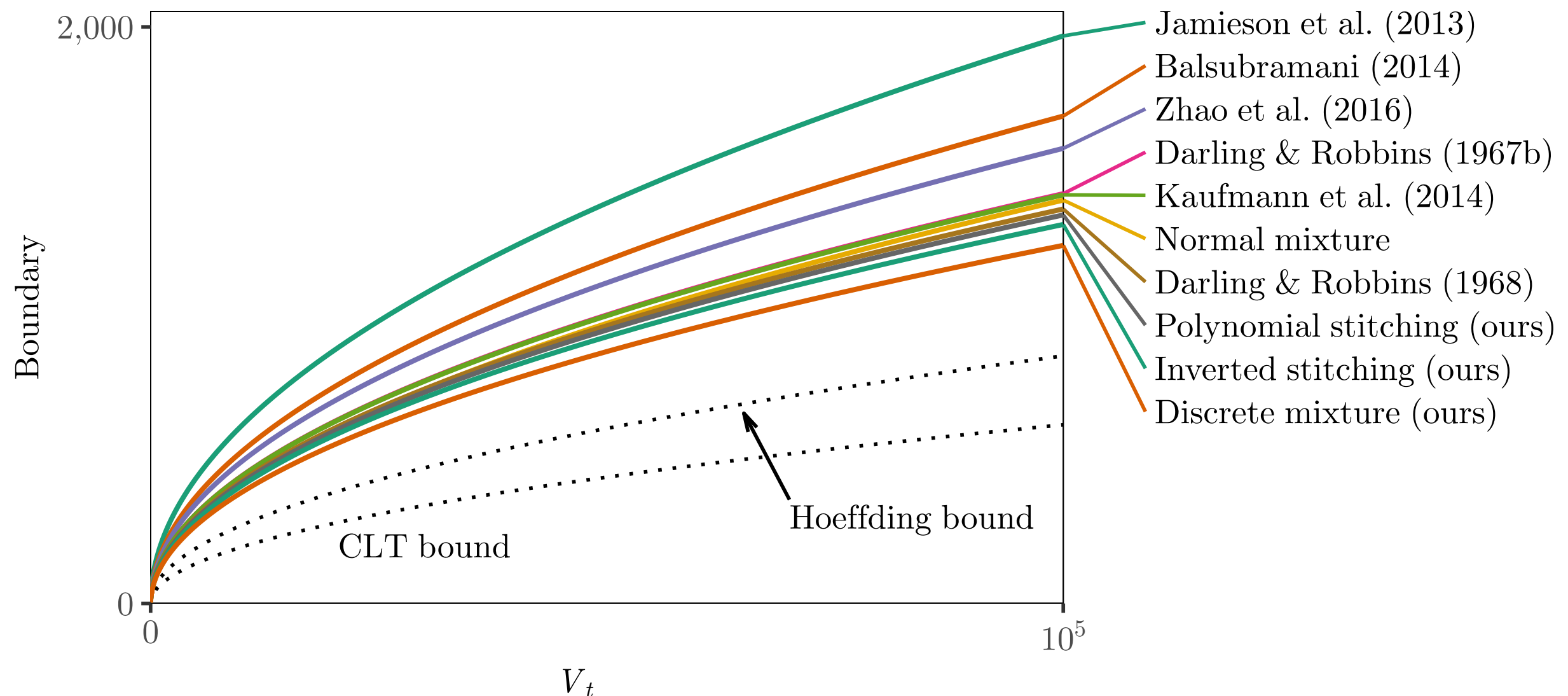
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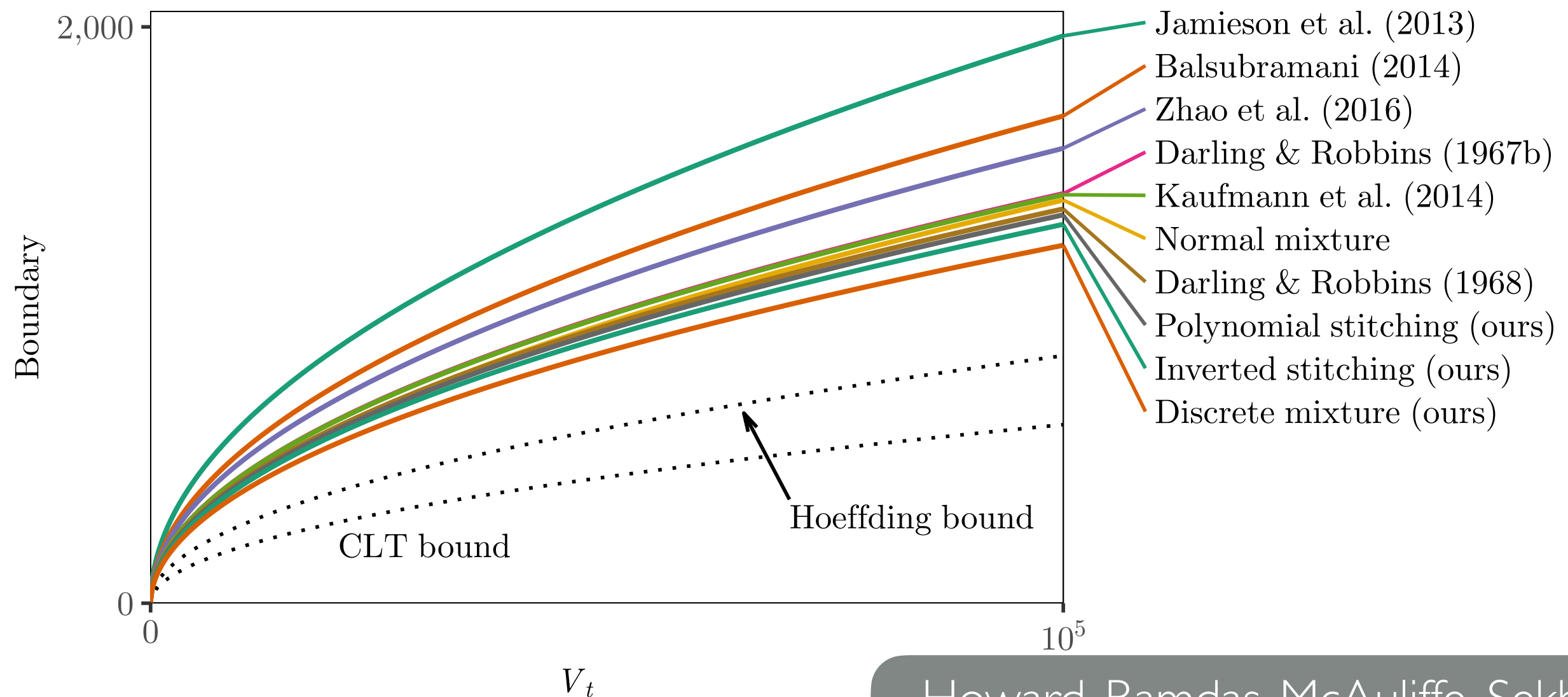
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$$\mathbb{P}(\bigcup_{n \in \mathbb{N}} \{\theta \notin (L_n, U_n)\}) \leq \alpha.$$

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3. No pre-specified sample size:

can extend or stop experiments adaptively.

The same duality between confidence intervals and p-values also holds in the sequential setting: “confidence sequences” are dual to “always valid p-values”.

# Duality between anytime p-value and CI

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For all stopping times  $\tau$ ,  $\Pr(P^{(\tau)} \leq \alpha) \leq \alpha.$

For all data-dependent times  $T$ ,  $\Pr(P^{(T)} \leq \alpha) \leq \alpha.$

# Relationship to Sequential Probability Ratio Test

Given a stream of data  $X_1, X_2, \dots \sim f_\theta$ , suppose we want to test a null hypothesis  $H_0 : \theta = \theta_0$  against an alternative hypothesis  $H_1 : \theta = \theta_1$ .



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Wald's SPRT (or SLRT) calculates a probability/likelihood ratio:

$$L^{(n)} := \frac{\prod_{i=1}^n f_1(X_i)}{\prod_{i=1}^n f_0(X_i)},$$

and rejects when  $L^{(n)} > 1/\alpha$ . Can also use prior/mixture over  $\theta_1$ .

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Equivalently, define  $P^{(n)} = 1/L^{(n)}$ . Then  $P^{(n)}$  is an always-valid p-value.

(And inverting it defines a confidence sequence.)

Can construct confidence sequences  
(and hence always valid p-values)  
in a wide variety of *nonparametric* settings  
(eg: random variables that are  
bounded, or subGaussian, or subexponential)

## Solutions for these issues

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Inner sequential process:

Part I

*“confidence sequence” for estimation*  
*also called “anytime confidence intervals”*  
*(correspondingly, “always valid  $p$ -values” for testing)*

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***“false coverage rate” for estimation***  
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***“false coverage rate” for estimation***  
*(correspondingly, “false discovery rate” for testing)*

**Modular solutions: fit well together**  
**Many extensions to each piece**

Part III



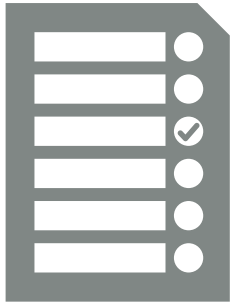
## Part II

# The OUTER Sequential Process (a sequence of experiments)

[40 mins]

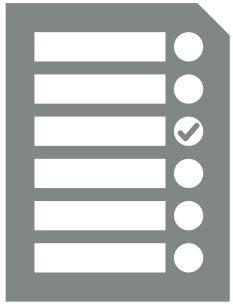
# Quick recap of **A/B testing**

A :

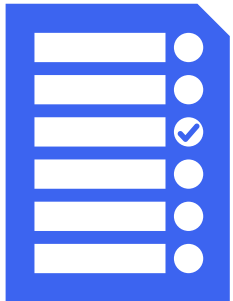


# Quick recap of **A/B testing**

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B :



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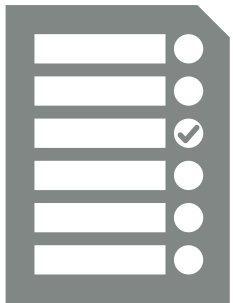


**Null hypothesis:**

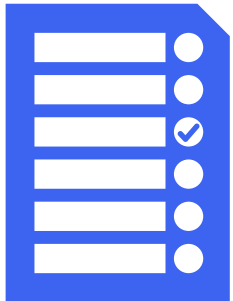
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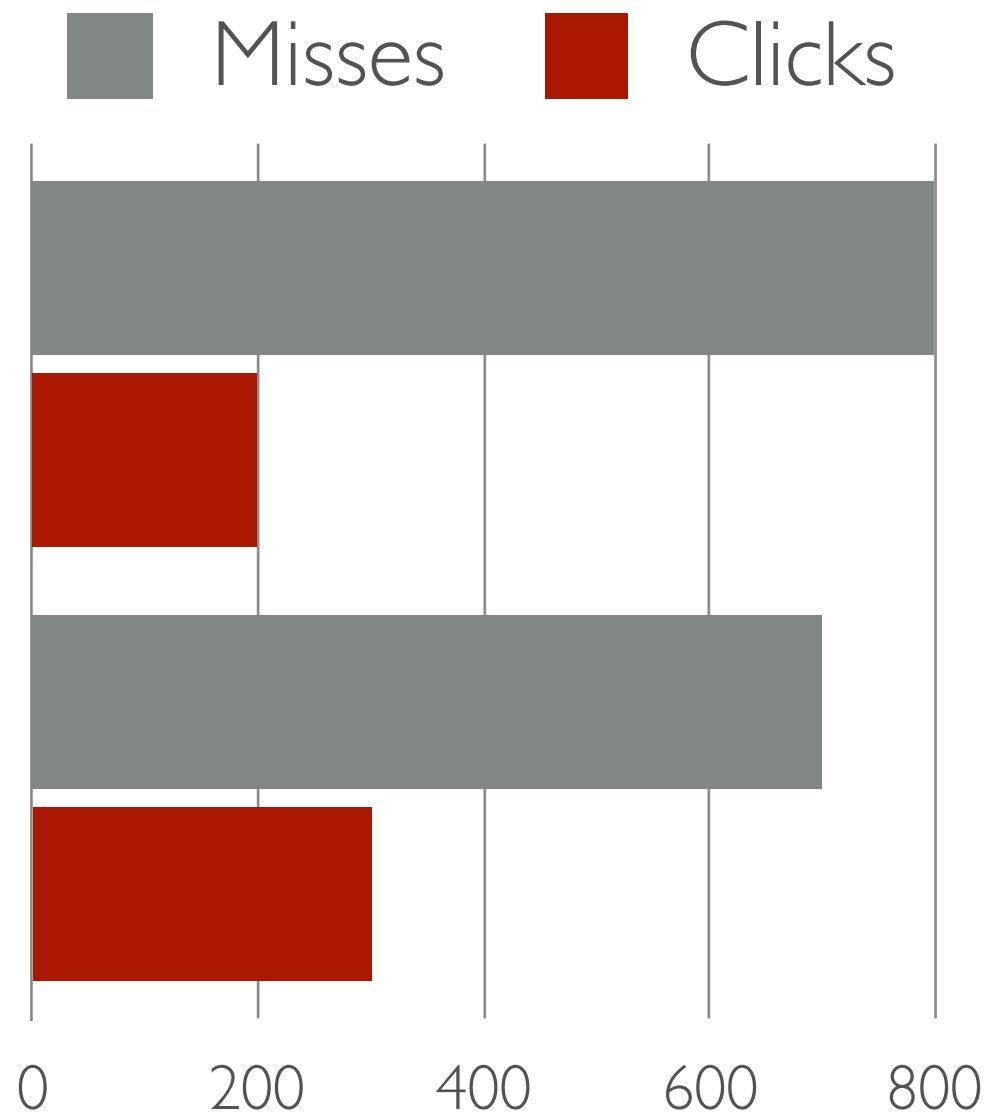


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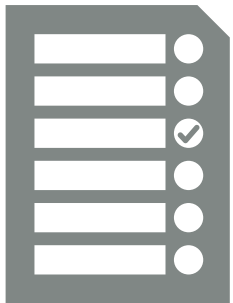
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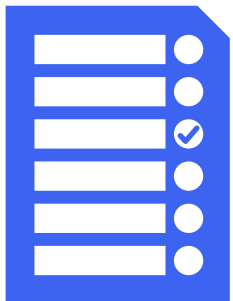


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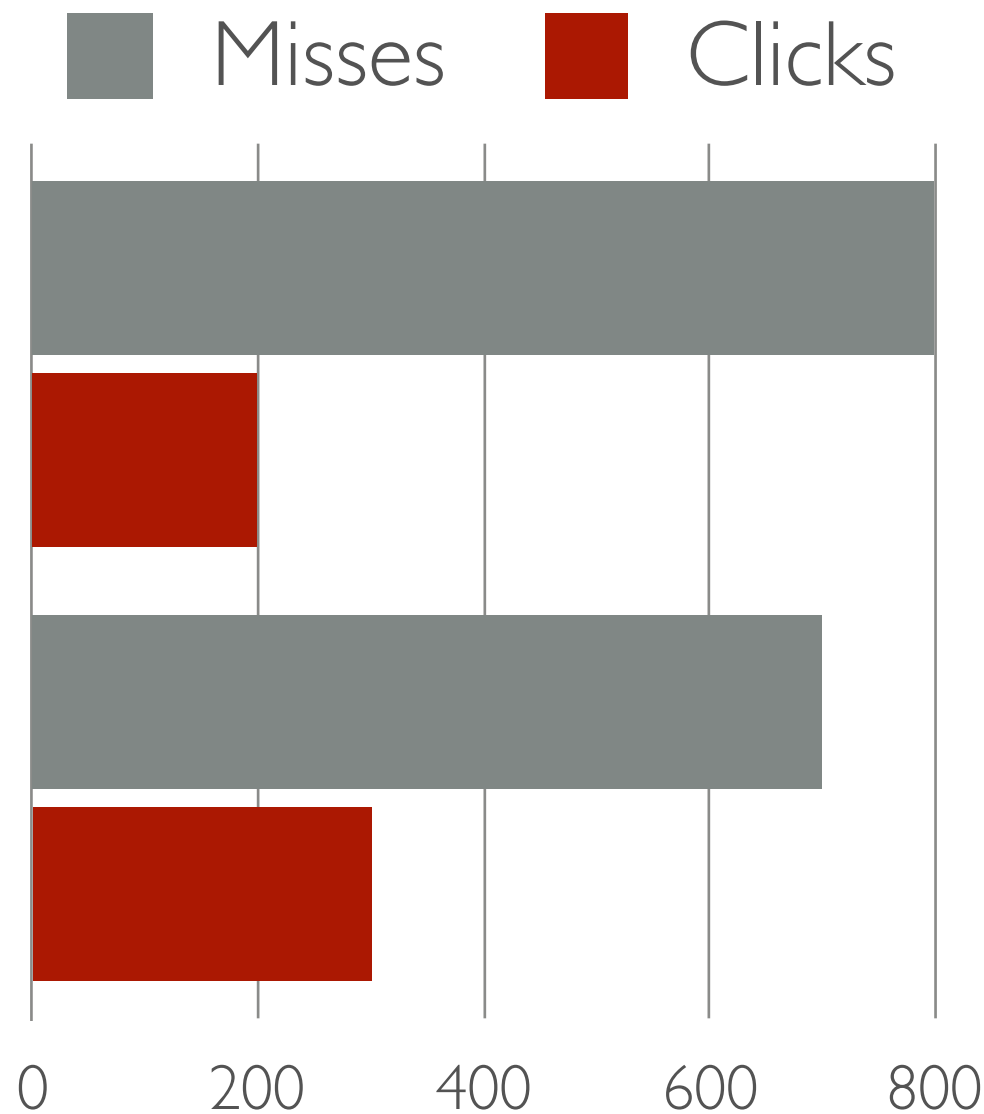


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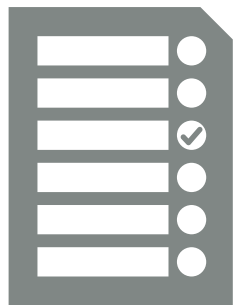
**Calculate p-value:**

$P = \Pr(\text{observed data or more extreme, assuming null is true})$

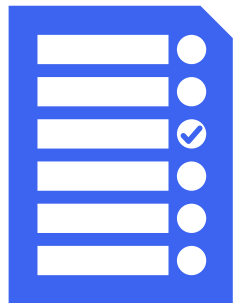


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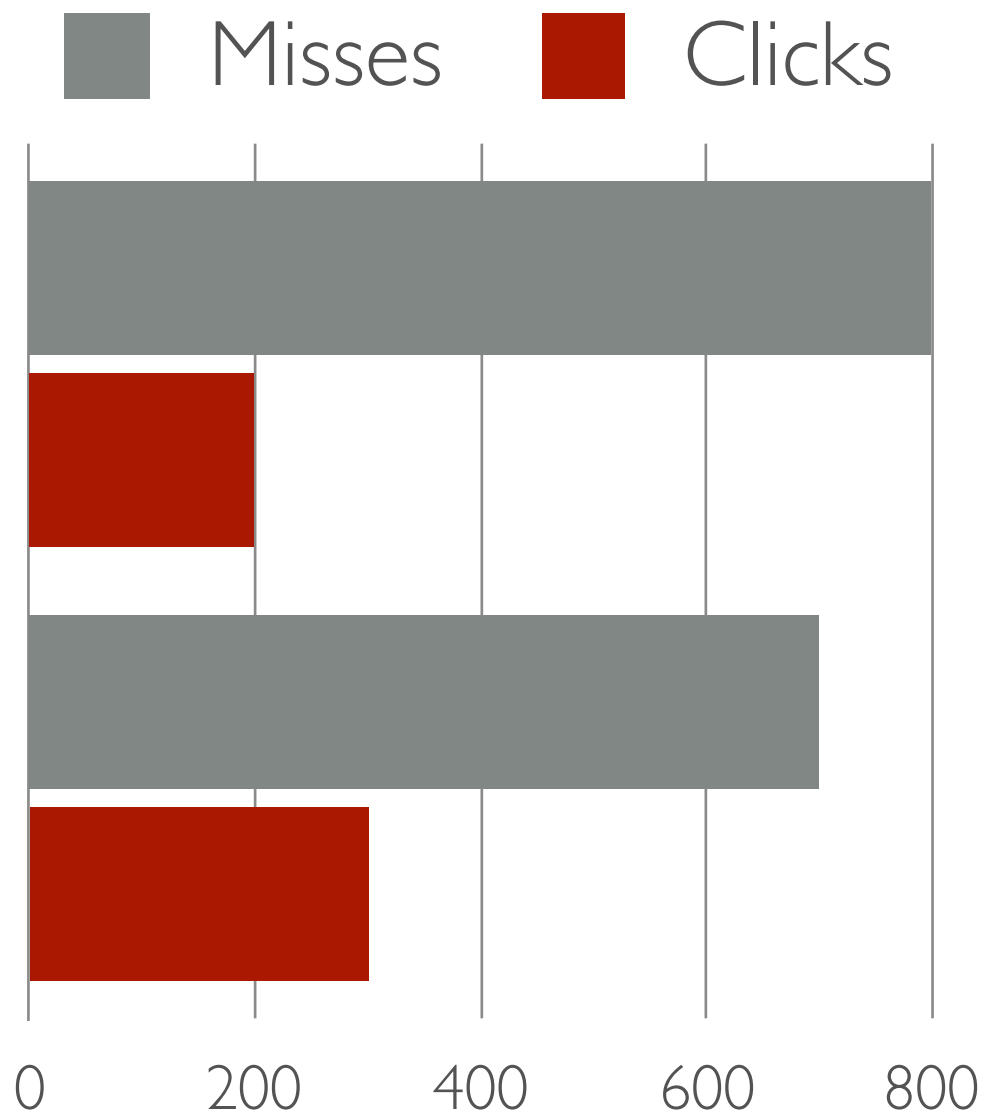


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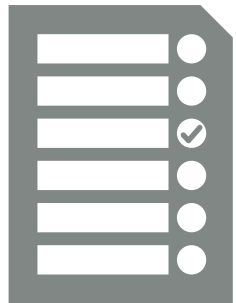
**Decision rule :**

if  $P \leq \alpha$ , then  
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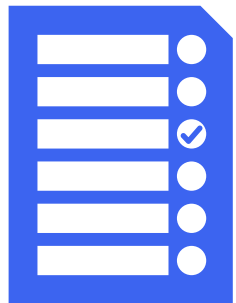
We **change A to B**,  
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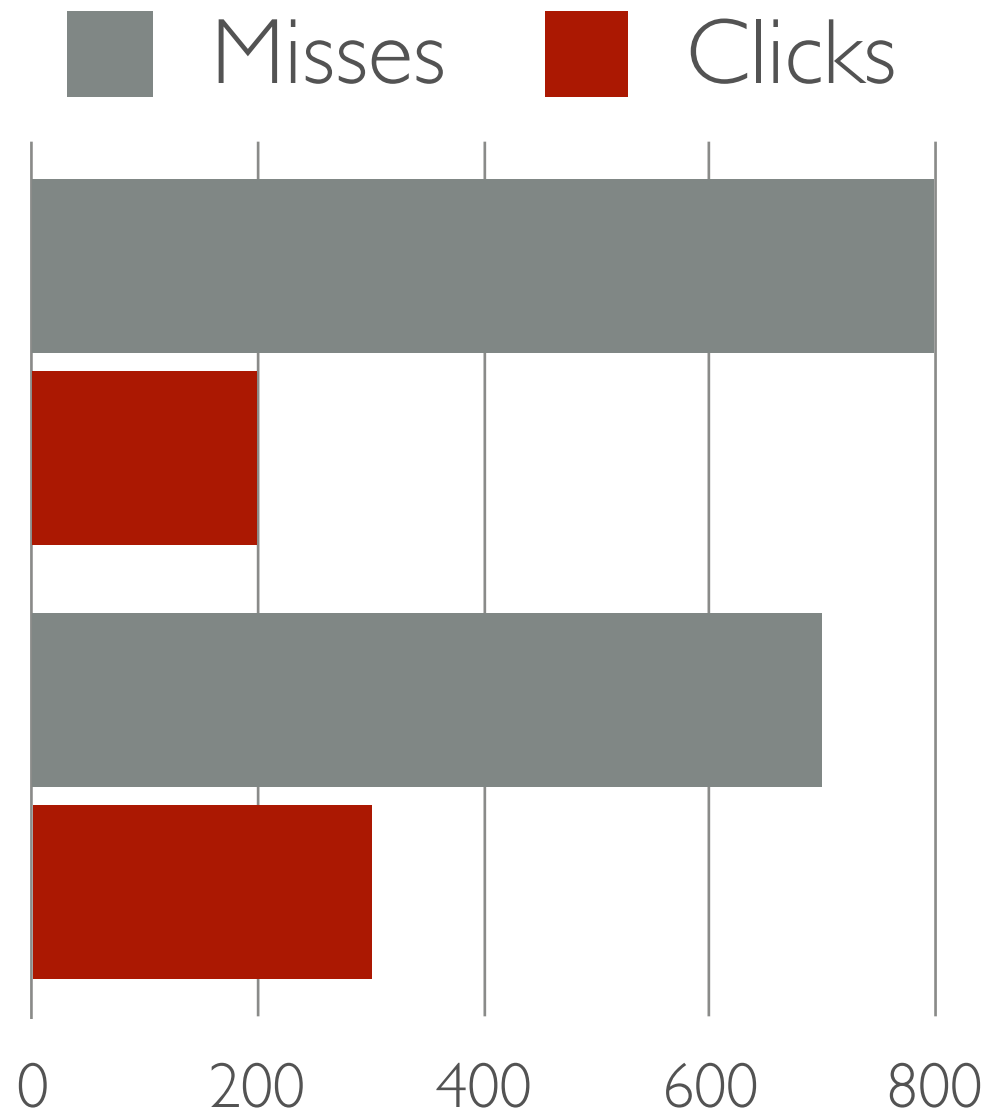


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We **change A to B**,  
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a wrong rejection  
of the null

is a **false discovery**

and implies

**a bad change  
from A to B.**



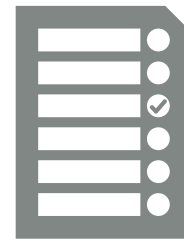
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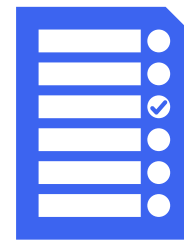
Time



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**vs.**



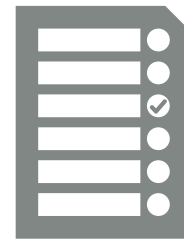
Color

Time

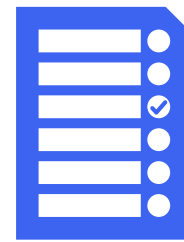


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**vs.**



Color

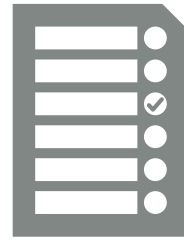
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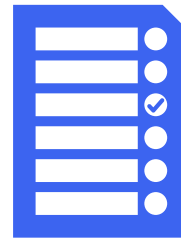
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**vs.**



Color

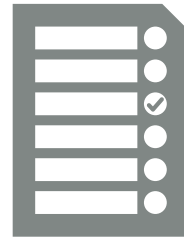
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**vs.**



Color



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Size

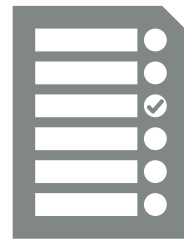
Time



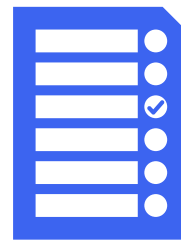
**Reality:** internet companies run thousands of different (independent) A/B tests over time.

Decision rule:

$$P_1 \leq \alpha?$$



**vs.**



Color

$$P_2 \leq \alpha?$$



**vs.**



Size

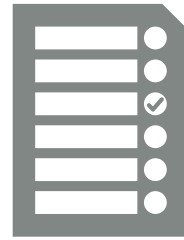
Time



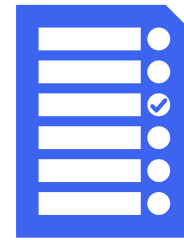
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Size



**vs.**



Orientation

Time

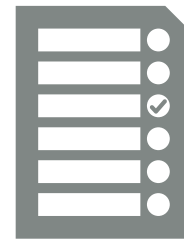




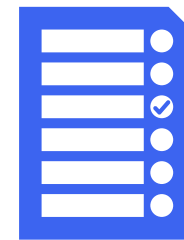
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Size

$$P_3 \leq \alpha?$$



**vs.**



Orientation

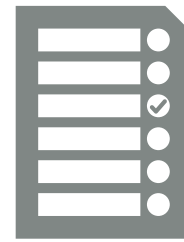
Time



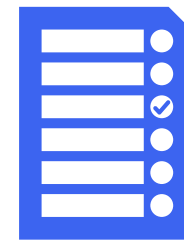
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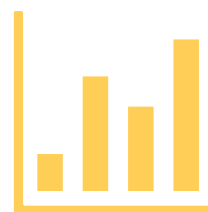
$$P_3 \leq \alpha?$$



**vs.**



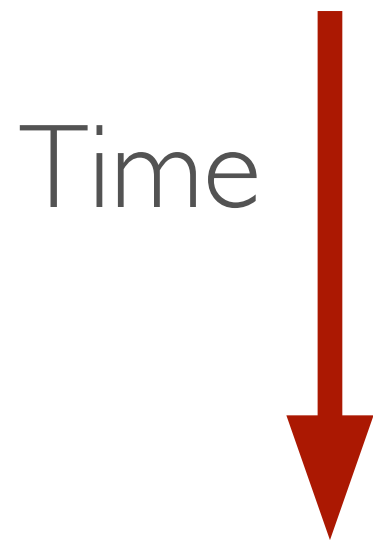
Orientation



**vs.**

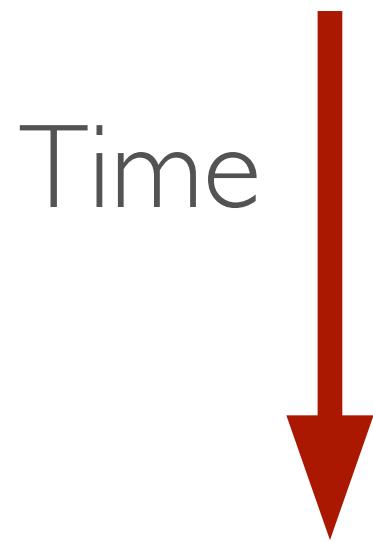


Style

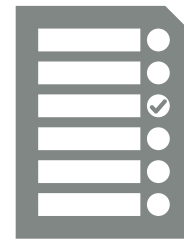


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Decision rule:



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**vs.**



Color

$$P_2 \leq \alpha?$$



**vs.**



Size

$$P_3 \leq \alpha?$$

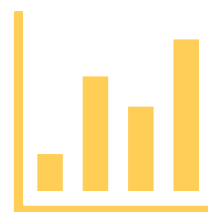


**vs.**



Orientation

$$P_4 \leq \alpha?$$



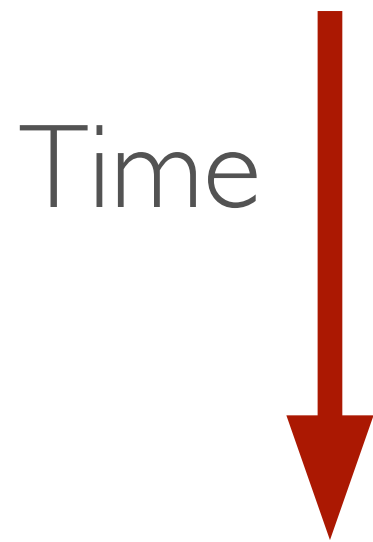
**vs.**



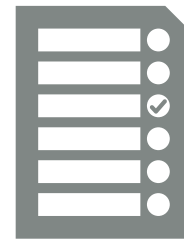
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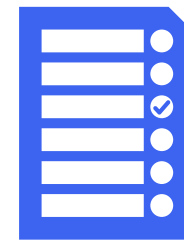
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Color

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**vs.**



Size

$$P_3 \leq \alpha?$$



**vs.**



Orientation

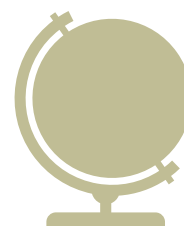
$$P_4 \leq \alpha?$$



**vs.**



Style



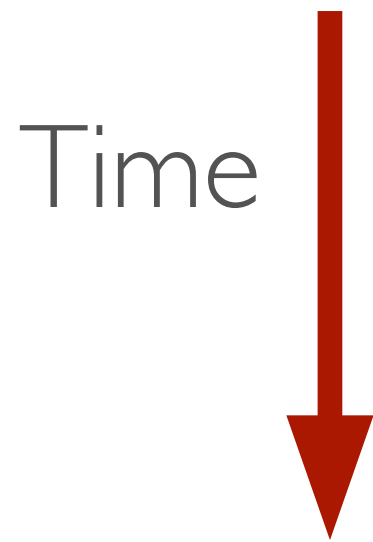
**vs.**



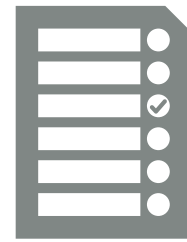
Logo

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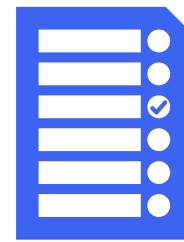
Decision rule:



$$P_1 \leq \alpha?$$



**vs.**



Color

$$P_2 \leq \alpha?$$



**vs.**



Size

$$P_3 \leq \alpha?$$

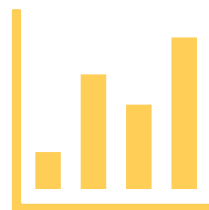


**vs.**



Orientation

$$P_4 \leq \alpha?$$

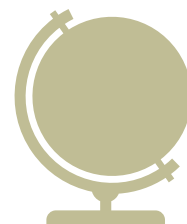


**vs.**



Style

$$P_5 \leq \alpha?$$



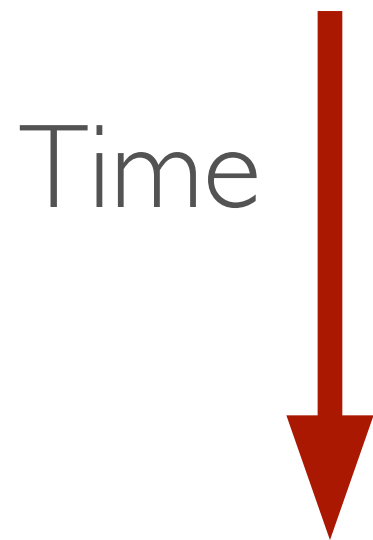
**vs.**



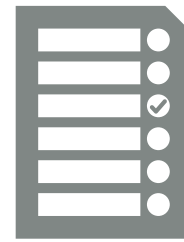
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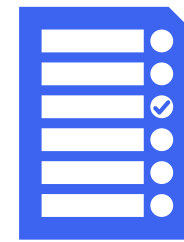
Decision rule:



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vs.



Color

$$P_2 \leq \alpha?$$



vs.



Size

$$P_3 \leq \alpha?$$

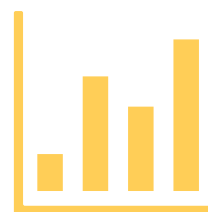


vs.



Orientation

$$P_4 \leq \alpha?$$

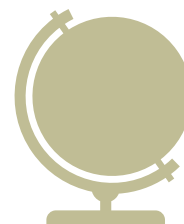


vs.



Style

$$P_5 \leq \alpha?$$



vs.



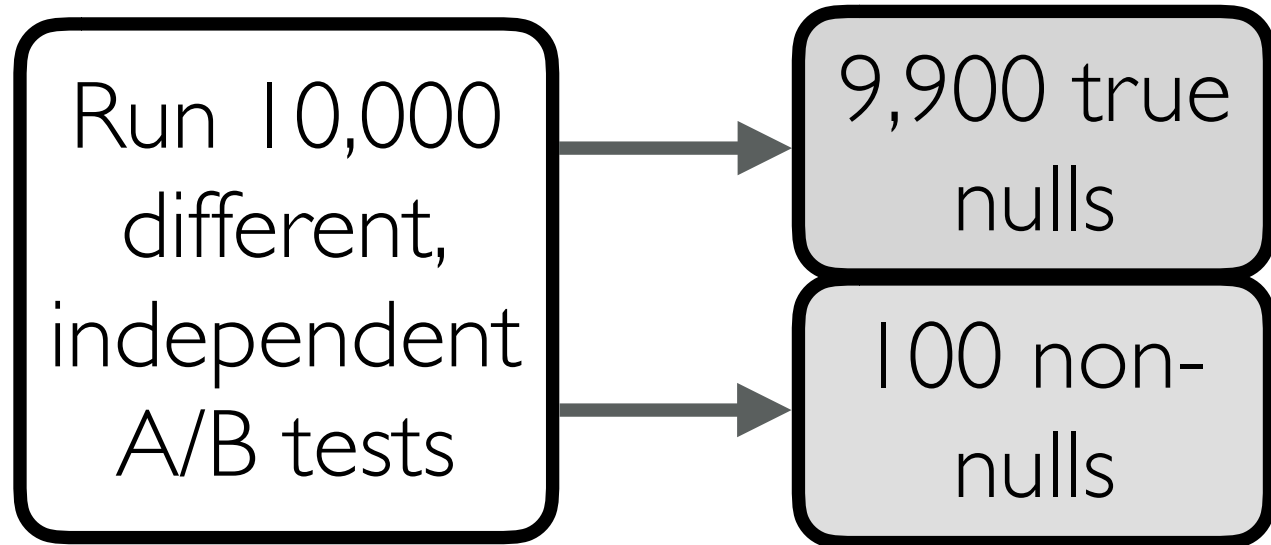
Logo

**Problem!**

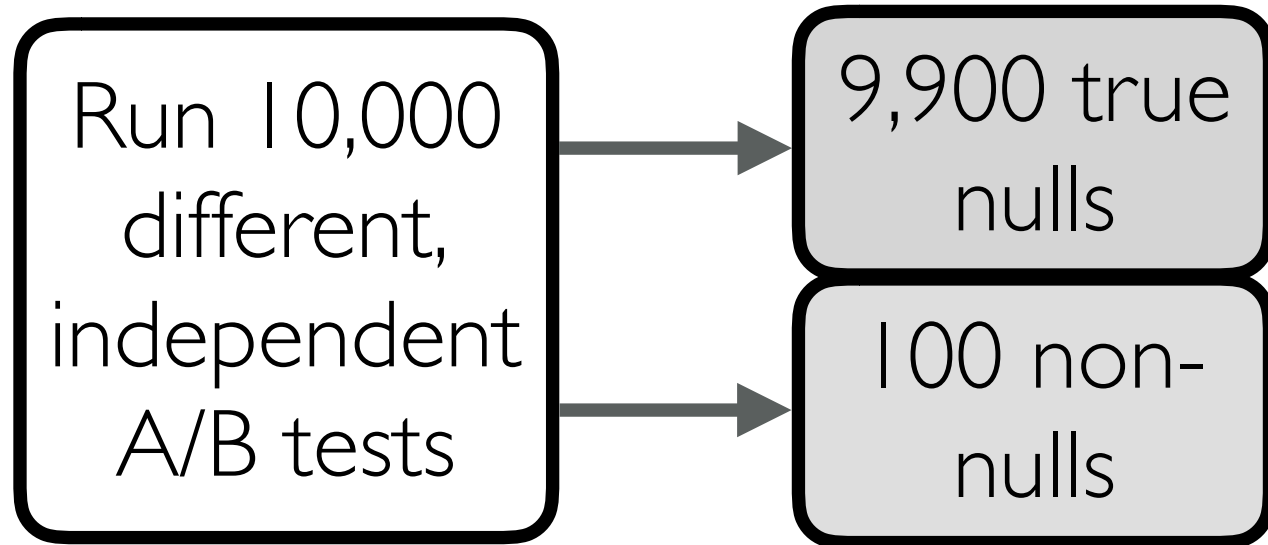


Run 10,000  
different,  
independent  
A/B tests

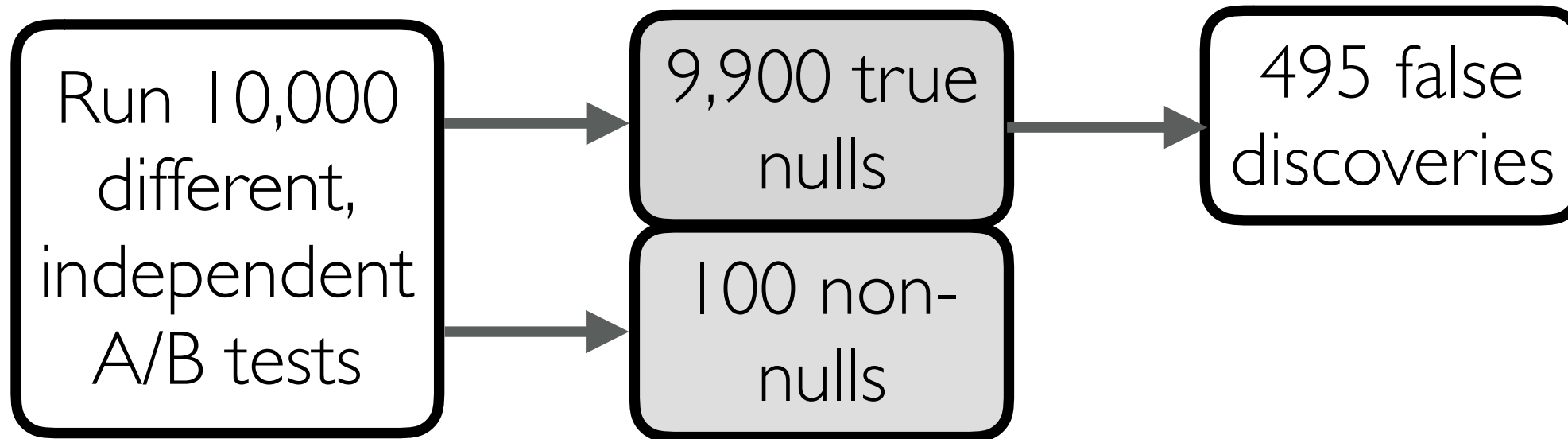




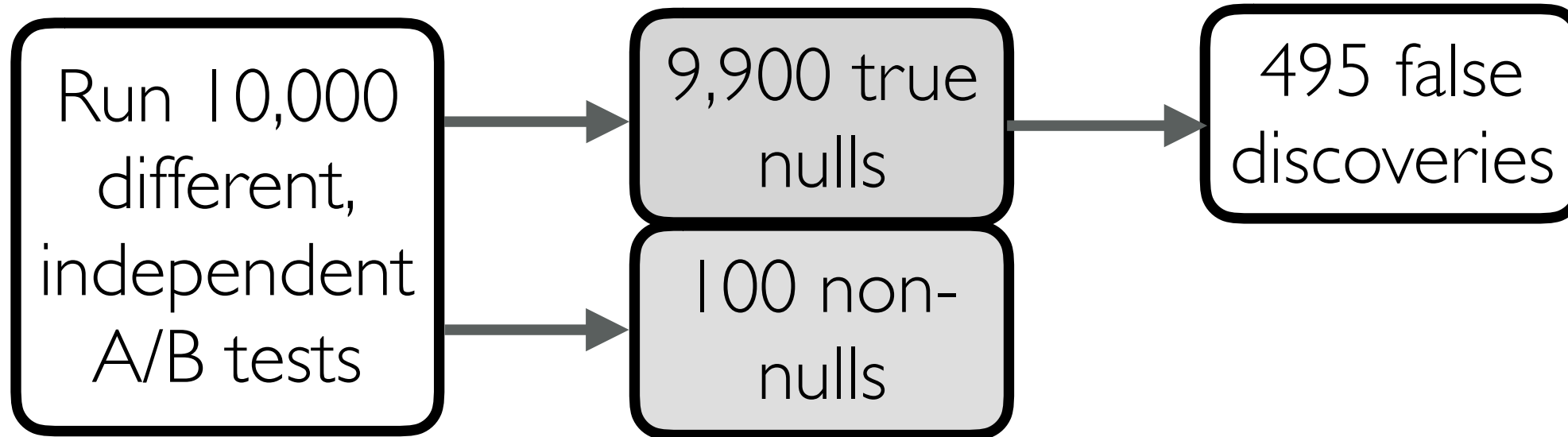
type-I error rate (per test)  
= 0.05



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= 0.05

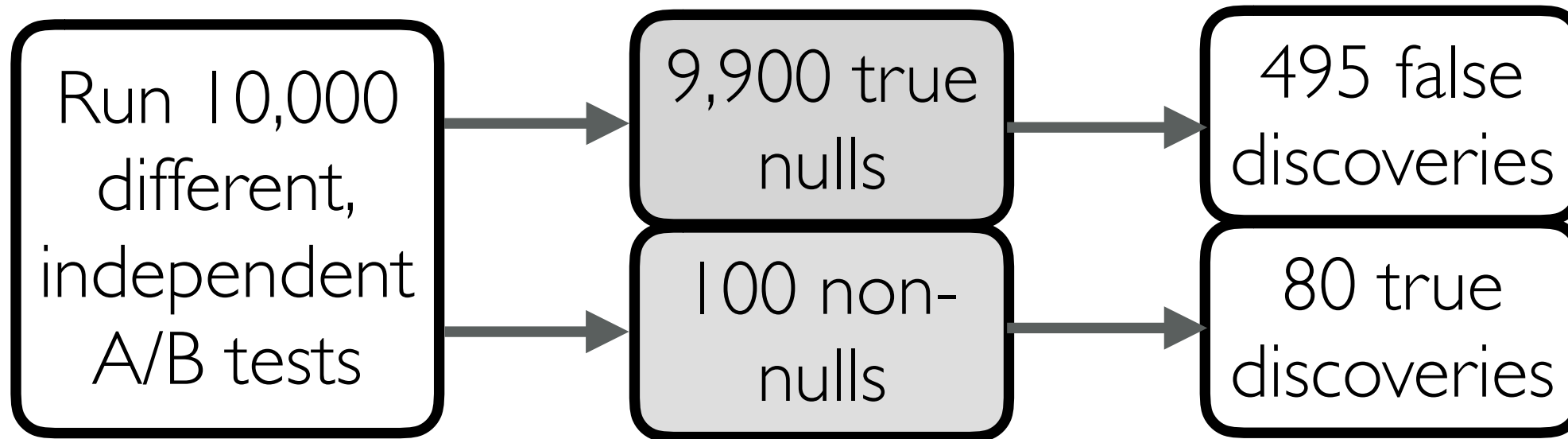


type-I error rate (per test)  
= 0.05



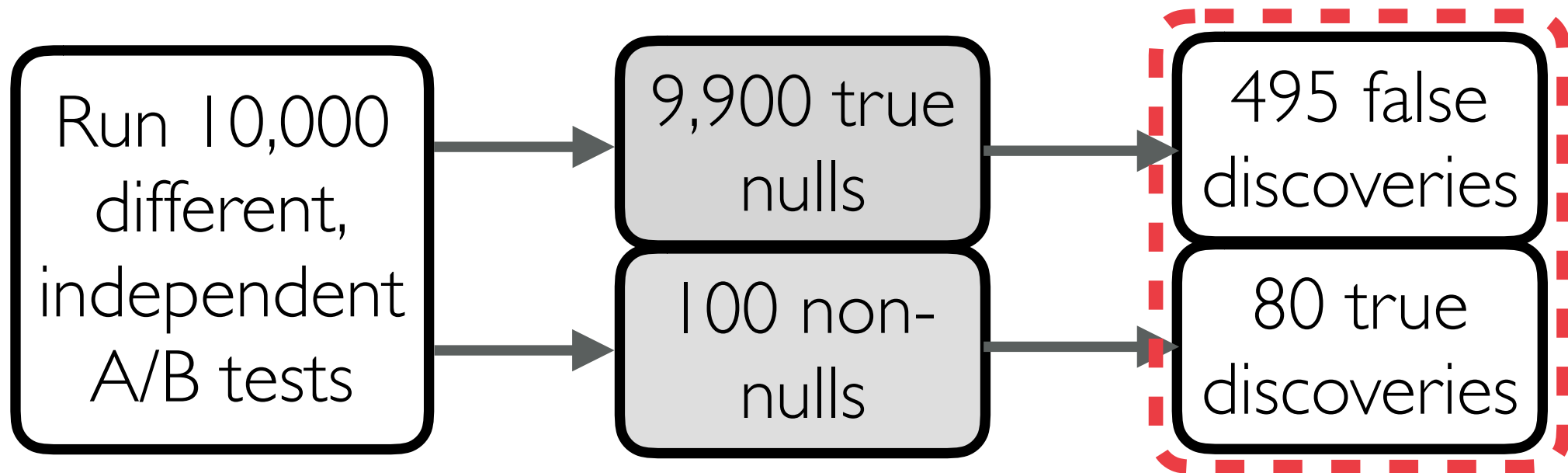
power (per test)  
= 0.80

type-I error rate (per test)  
= 0.05



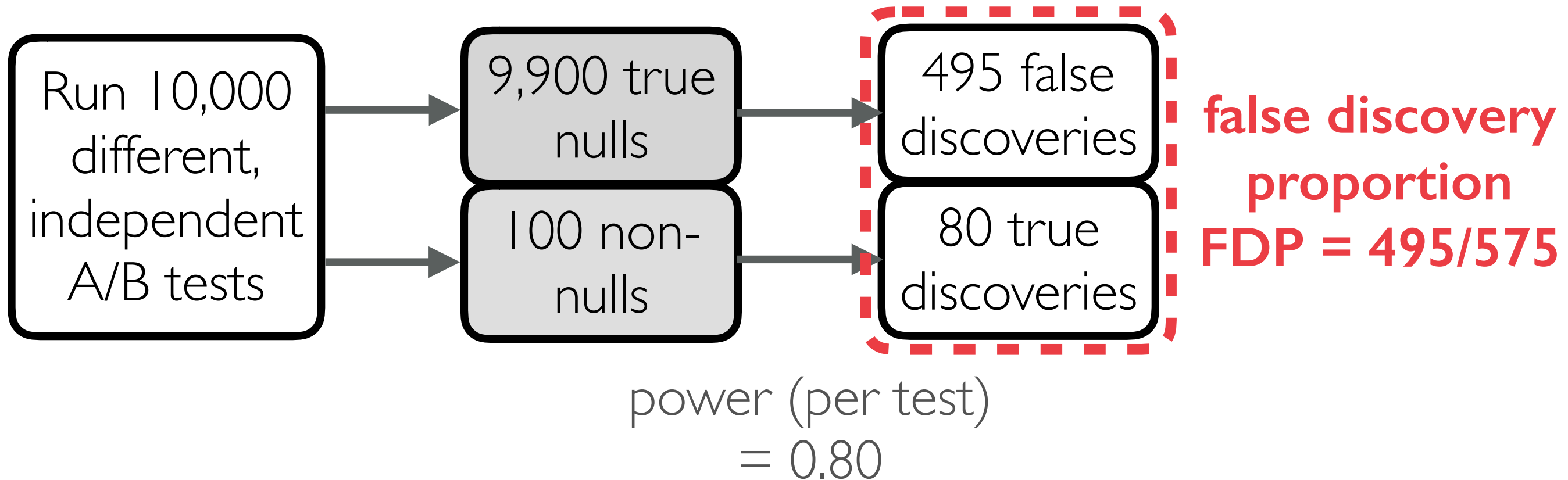
power (per test)  
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type-I error rate (per test)  
 $= 0.05$



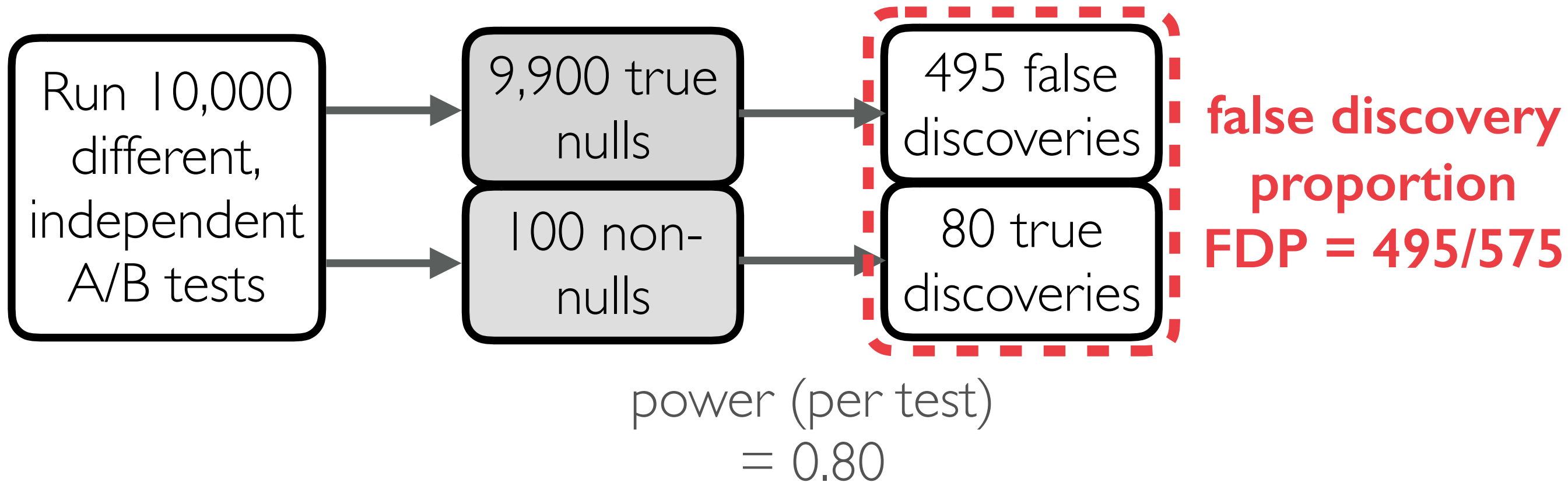
power (per test)  
 $= 0.80$

type-I error rate (per test)  
= 0.05



$$\text{FDP} = \frac{\# \text{ false discoveries}}{\# \text{ discoveries}}$$

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= 0.05

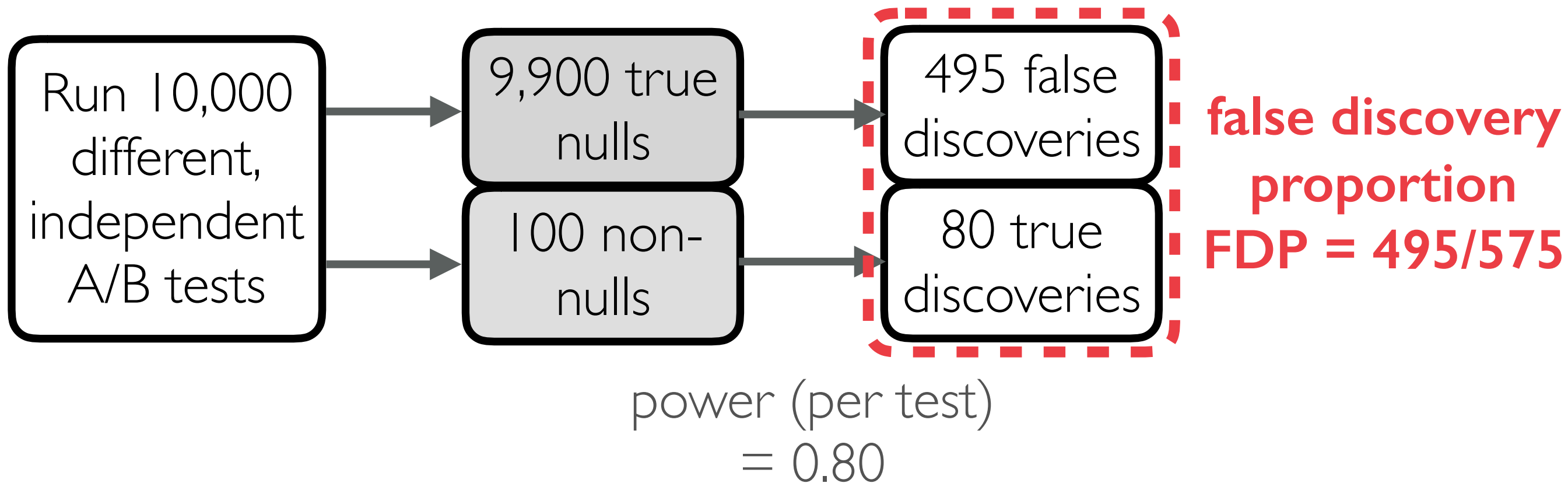


$$\text{FDP} = \frac{\# \text{ false discoveries}}{\# \text{ discoveries}}$$

$$\text{FDR} = \mathbb{E}[\text{FDP}]$$



type-I error rate (per test)  
= 0.05



$$\text{FDP} = \frac{\# \text{ false discoveries}}{\# \text{ discoveries}}$$

$$\text{FDR} = \mathbb{E}[\text{FDP}]$$

**Summary:** FDR can be larger than per-test error rate.  
(even if hypotheses, tests, data are independent)

**Given a possibly infinite sequence of independent tests (p-values), can we guarantee control of the FDR in a fully online fashion?**

Foster-Stine '08

Aharoni-Rosset '14

Javanmard-Montanari '16

Ramdas-Yang-Wainwright-Jordan '17

Ramdas-Zrnic-Wainwright-Jordan '18

Tian-Ramdas '19

# The aim of online FDR procedures

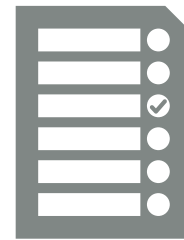
Decision rule:

Time

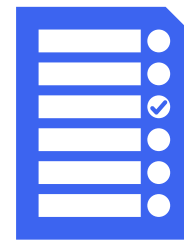


# The aim of online FDR procedures

Decision rule:



**vs.**



Color

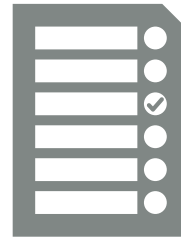
Time



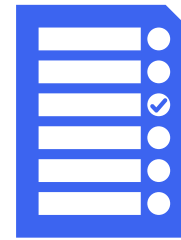
# The aim of online FDR procedures

Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

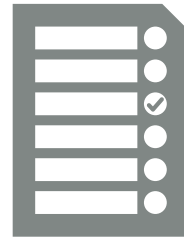
Time



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Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color



**vs.**



Size

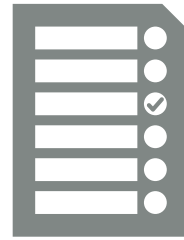
Time



# The aim of online FDR procedures

Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size

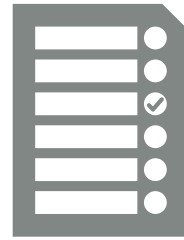
Time



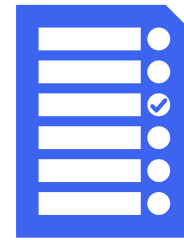
# The aim of online FDR procedures

Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size



**vs.**



Orientation

Time

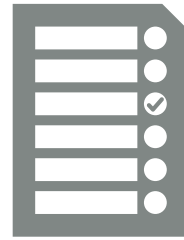




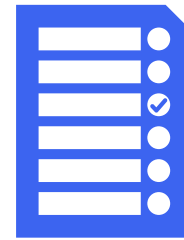
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Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size

$$P_3 \leq \alpha_3?$$



**vs.**



Orientation

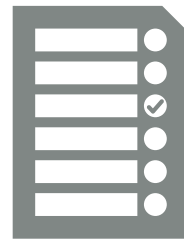
Time



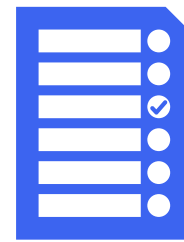
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Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size

$$P_3 \leq \alpha_3?$$



**vs.**



Orientation



**vs.**



Style

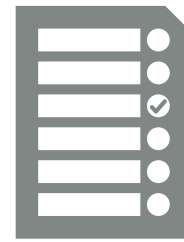
Time



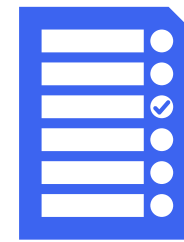
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Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size

$$P_3 \leq \alpha_3?$$

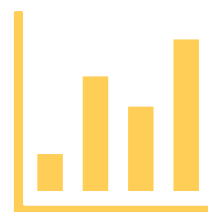


**vs.**



Orientation

$$P_4 \leq \alpha_4?$$



**vs.**



Style

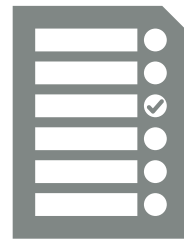
Time



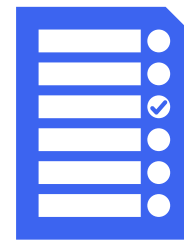
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Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size

$$P_3 \leq \alpha_3?$$

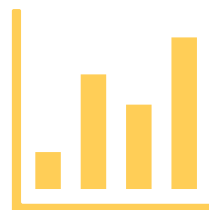


**vs.**



Orientation

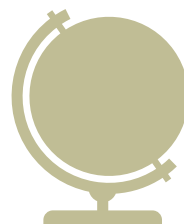
$$P_4 \leq \alpha_4?$$



**vs.**



Style



**vs.**



Logo

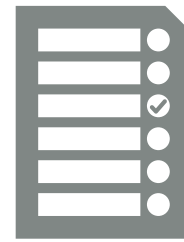
Time



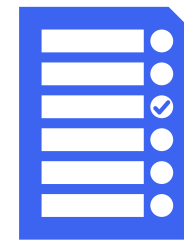
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Decision rule:

$$P_1 \leq \alpha_1?$$



**vs.**



Color

Time



$$P_2 \leq \alpha_2?$$



**vs.**



Size

$$P_3 \leq \alpha_3?$$

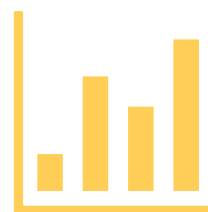


**vs.**



Orientation

$$P_4 \leq \alpha_4?$$

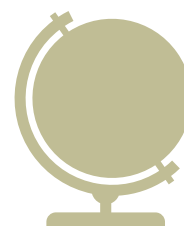


**vs.**

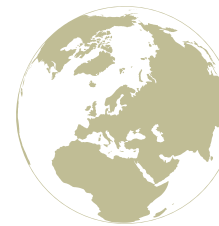


Style

$$P_5 \leq \alpha_5?$$



**vs.**



Logo

# The aim of online FDR procedures

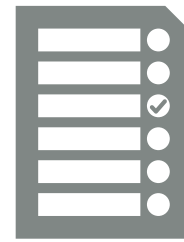
Decision rule:

Time

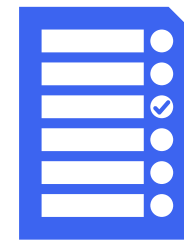


How do we  
set each  
error level to  
control FDR  
at any time?

$$P_1 \leq \alpha_1?$$



**vs.**



Color

$$P_2 \leq \alpha_2?$$



**vs.**



Size

$$P_3 \leq \alpha_3?$$

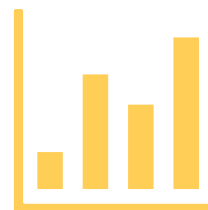


**vs.**



Orientation

$$P_4 \leq \alpha_4?$$

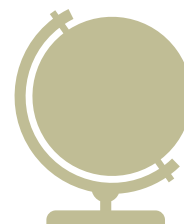


**vs.**



Style

$$P_5 \leq \alpha_5?$$



**vs.**



Logo

One of the most famous offline FDR methods is the “Benjamini-Hochberg” (BH) method

Offline FDR methods  
do not control the FDR  
in online settings

The following method is **not** a valid online FDR algorithm:

At the end of experiment  $t$ , run BH on  $P_1, \dots, P_t$ .



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The reason is that the decision about the first hypothesis depends on all future hypotheses. We cannot commit to a decision and stick to it.

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At the end of experiment  $t$ , run BH on  $P_1, \dots, P_t$ .

The reason is that the decision about the first hypothesis depends on all future hypotheses. We cannot commit to a decision and stick to it.

We need the error level  $\alpha_t$  for experiment  $t$  to be specified when it starts, and we need to make a final decision when experiment  $t$  ends.

This multiple testing issue is not particular to p-values. It also exists when selectively reporting treatment effects with confidence intervals.

Benjamini, Yekutieli '05  
Weinstein, Ramdas '19

# Multiplicity in reported CIs

One rarely cares about all CIs or follows-up on them, one usually reports only the most “promising” CIs.

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$$\text{FCP} = \frac{\# \text{ incorrectly reported CIs}}{\# \text{ reported CIs}}$$

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## False coverage proportion

$$\text{FCP} = \frac{\# \text{ incorrectly reported CIs}}{\# \text{ reported CIs}}$$

## False coverage rate

$$\text{FCR} = \mathbb{E}[\text{FCP}]$$

Benjamini-Yekutieli '06  
Weinstein-Yekutieli '14  
Fithian et al. '14

# Controlling FCR is nontrivial

Constructing marginal 95% CIs for all parameters fails to control FCR at 0.05.

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Constructing marginal 95% CIs for all parameters fails to control FCR at 0.05.

Suppose treatment effect  $\theta_j \in \{\pm 0.1\}$  for all  $j$ ,  
and experimental observations are normalized to  
 $X_j \sim N(\theta_j, 1)$ .



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Constructing marginal 95% CIs for all parameters fails to control FCR at 0.05.

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Suppose we only care about drugs with large effects. So we only pursue phase II of the trial if  $X_j > 3$ .

For these drugs, the standard marginal 95% CI does not cover  $\theta_j$ . So FCR=1.

# Can we control FCR \*online\*?

When experiment  $j$  starts, we must assign a target confidence level  $\alpha_j$ .

When experiment  $j$  ends, we must decide if we wish to report  $\theta_j$ .

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A simple solution for both  
online FDR control, and  
online FCR control

# Online FCR control: the main idea

Let  $S_i \in \{0, 1\}$  denote the selection decision made after experiment  $i$ .

$$\text{Maintain } \widehat{\text{FCP}}(T) := \frac{\sum_{i=1}^T \alpha_i}{1 \vee \sum_{i=1}^T S_i} \leq \alpha.$$

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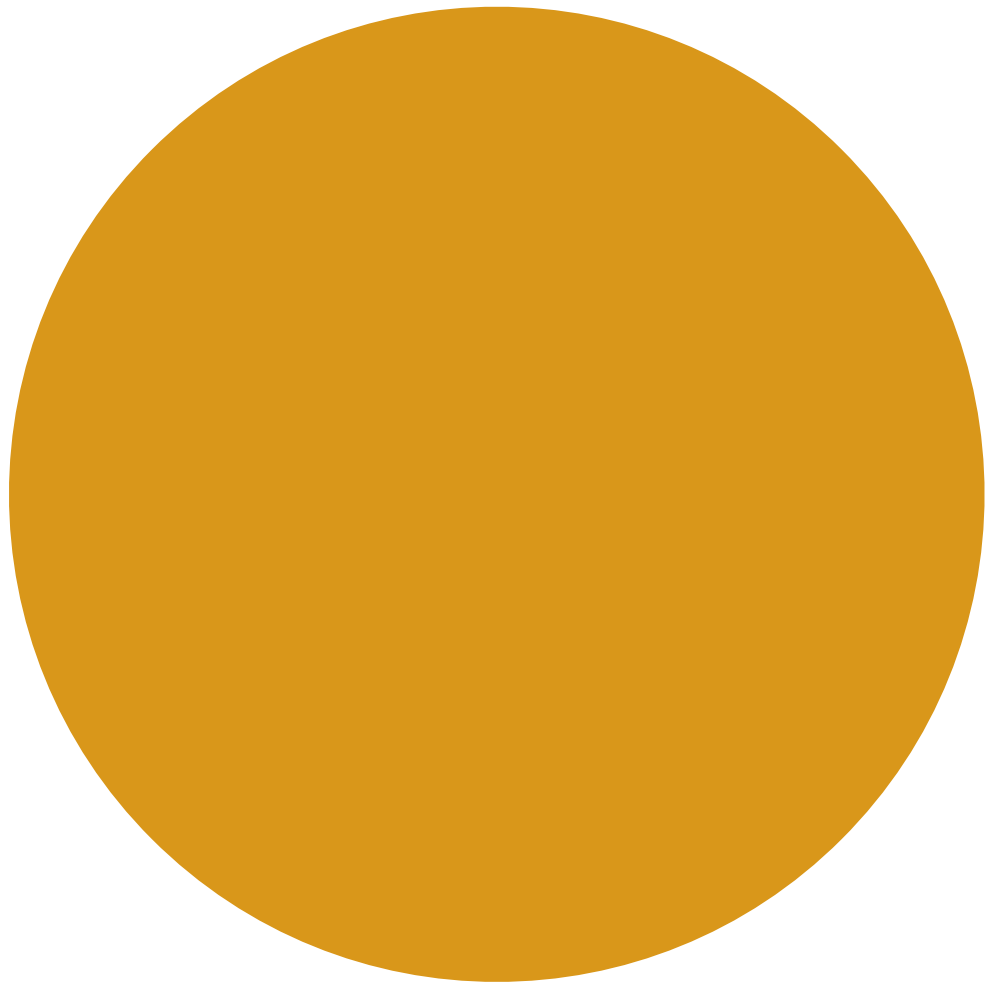
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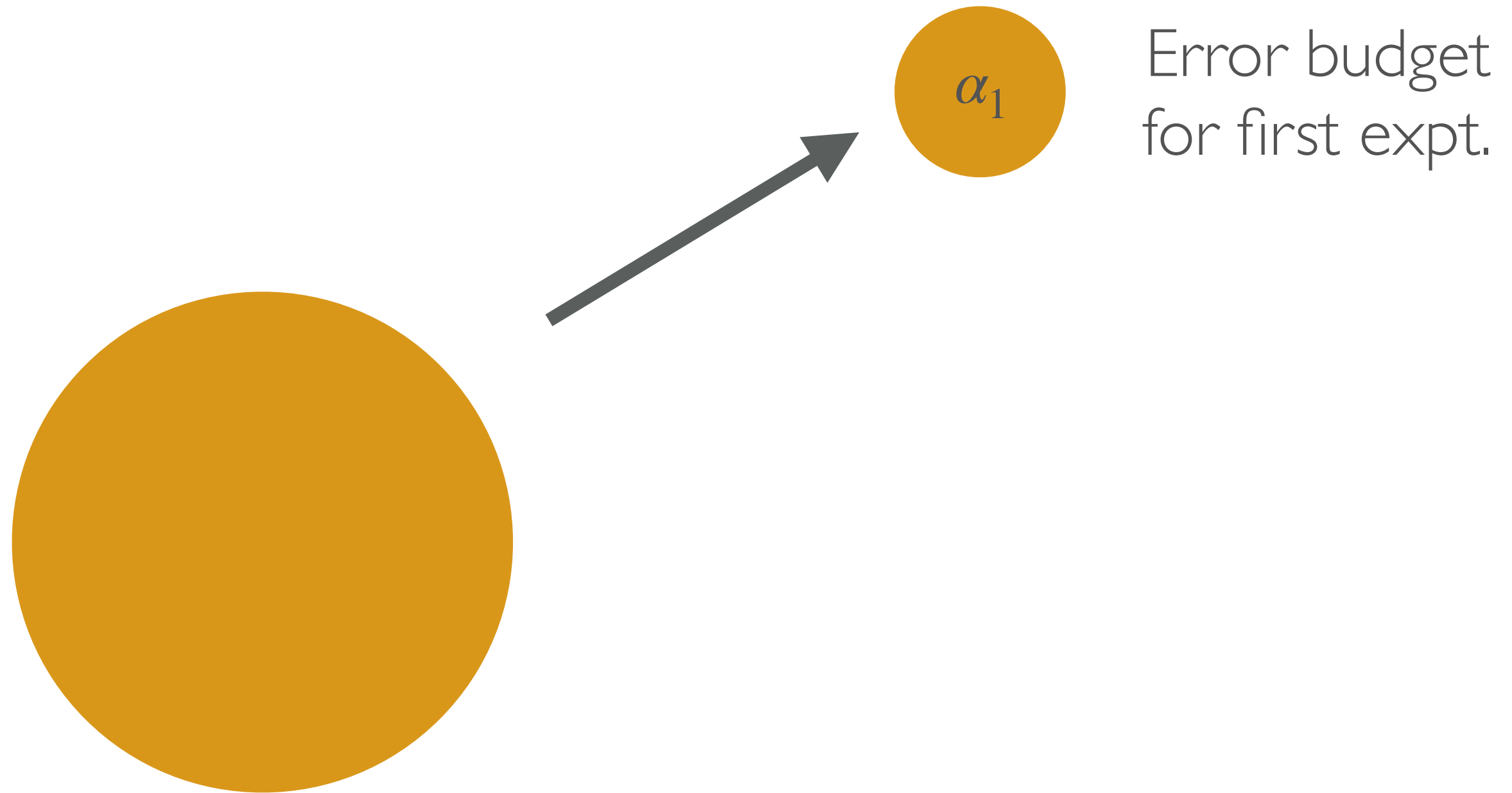
This provably controls FCR/FDR at level  $\alpha$ .

# Online FCR control : high-level picture



Remaining error budget  
or “alpha-wealth”

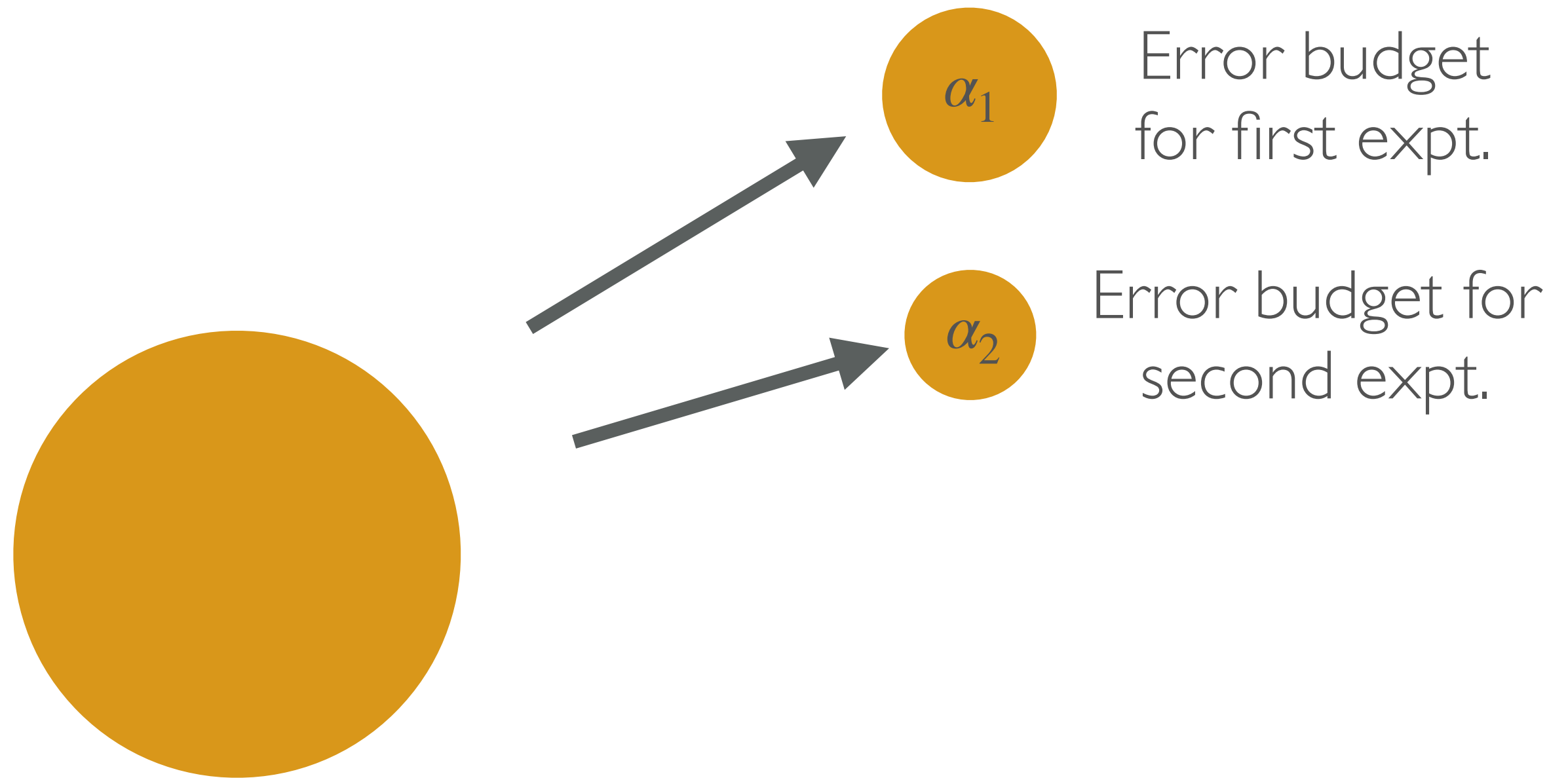
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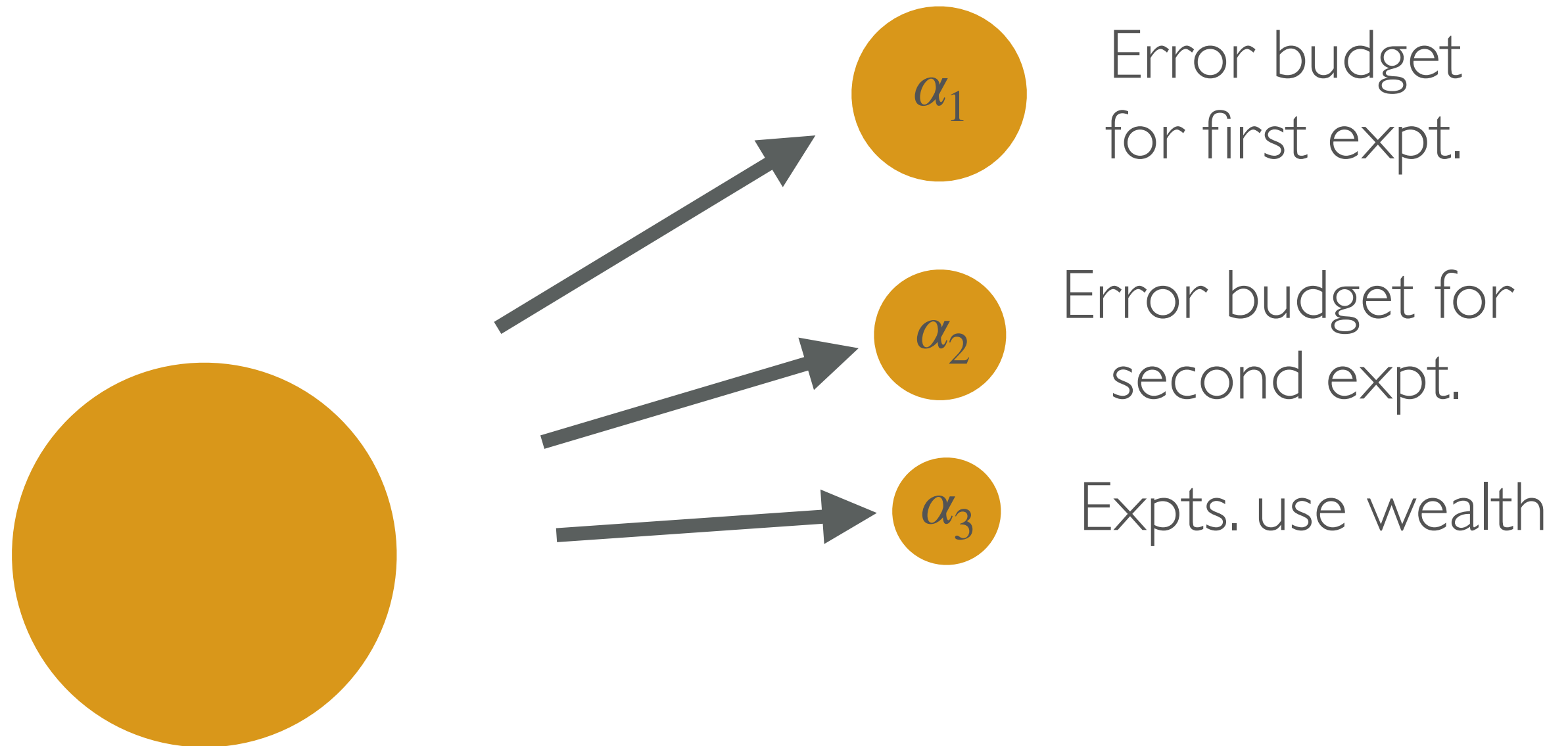
Error budget  
for first expt.

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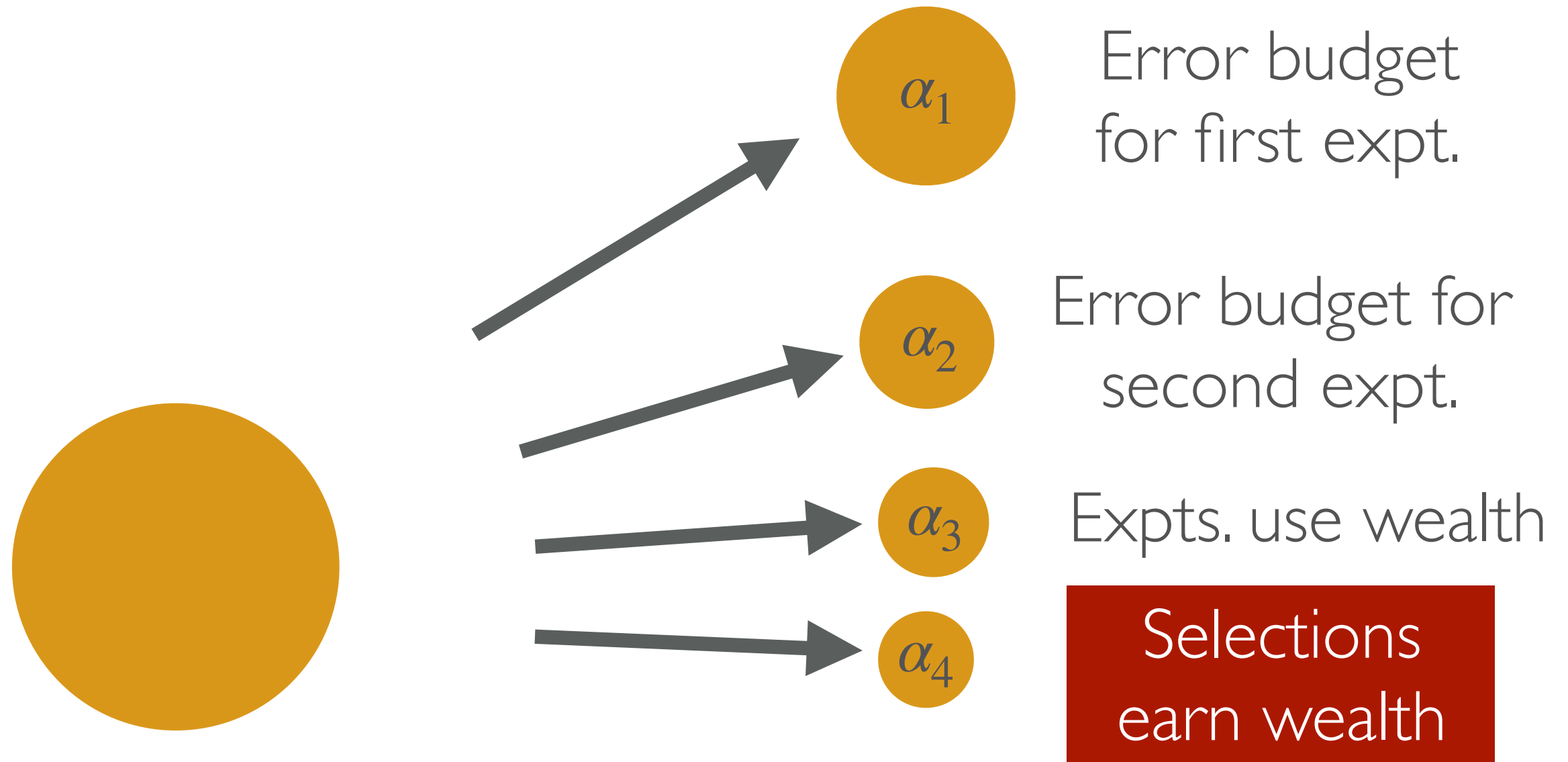


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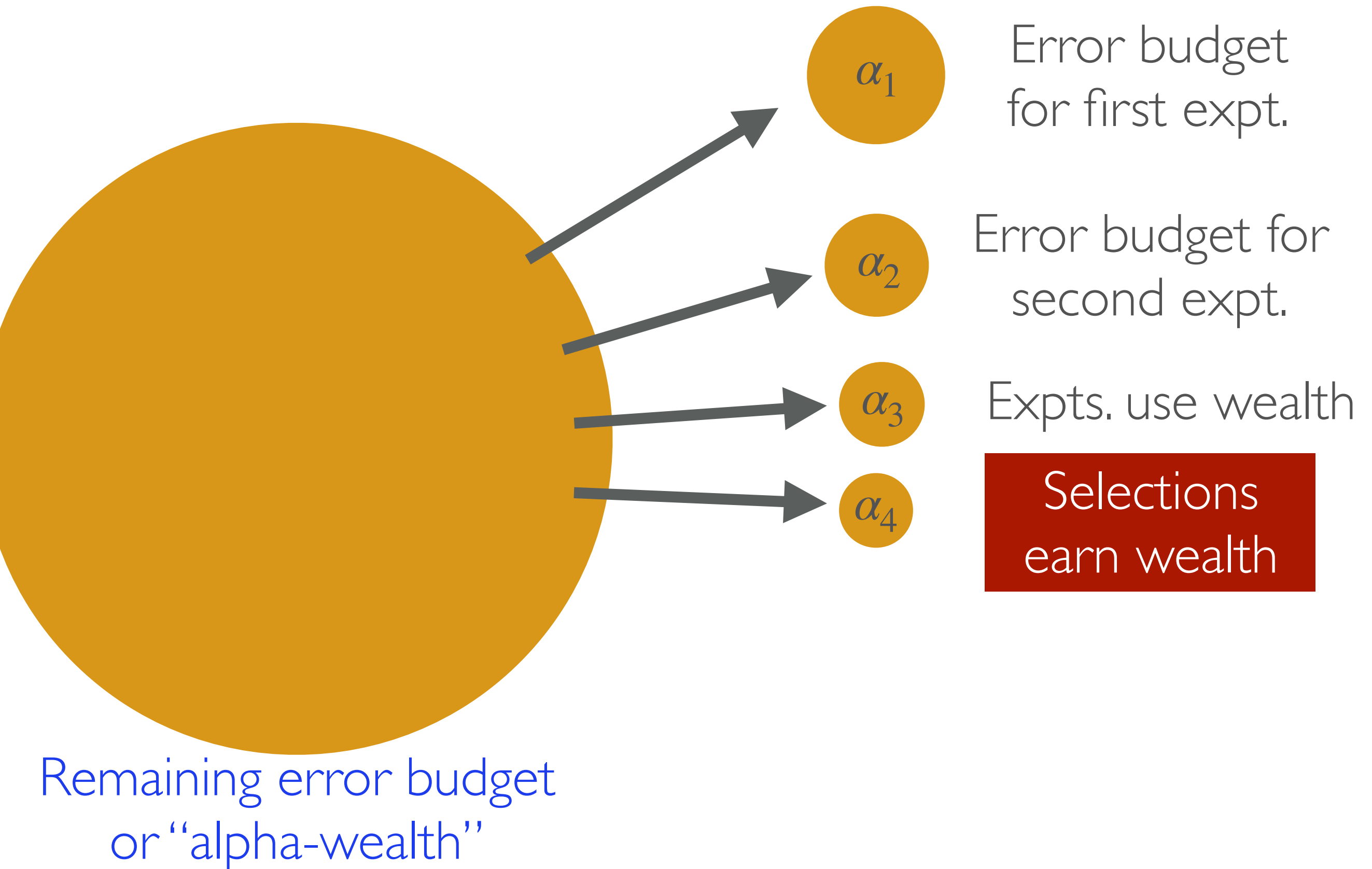


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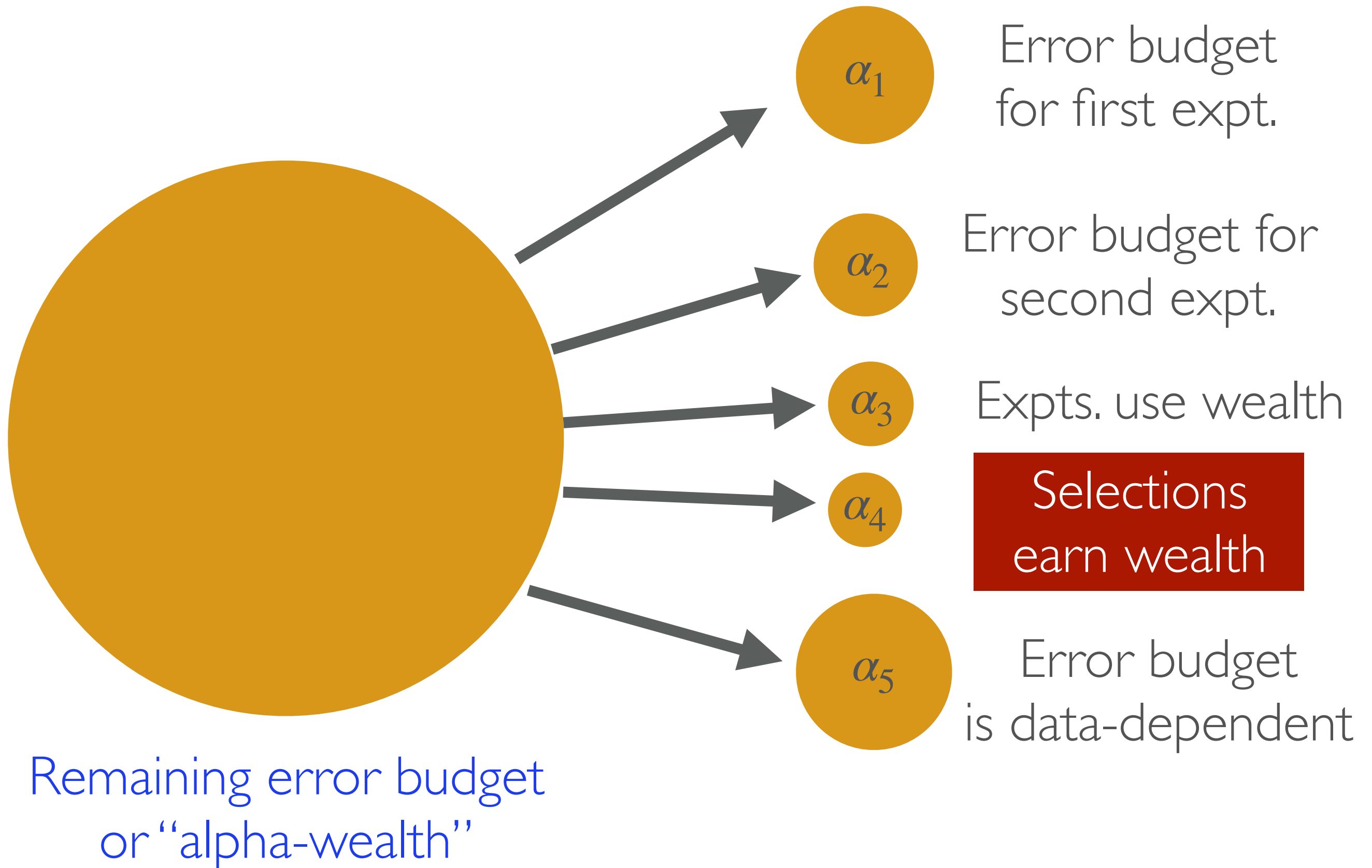


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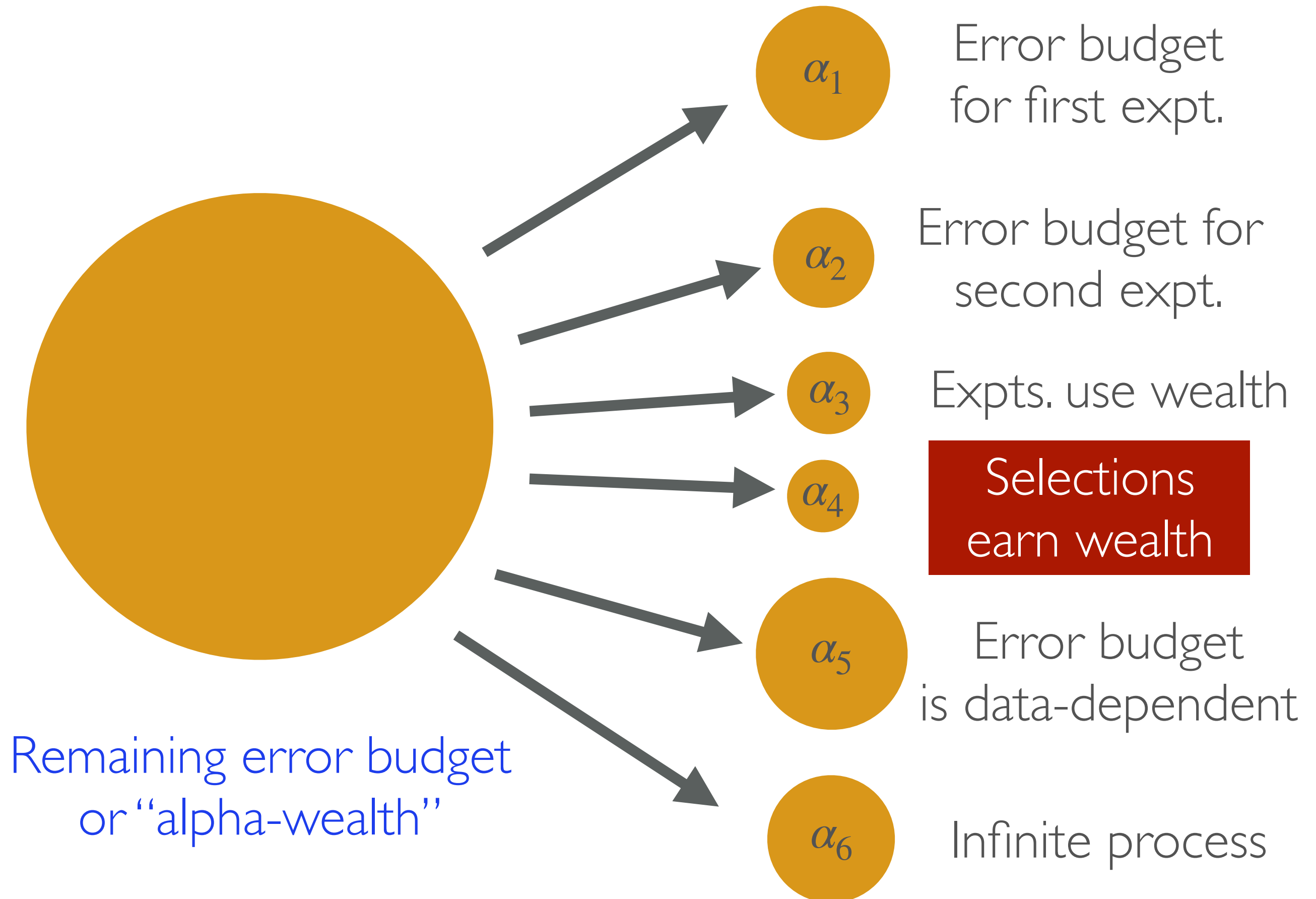


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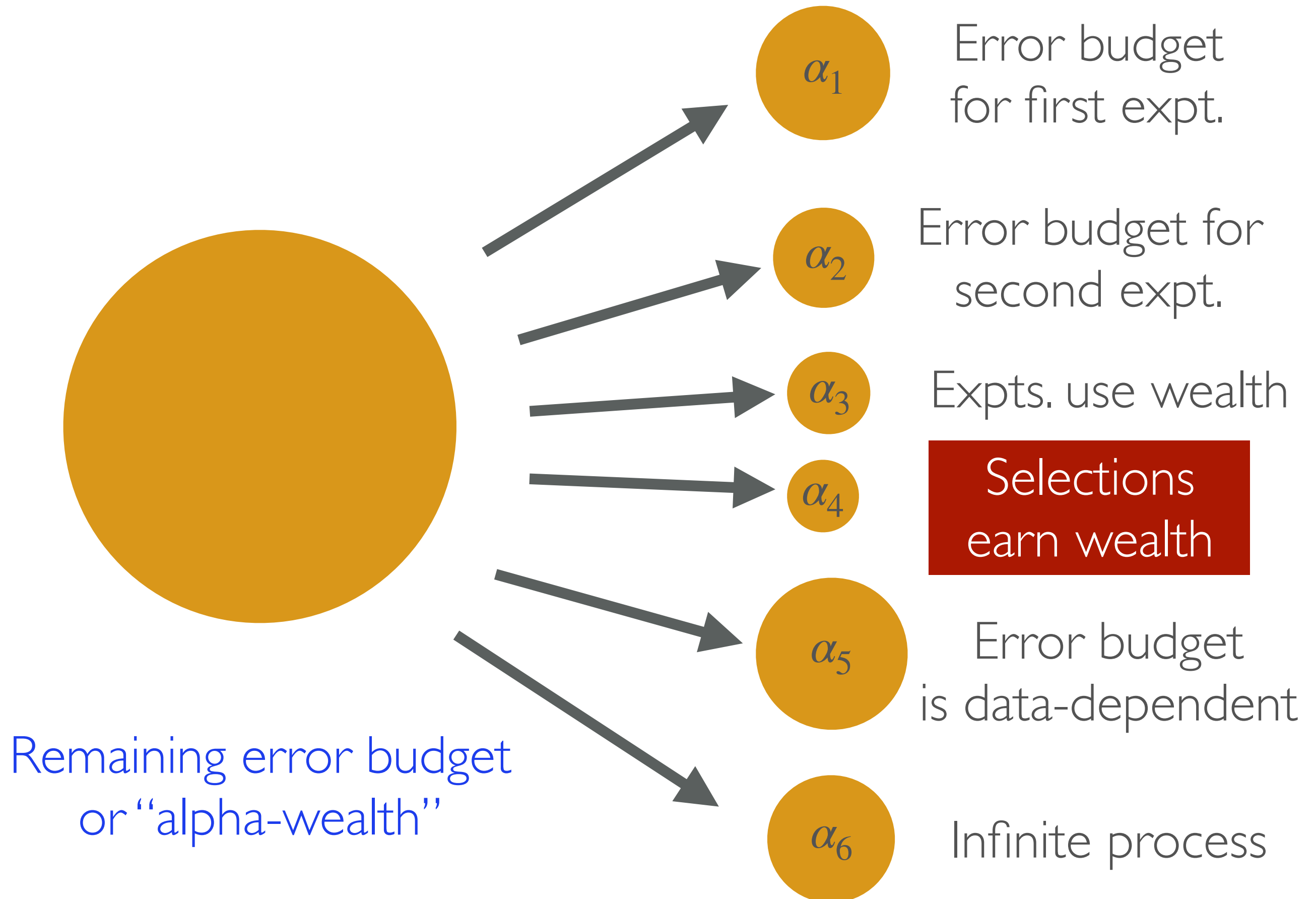




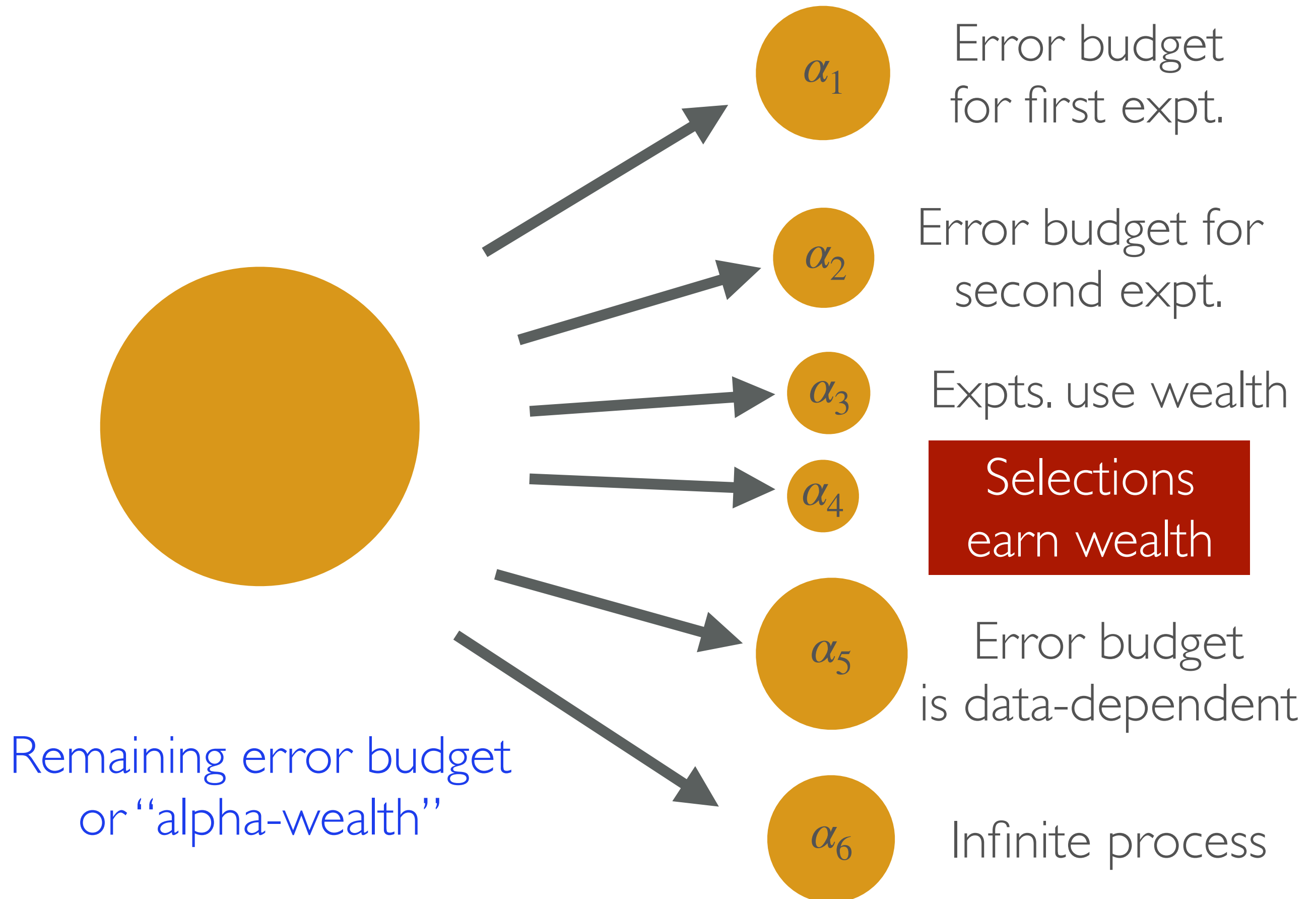
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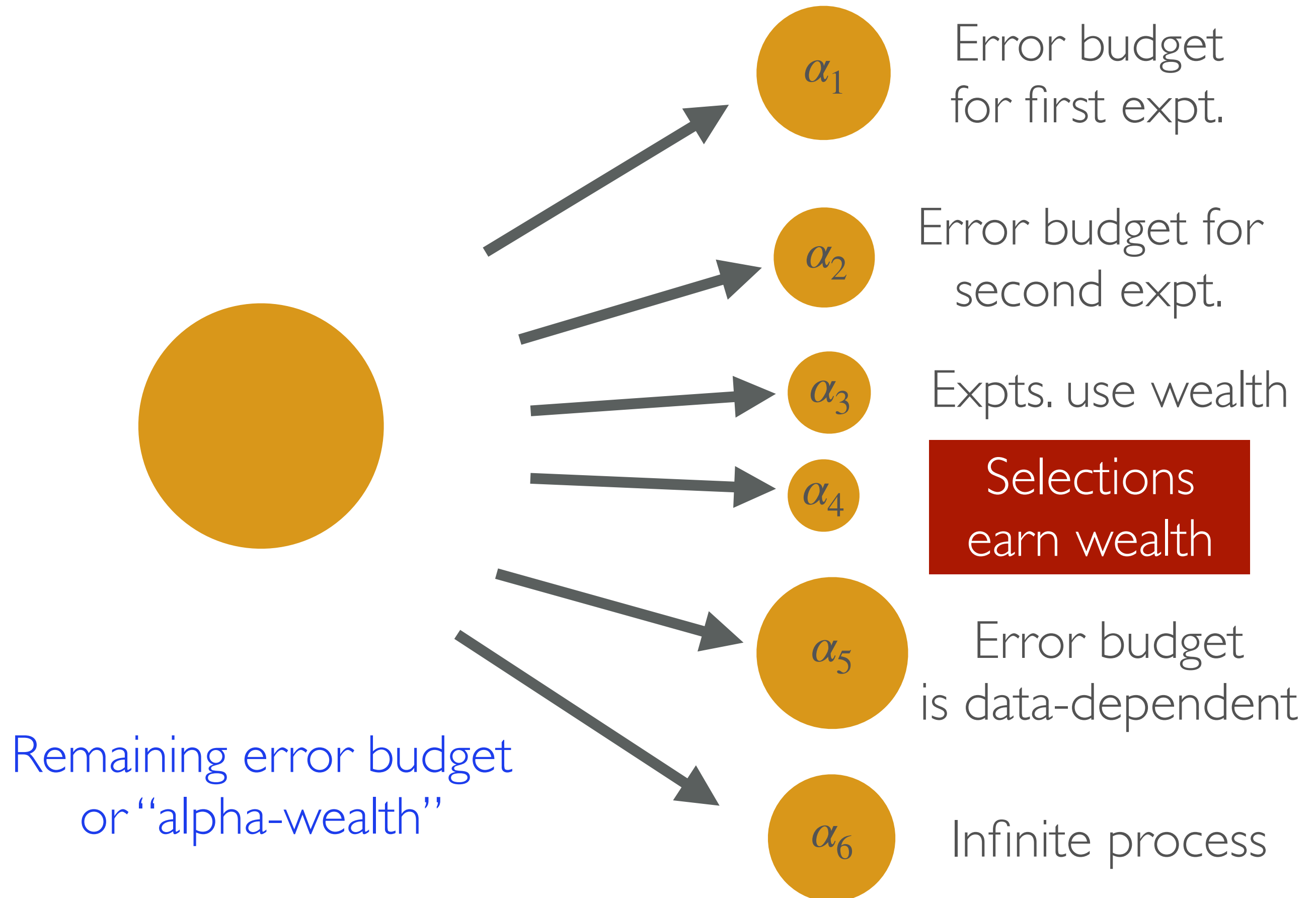
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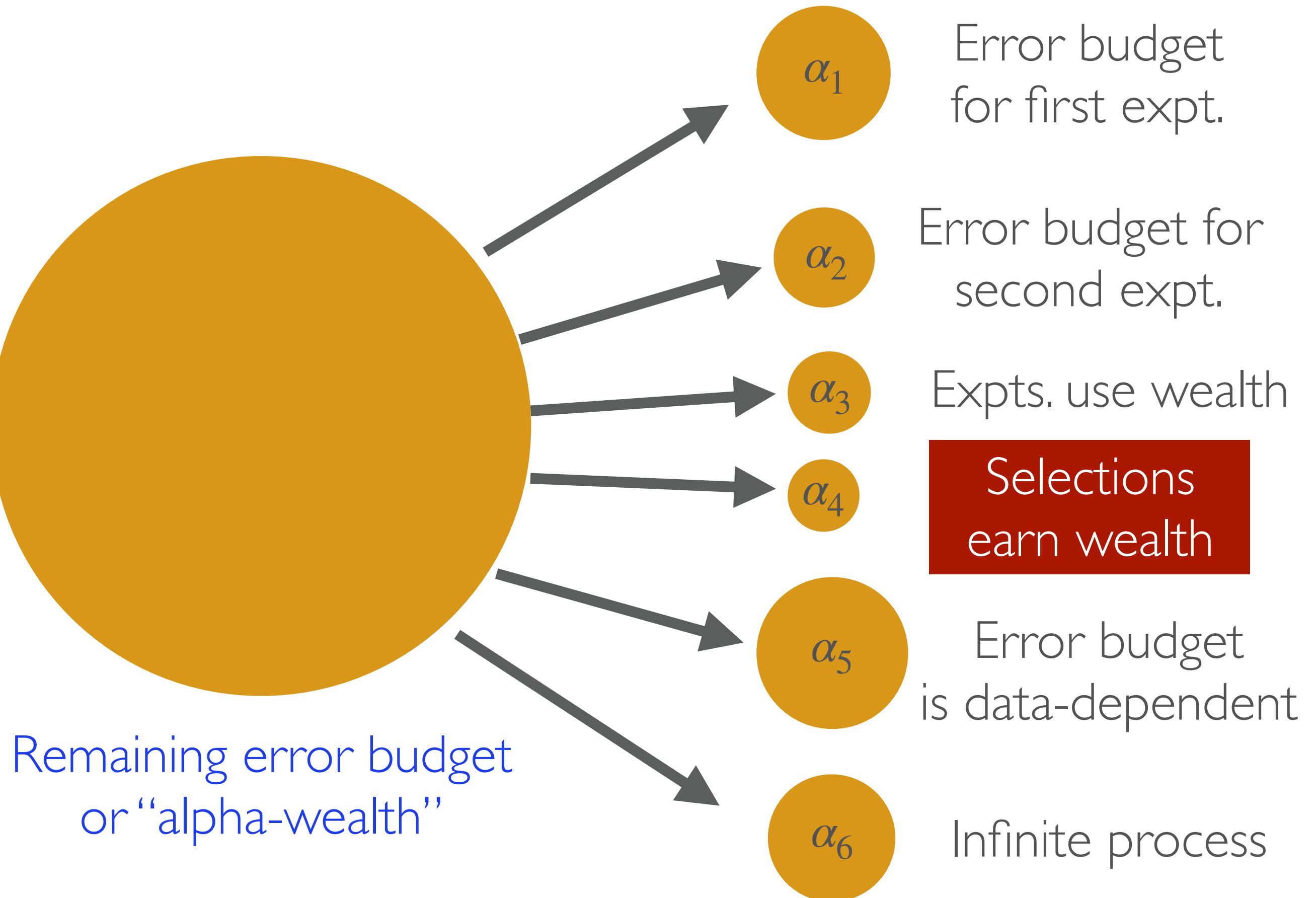
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- $\forall t, \text{error}_t \leq \alpha$  does not imply  $\forall t, \text{FDR}(t) \leq \alpha$ , even if hypotheses, data, p-values are independent.
- Can track a **running estimate** of the FDP (or FCP):  
a simple update rule to keep this estimate bounded  
also results in the FDR (or FCR) being controlled.



# Handling local dependence

Most online FDR algorithms assume independent p-values (but hypotheses can be dependent).

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The online FDR and FCR algorithms can be easily modified to handle local dependence.

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*“confidence sequence” for estimation*  
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**Modular solutions: fit well together**  
**Many extensions to each piece**

Part III



Putting the modular pieces together:  
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[Next 10 mins]

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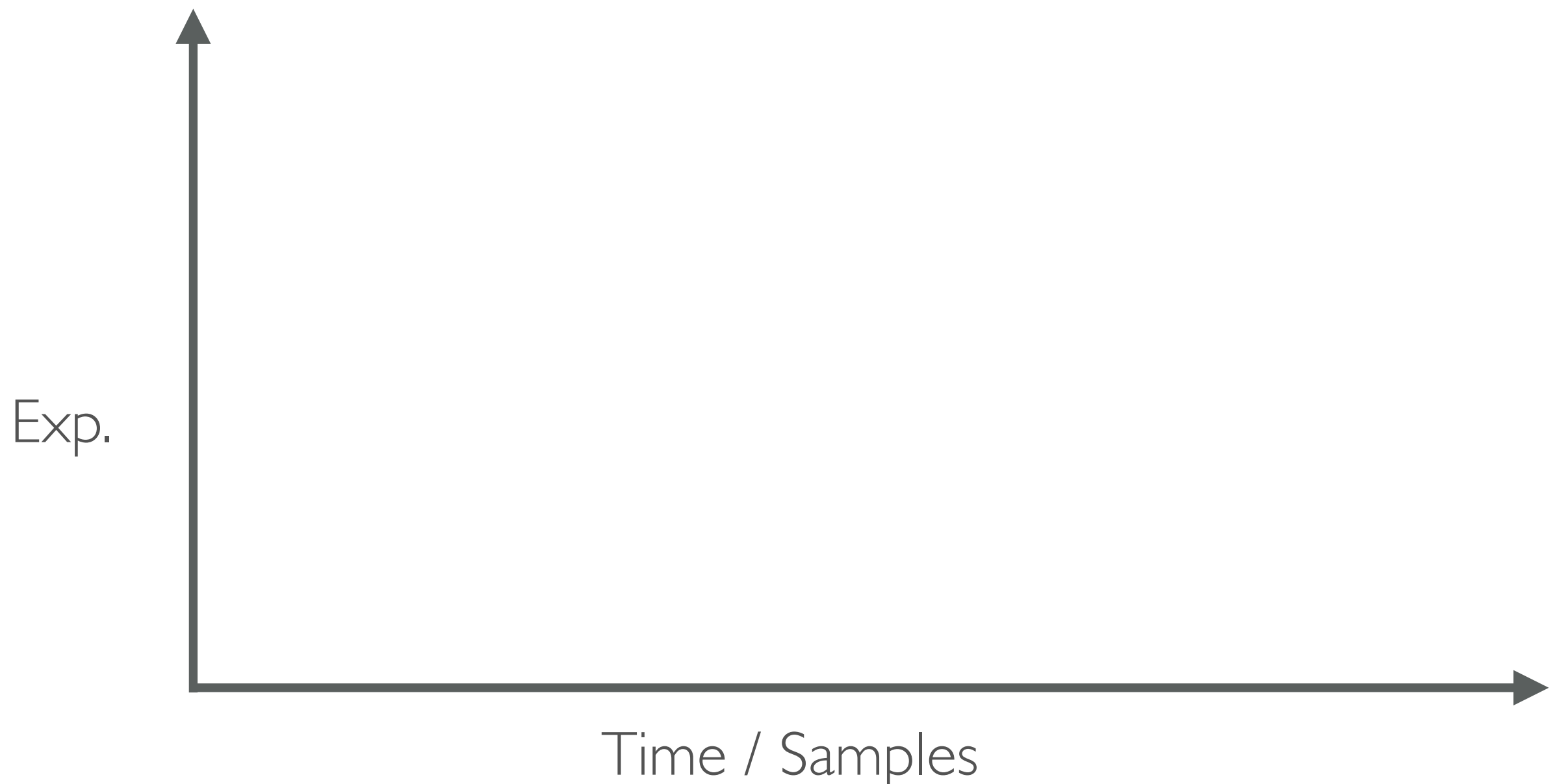
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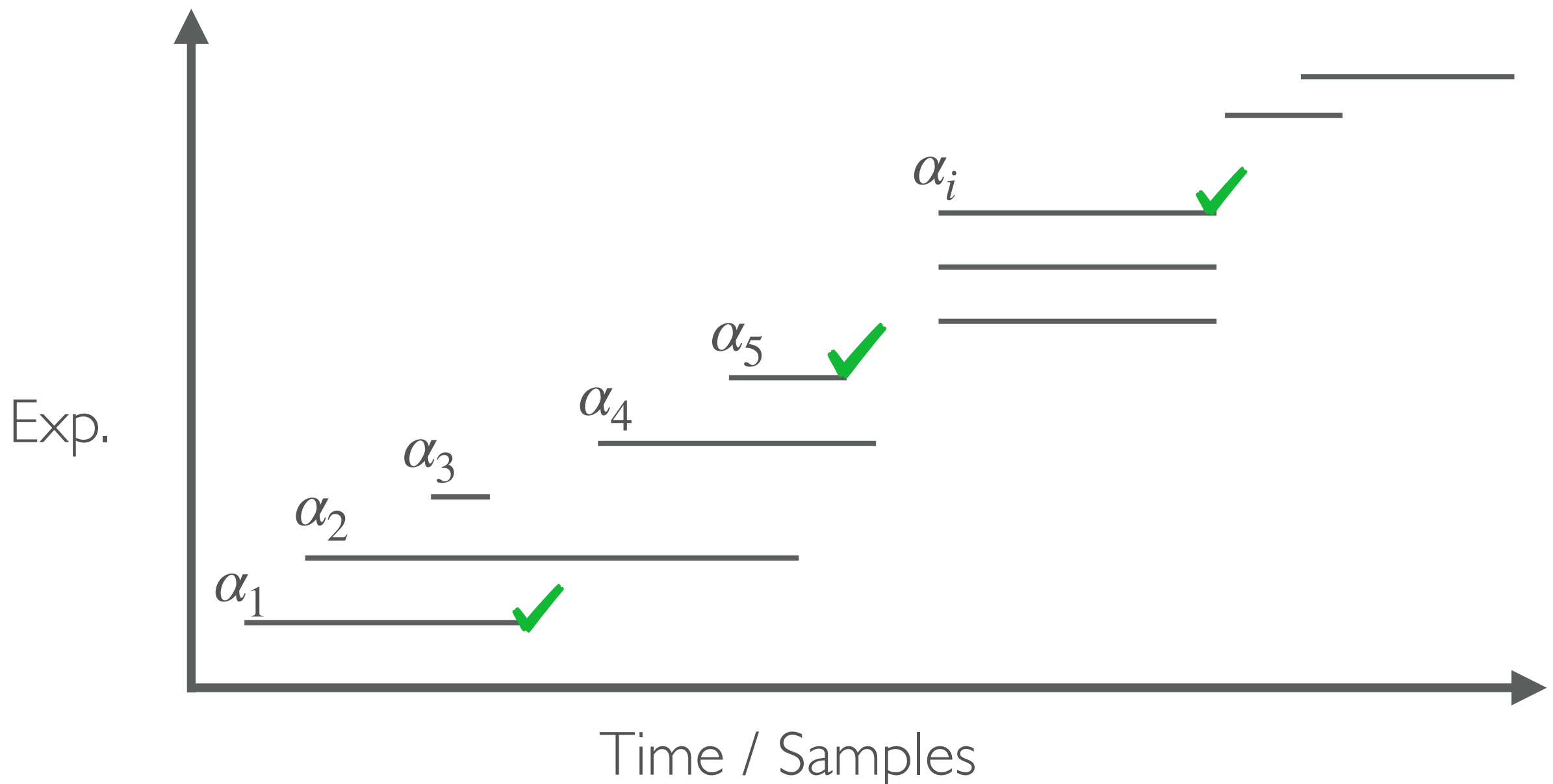
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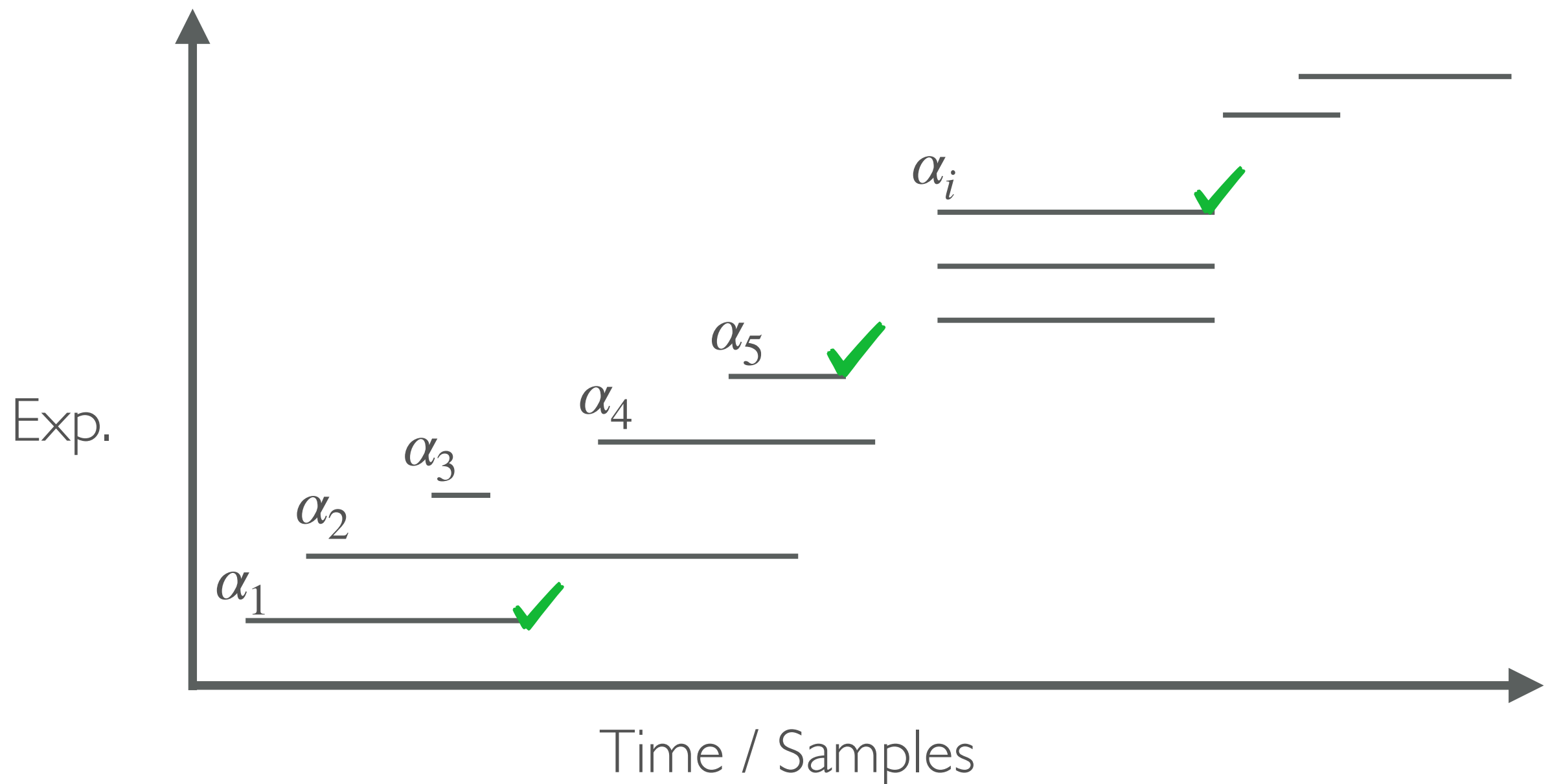


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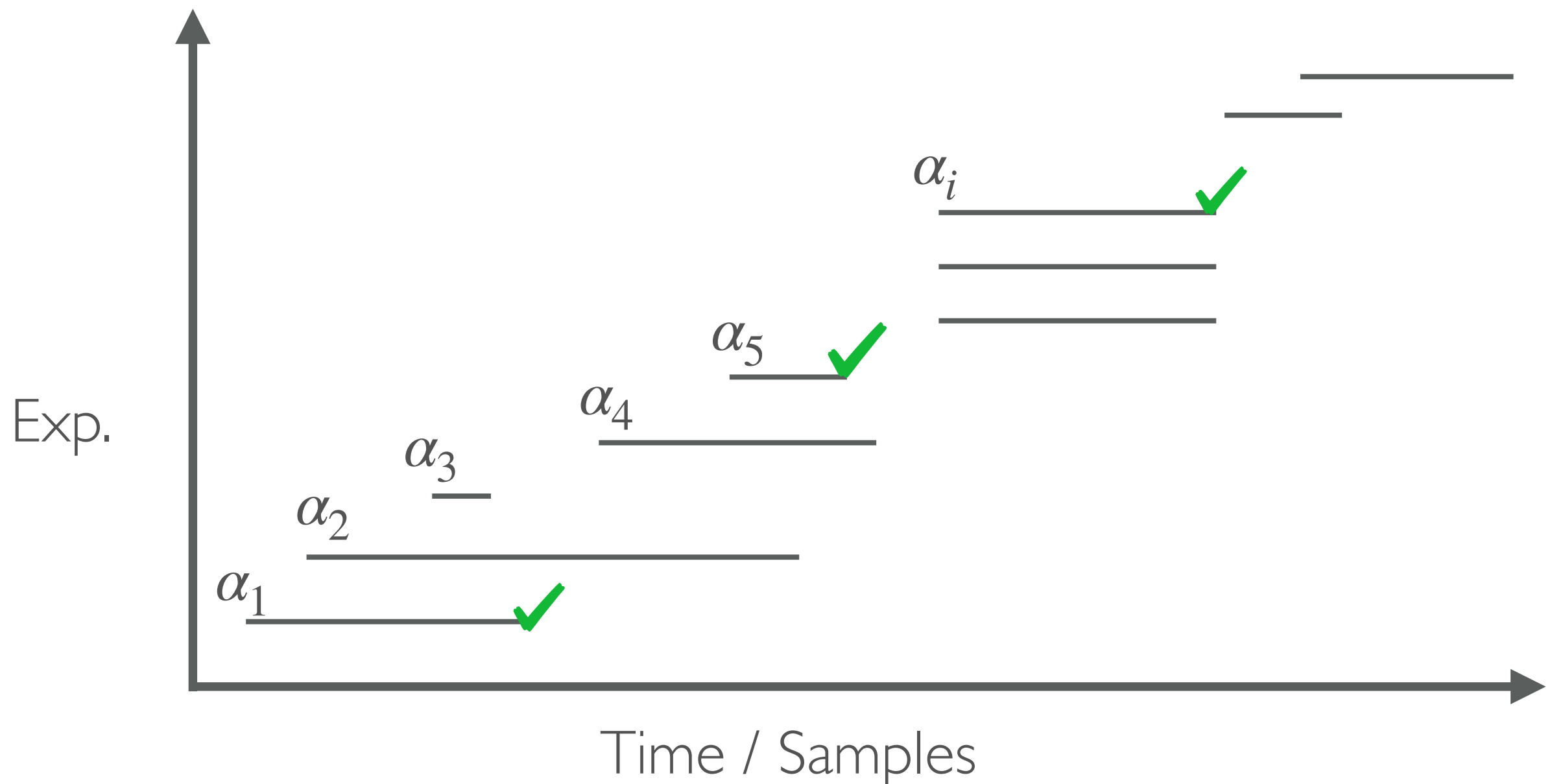


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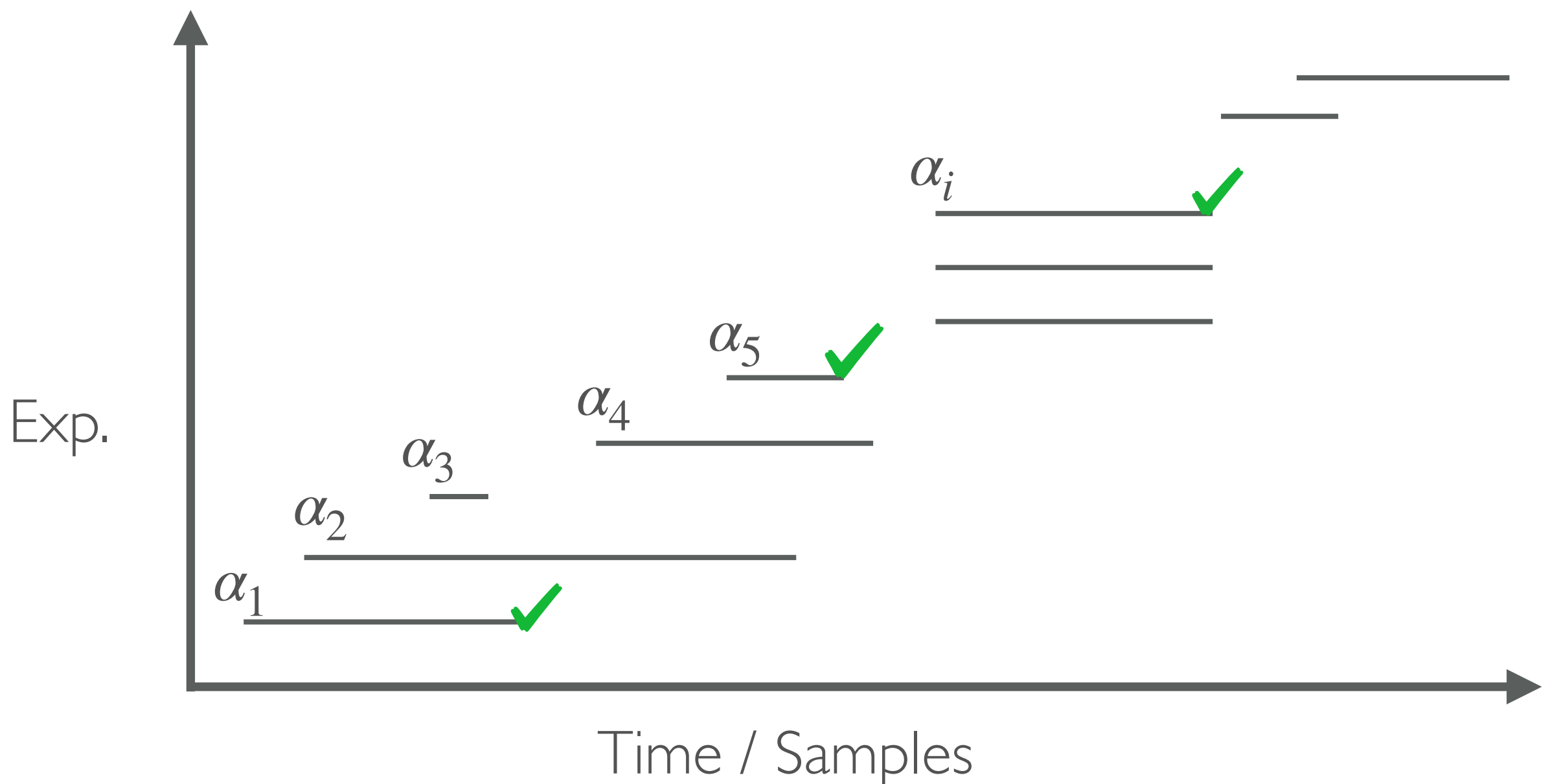
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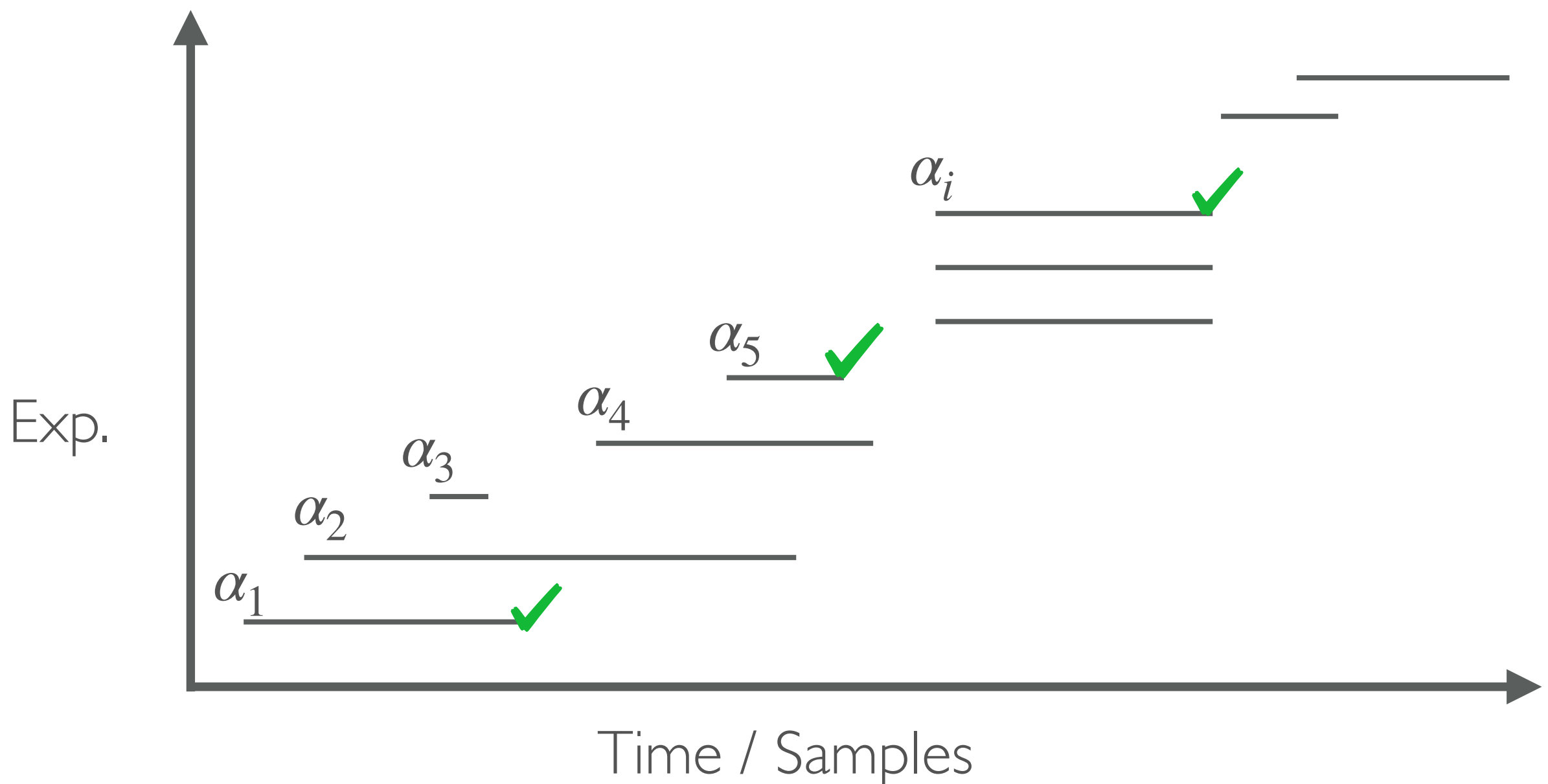
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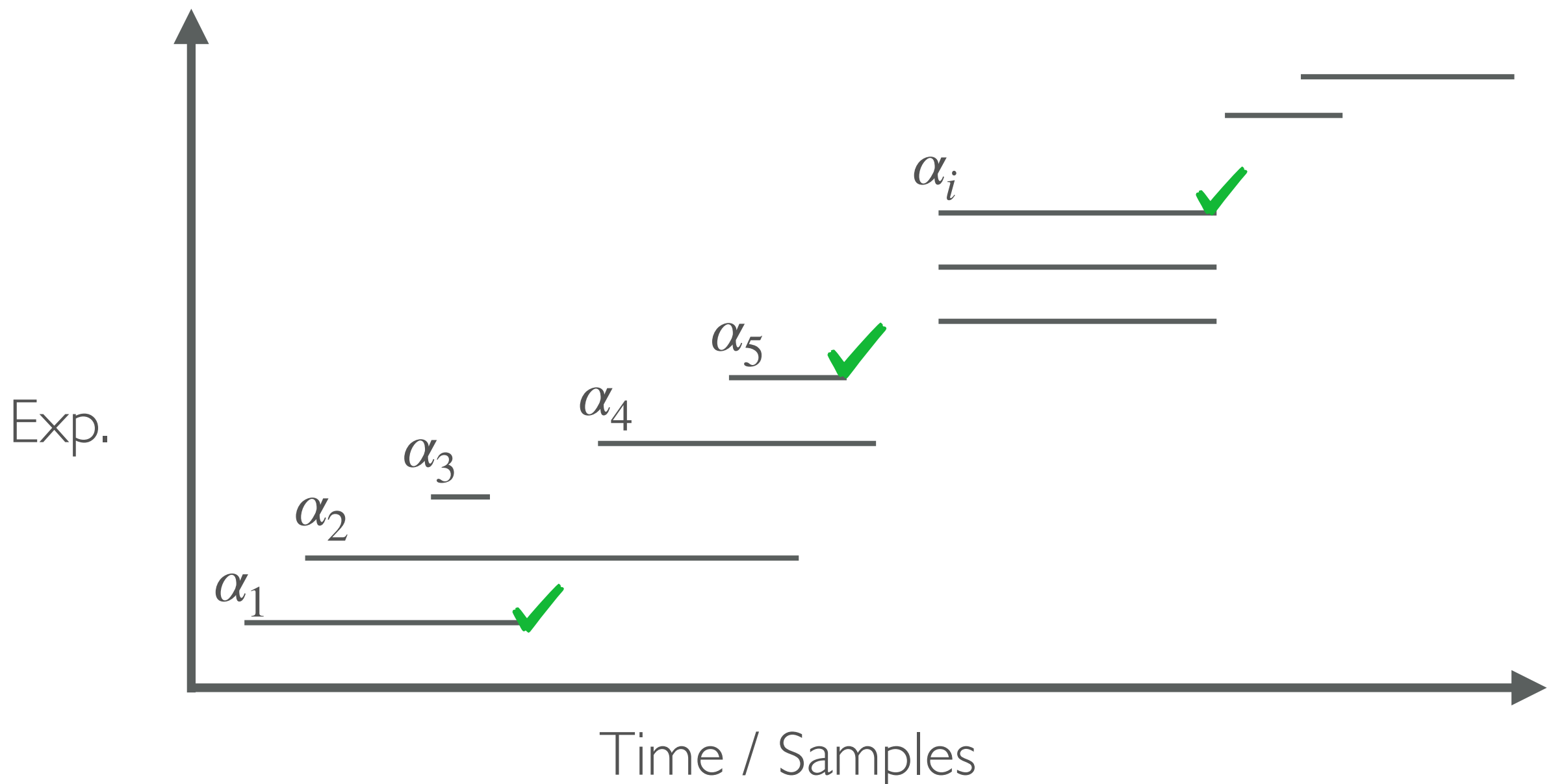
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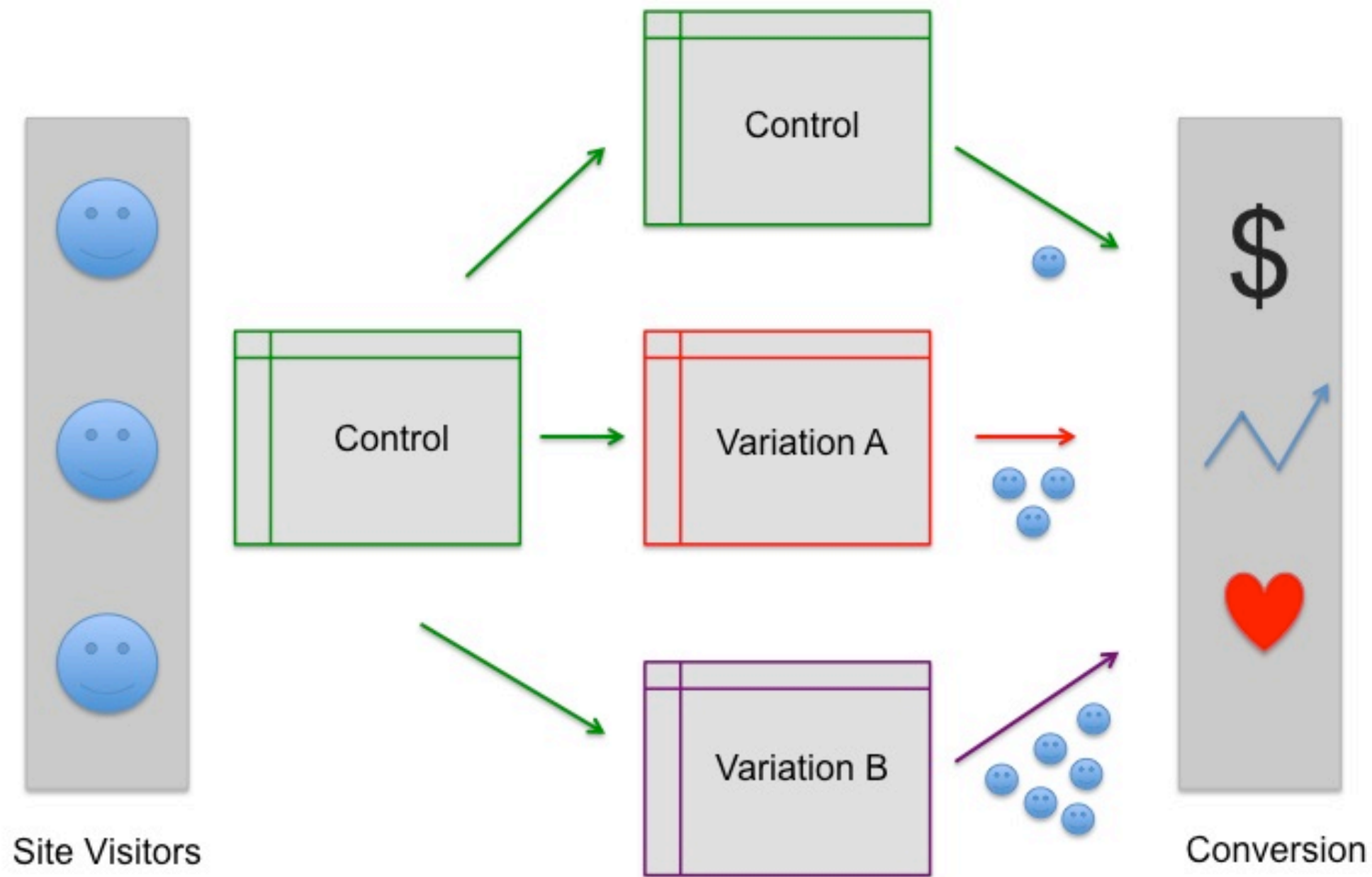
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# PART IV: Advanced topics (inner sequential process)

[Next 25 mins]

# I. What if we are testing more than one alternative?



Much more traffic needed by an A/B/n test



# I. Multi-armed bandits for hypothesis testing



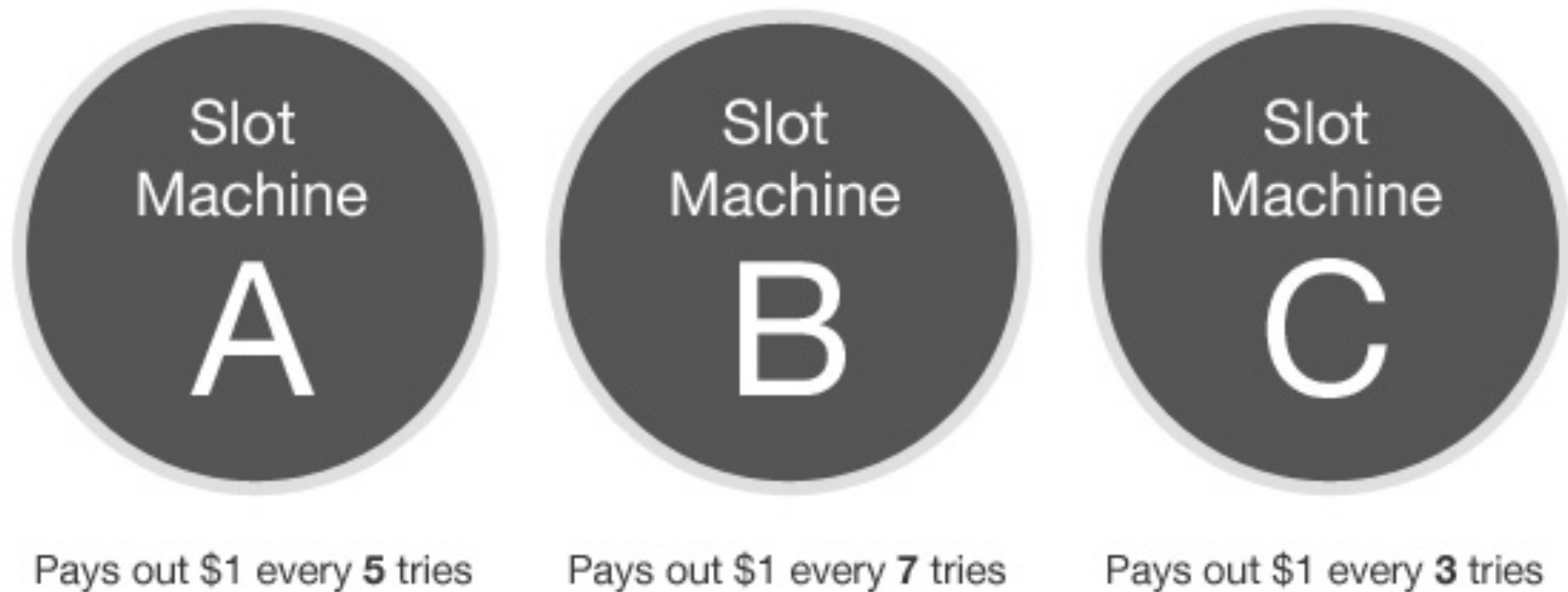
Pays out \$1 every **5** tries

Pays out \$1 every **7** tries

Pays out \$1 every **3** tries

What would **you** do?

# I. Multi-armed bandits for hypothesis testing



What would **you** do?

Depends on the aim: minimize regret OR identify best arm?

We would like to test null hypothesis

$$H_0 : \mu_A \geq \max\{\mu_B, \mu_C\} .$$

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desired FDR level  $\alpha$

Online FDR procedure

$\alpha_j$

$R_j(\alpha_j)$

$\alpha_{j+1}$

$R_{j+1}(\alpha_{j+1})$

Exp j

Exp j+1

MAB

$p_j(\alpha_j)$

Test

$p_j < \alpha_j$

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MAB-FDR meta algorithm



## 2. Switch from estimating means to quantiles?

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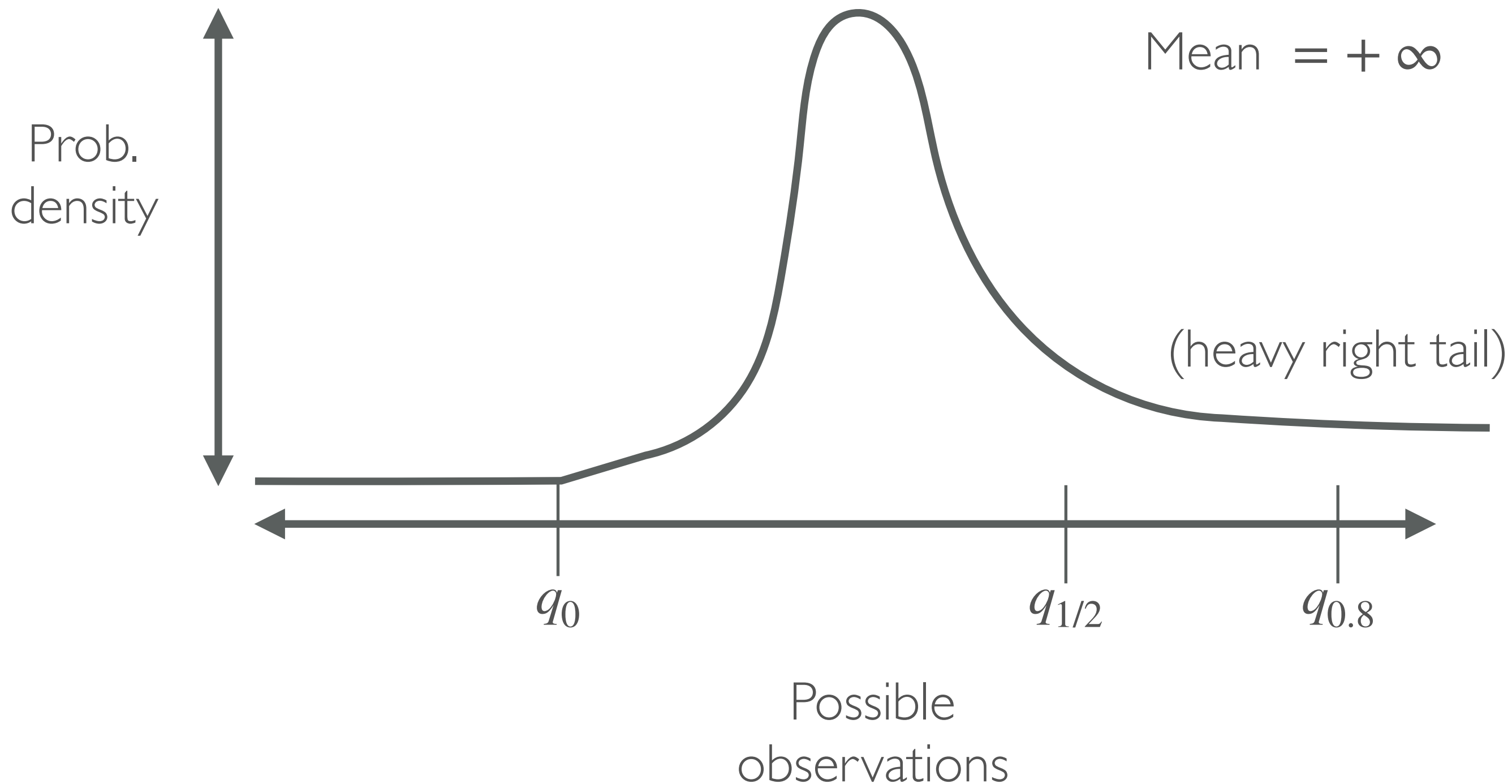
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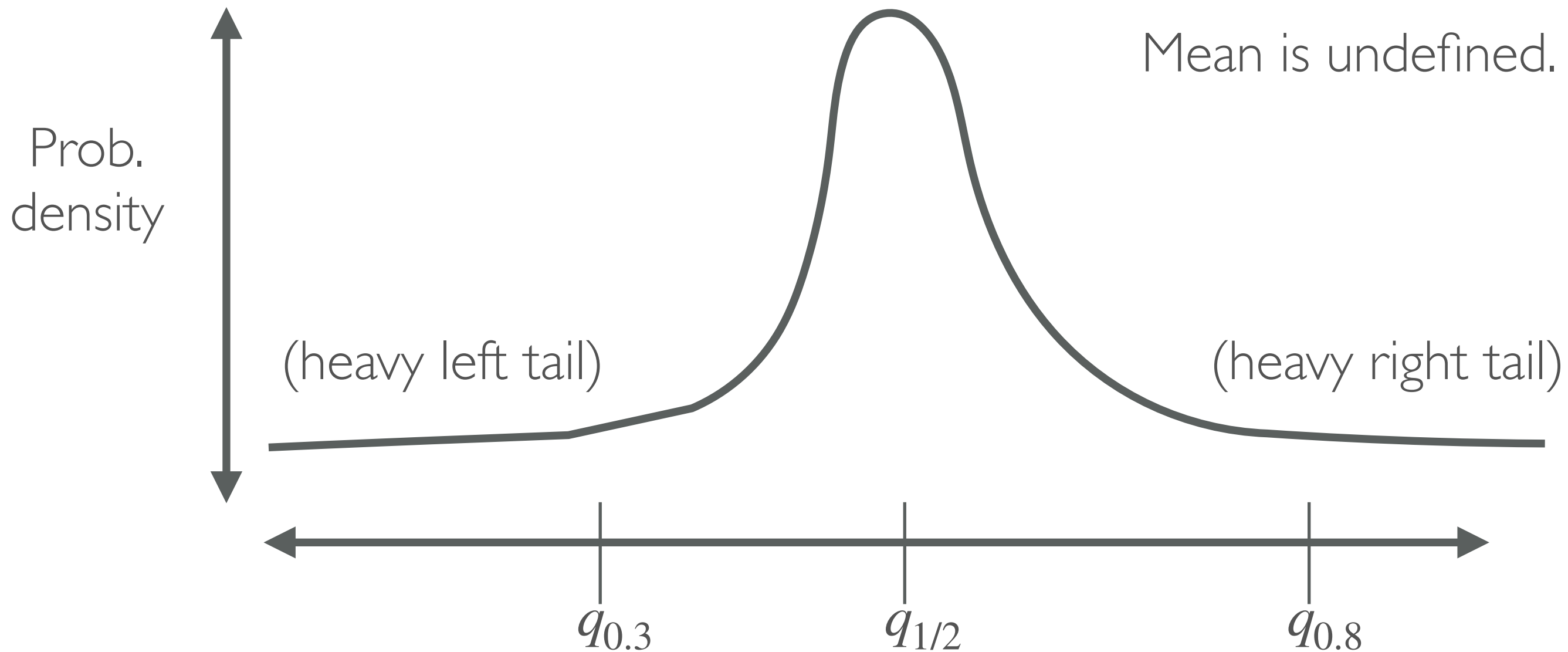
**Can also estimate all quantiles simultaneously!**

## 2. Quantiles are informative for heavy tails



Eg: amount of time spent on Reddit

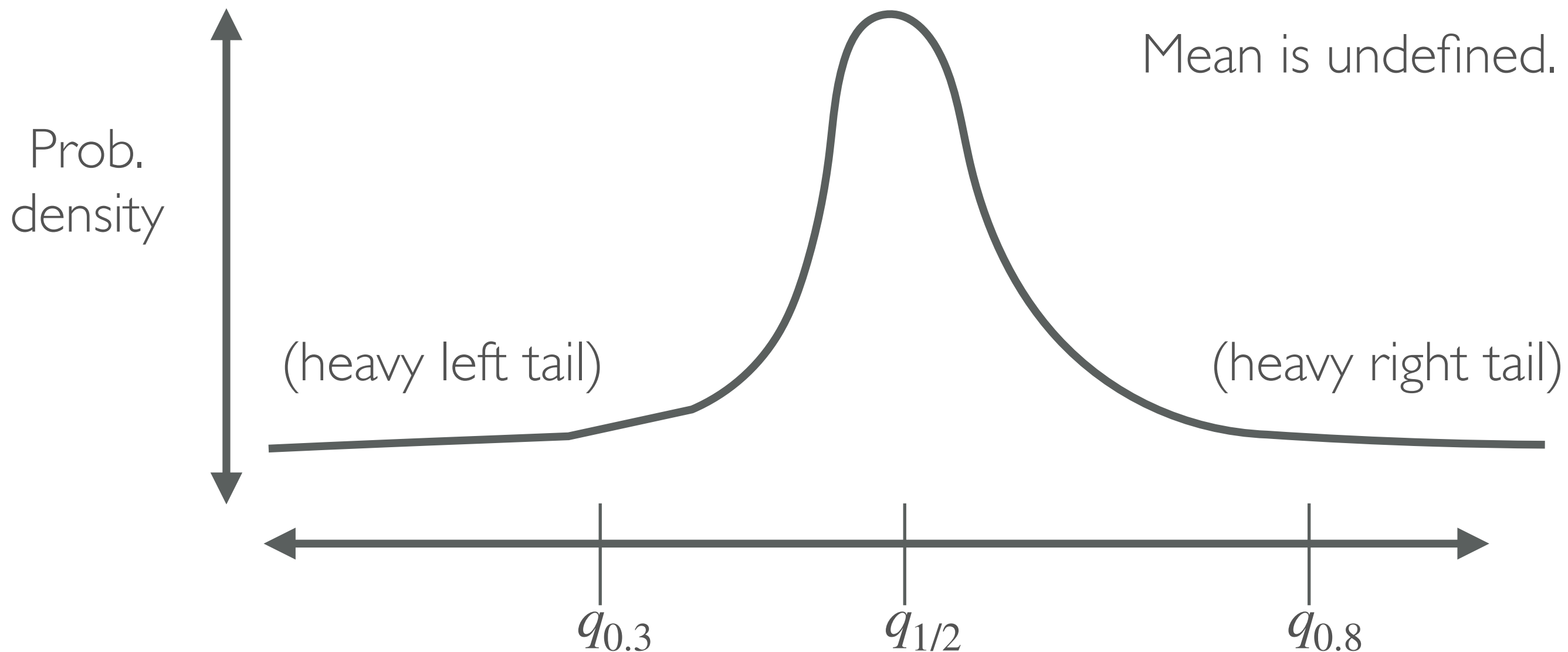
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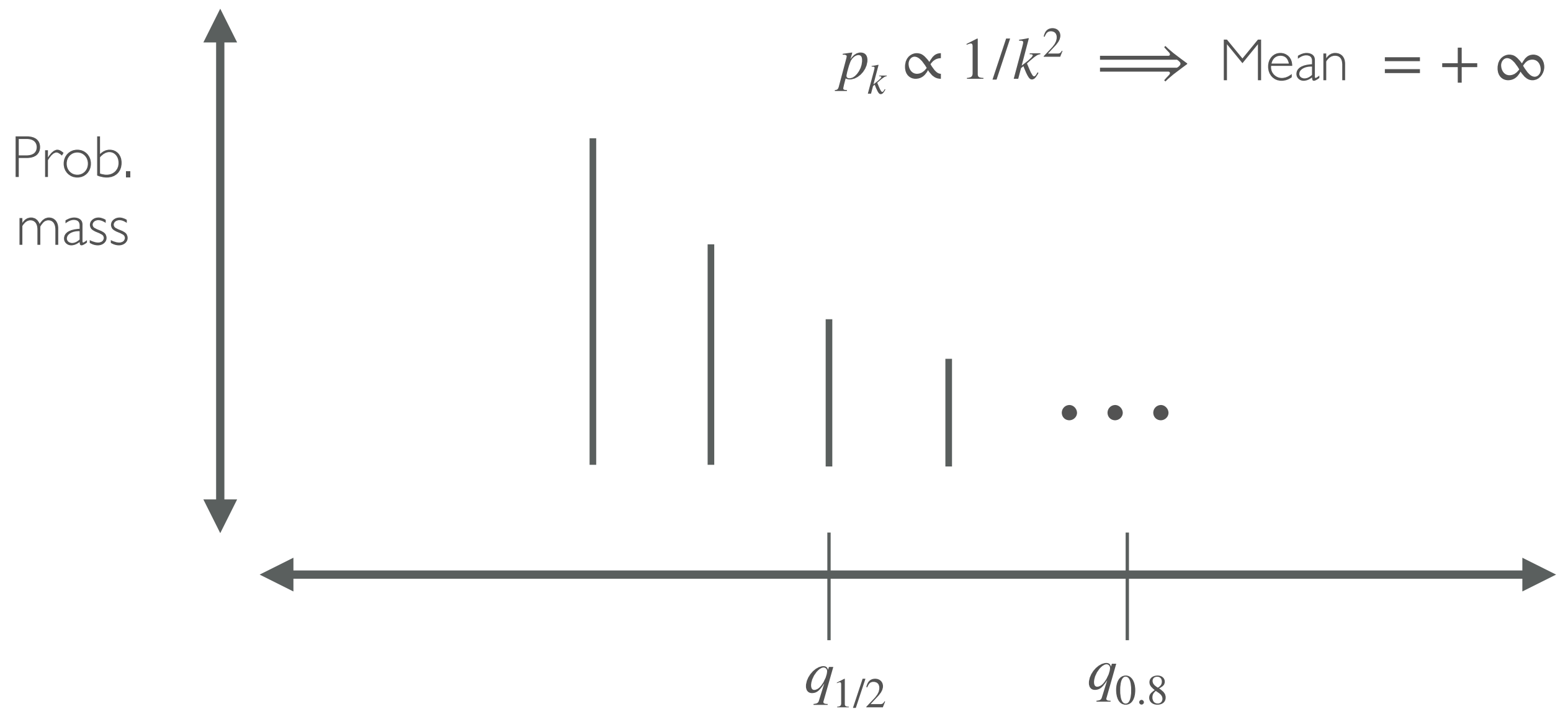
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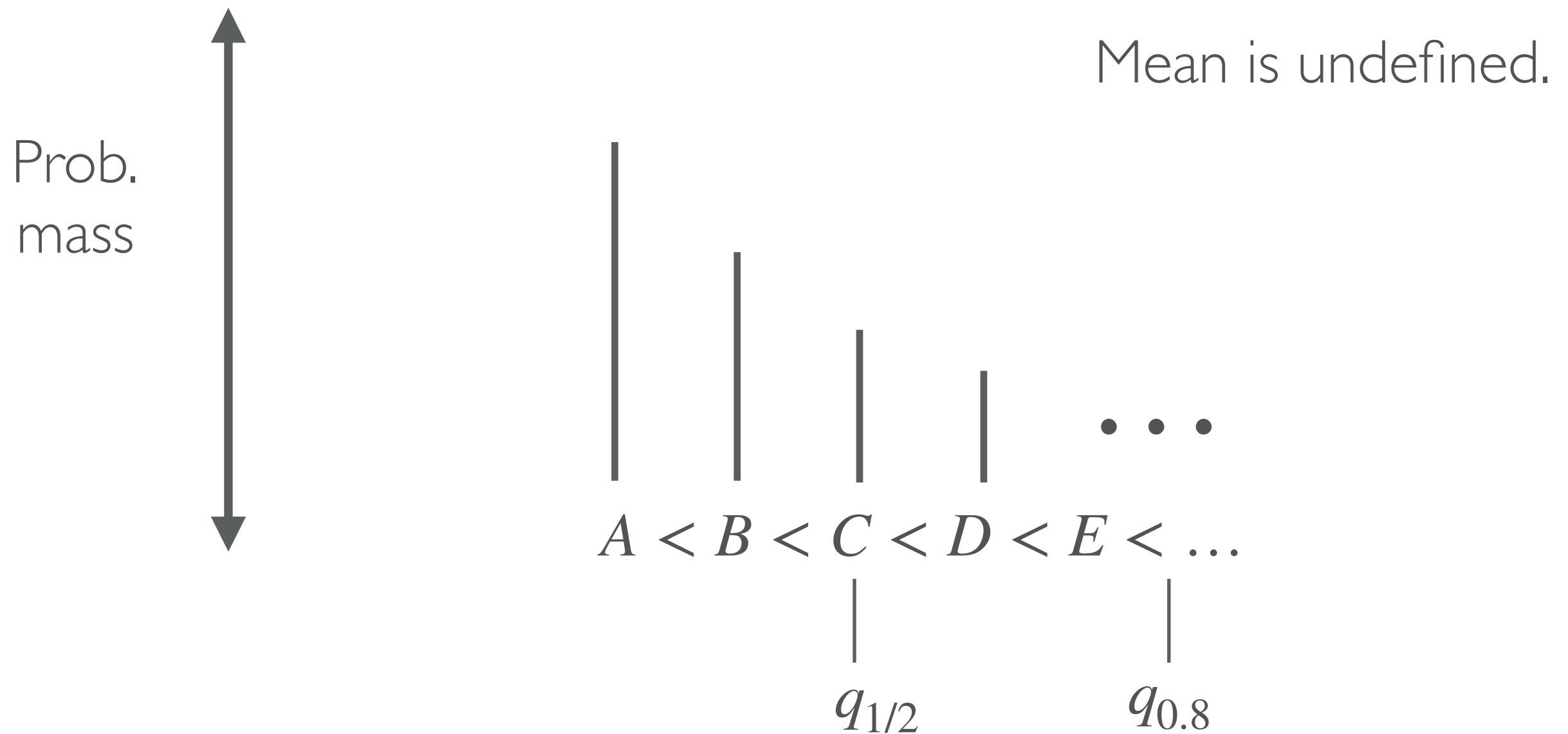
Do not need to resort to trimming “outliers”.  
(How to pick threshold? Throw away or cap?)

## 2. The same could arise in discrete settings



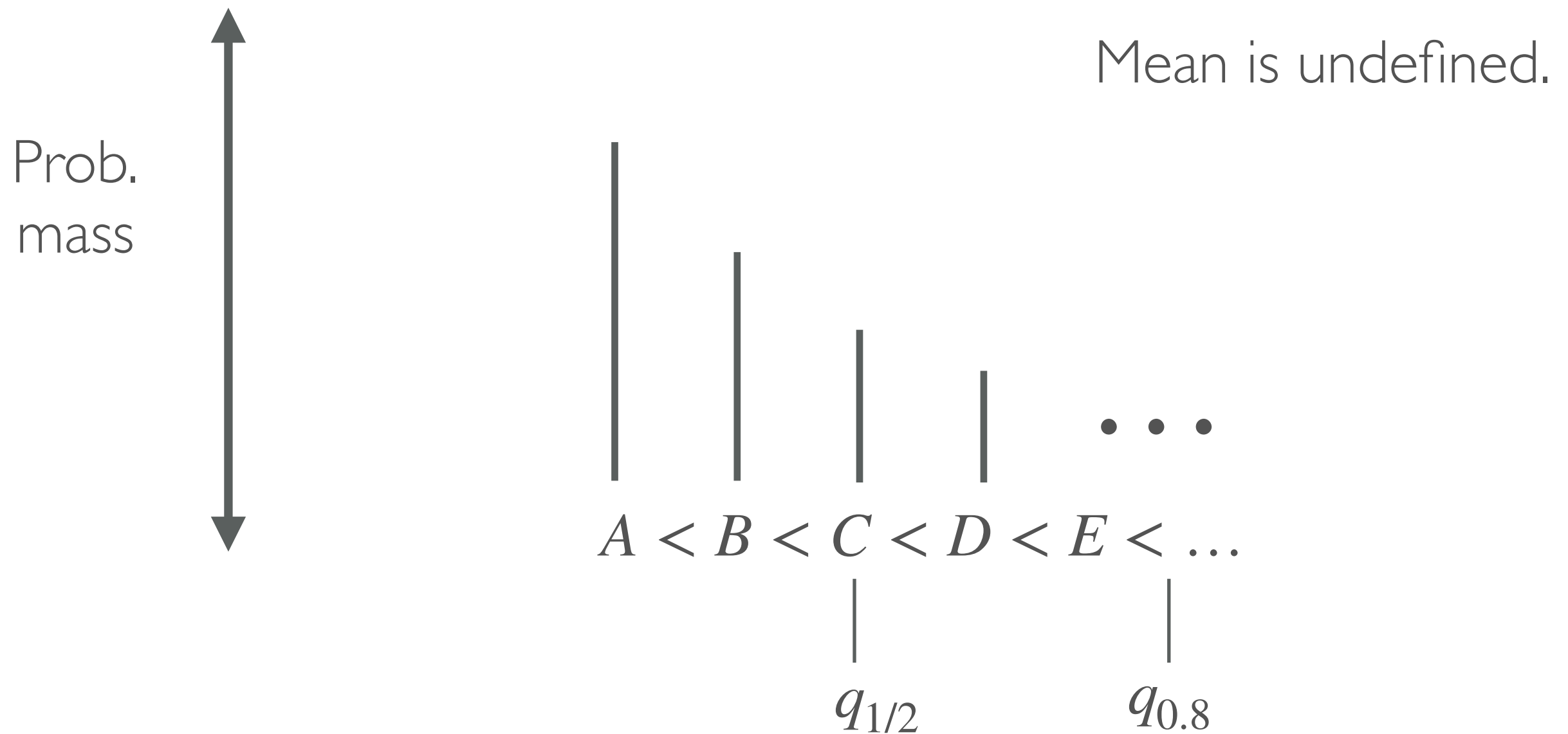
Eg: number of links clicked

## 2. Quantile sensible in totally ordered settings



Eg: grades or non-numerical ratings

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Do not need to artificially assign numerical values.  
(Are they equally spaced? Spacing and start point matter.)

## 2. A/B testing with quantiles

First pick target quantile  $\alpha$  (say 0.9).

$$H_0 : q_{0.9}(A) = q_{0.9}(B)$$

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(In that case, one way to define sequential p-value is the smallest  $\delta$  such that the  $(1 - \delta)$  CS overlaps with  $\mathbb{R}_0^-$ .)

## 2. Best-arm identification with quantiles



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If the first arm is “special”, can design MAB algorithms to adaptively test the null hypothesis that A is best, and get a sequential p-value.

### 3. Running intersections or minimums: pros/cons

Fact 1: if  $P^{(n)}$  is an anytime p-value, so is  $\min_{m \leq n} P^{(m)}$ .

Fact 2: if  $(L^{(n)}, U^{(n)})$  is a confidence sequence, so is  $\bigcap_{m \leq n} (L^{(m)}, U^{(m)})$ .

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- Smaller width, hence tighter inference, without inflating error.

#### **Con of taking running intersections of CIs :**

- Can have intervals of decreasing width (great!) and then in the next step, end up with an empty interval (disconcerting).



### 3. Running intersections or minimums: pros/cons

Fact 1: if  $P^{(n)}$  is an anytime p-value, so is  $\min_{m \leq n} P^{(m)}$ .

Fact 2: if  $(L^{(n)}, U^{(n)})$  is a confidence sequence, so is  $\bigcap_{m \leq n} (L^{(m)}, U^{(m)})$ .

#### **Pro of taking running intersections of CIs :**

- Smaller width, hence tighter inference, without inflating error.

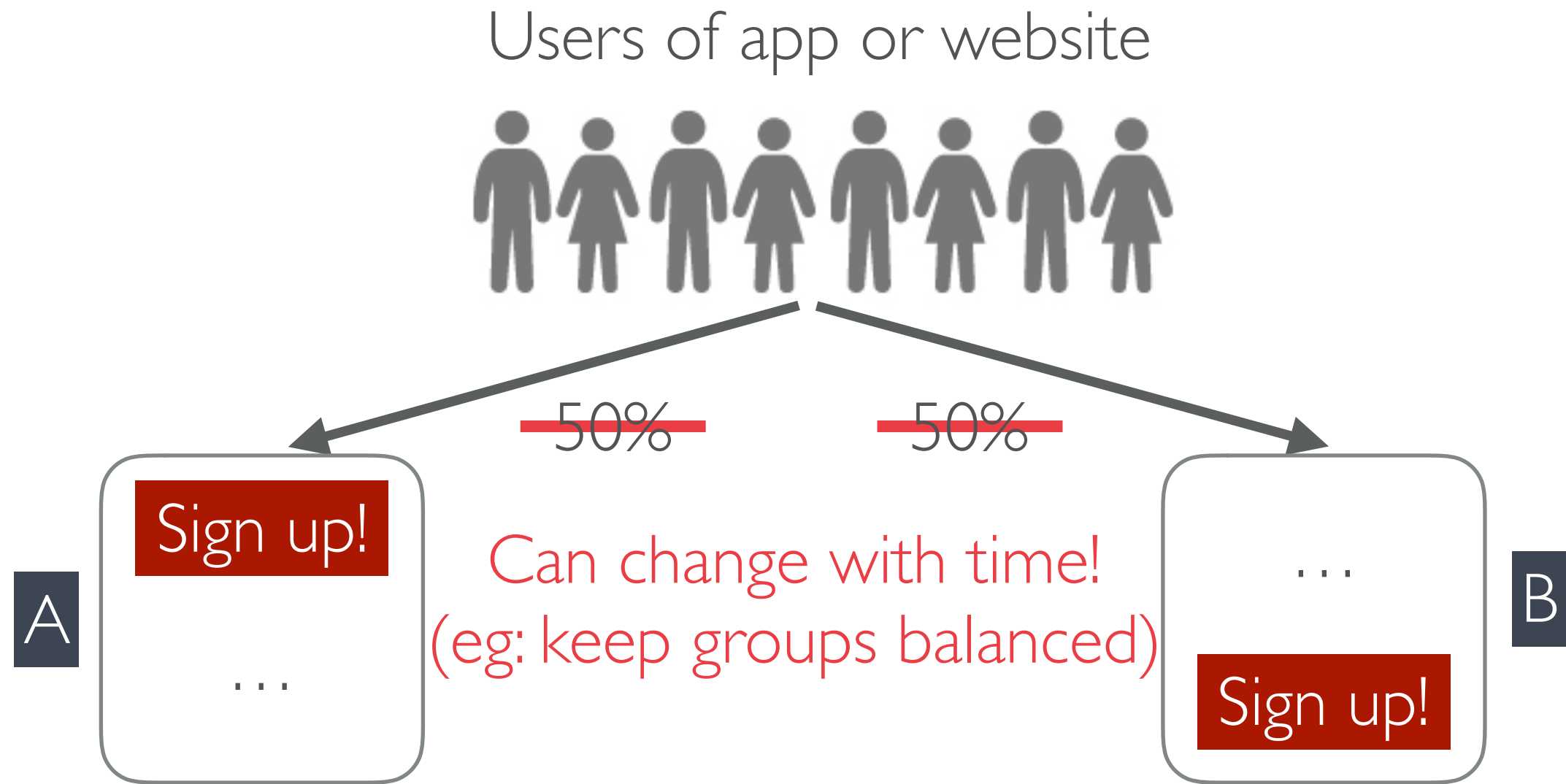
#### **Con of taking running intersections of CIs :**

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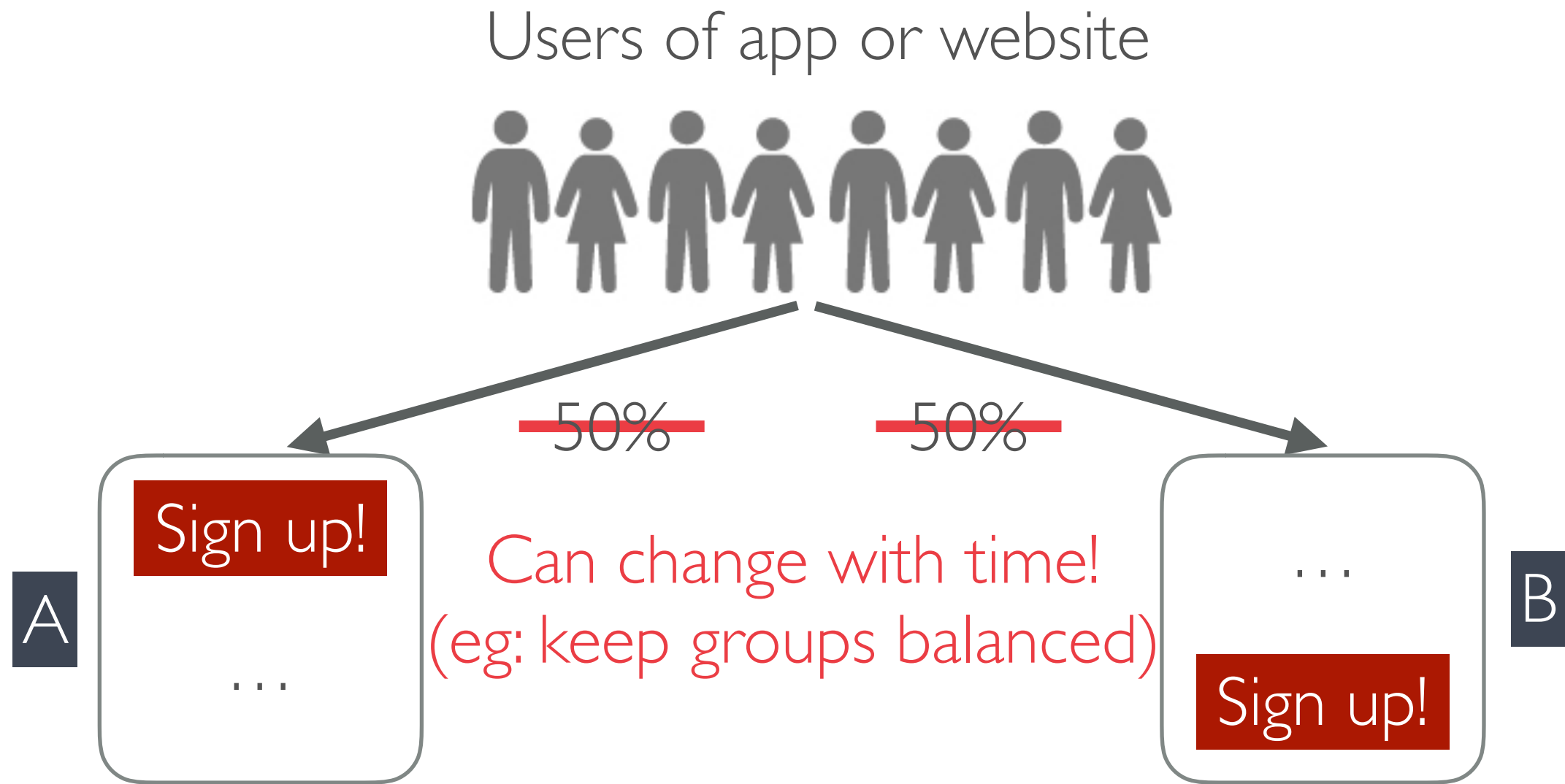
#### **Pro of ending up with zero width :**

- “Failing loudly”: you know you’re in the low-probability error event, or assumptions have been violated.

## 4. Sequential Average Treatment Effect estimation with adaptive randomization



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Can infer the treatment effect sequentially (Neyman-Rubin potential outcomes model) using anytime p-value or CI.

# PART V: Advanced topics (outer sequential process)

[Next 15 mins]

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With probability at least  $1 - \delta$  we have

$$FDP_t \leq \frac{1 + \sum_{i \leq t} \alpha_i}{\sum_{i \leq t} R_i} \cdot \frac{\log(1/\delta)}{\log(1 + \log(1/\delta))} \text{ simultaneously for all } t.$$

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$$FCP_t \leq \frac{1 + \sum_{i \leq t} \alpha_i}{\sum_{i \leq t} S_i} \cdot \frac{\log(1/\delta)}{\log(1 + \log(1/\delta))} \text{ simultaneously for all } t.$$

# 3. Weighted error metrics and algorithms

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Can define “weighted” variants of FDR and FCR  
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Online FDR and FCR algorithms can be extended to  
control weighted error metrics.

## 4. False-sign rate

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Sometimes, all we want is a “sign decision” about parameter:  
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$$FSR := \mathbb{E} \left[ \frac{\# \text{ incorrect sign decisions made}}{\# \text{ sign decisions made}} \right]$$

To control the FSR, just using the online FCR algorithm, and report the sign iff the CI does not contain zero.

Open Problems [5 mins]

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A large number of different teams run such A/B tests or randomized experiments

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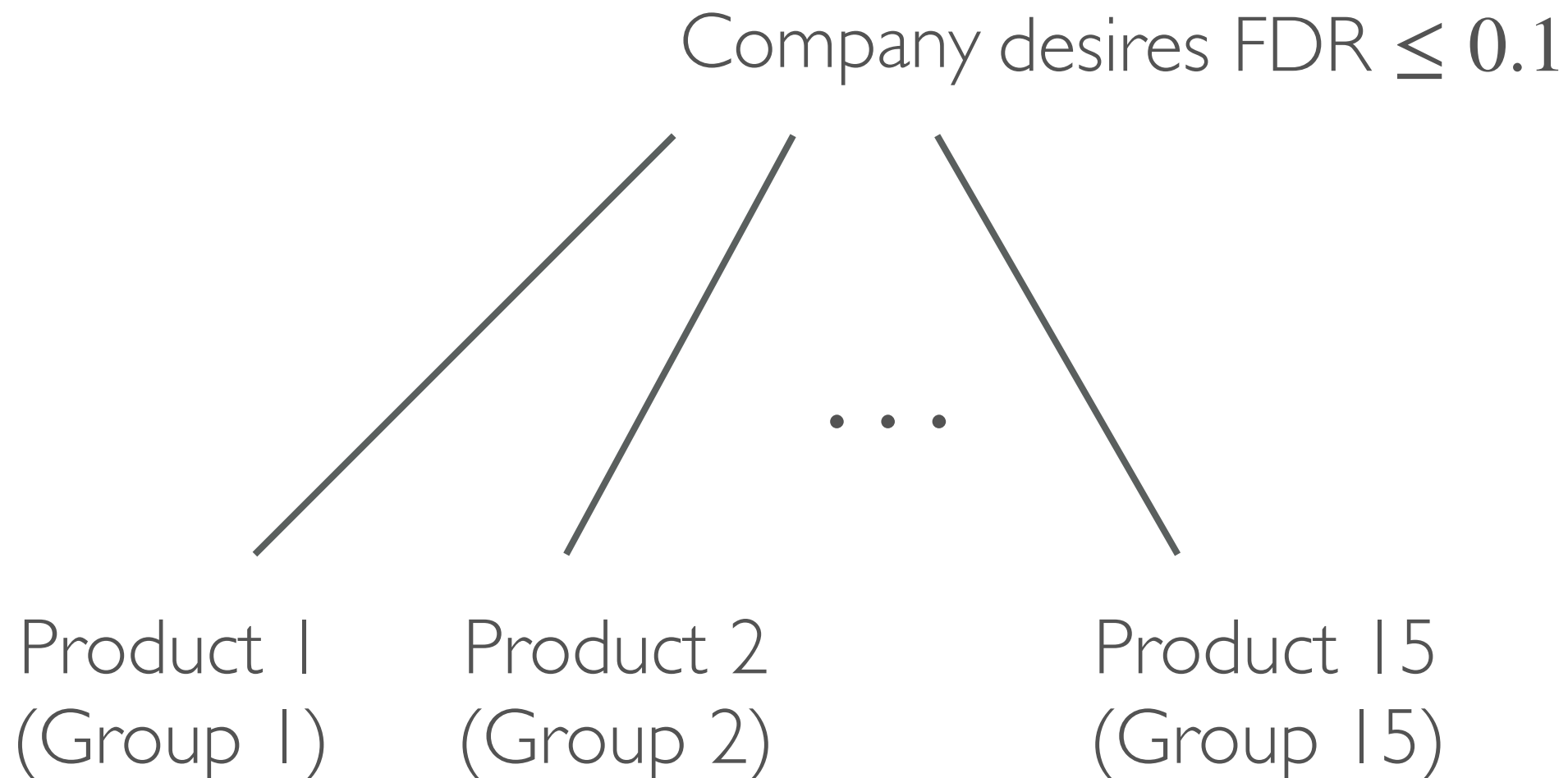
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But each individual group or team might feel “why do we have to pay if some other group is running lots of random tests/experiments”?

How do we align incentives?

Should our notion of error be hierarchical?

# I. A hierarchical FDR or FCR control?



The average of group FDRs does not give company FDR.

FDR is additive in the worst case: if each group separately controls FDR at 0.1, the company FDR could be trivial.

## 2. Utilizing contextual information

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Is such information useful for hypothesis testing?  
How do we use contextual bandits for hypothesis testing?

### 3. Designing systems that fail loudly

When our assumptions are wrong, and the system is not behaving like intended or expected, how can we *automatically* detect and report this?

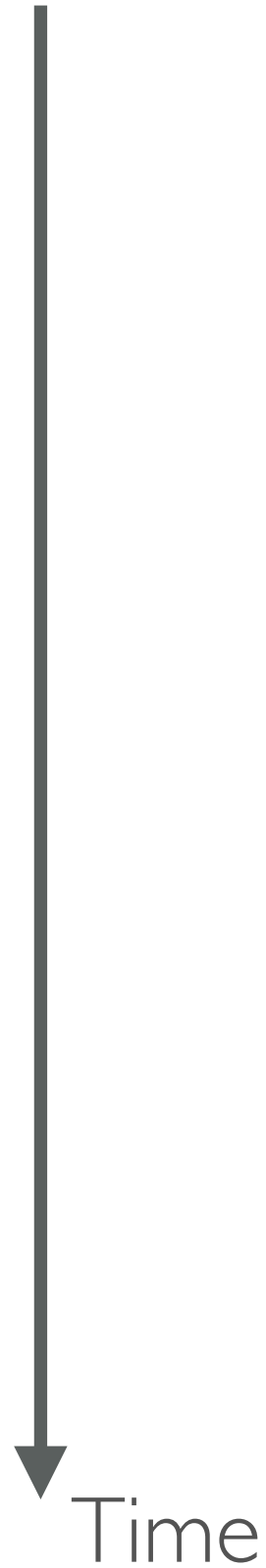
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Is it possible to design such self-critical systems that “announce” failures?

Summary [15 mins]

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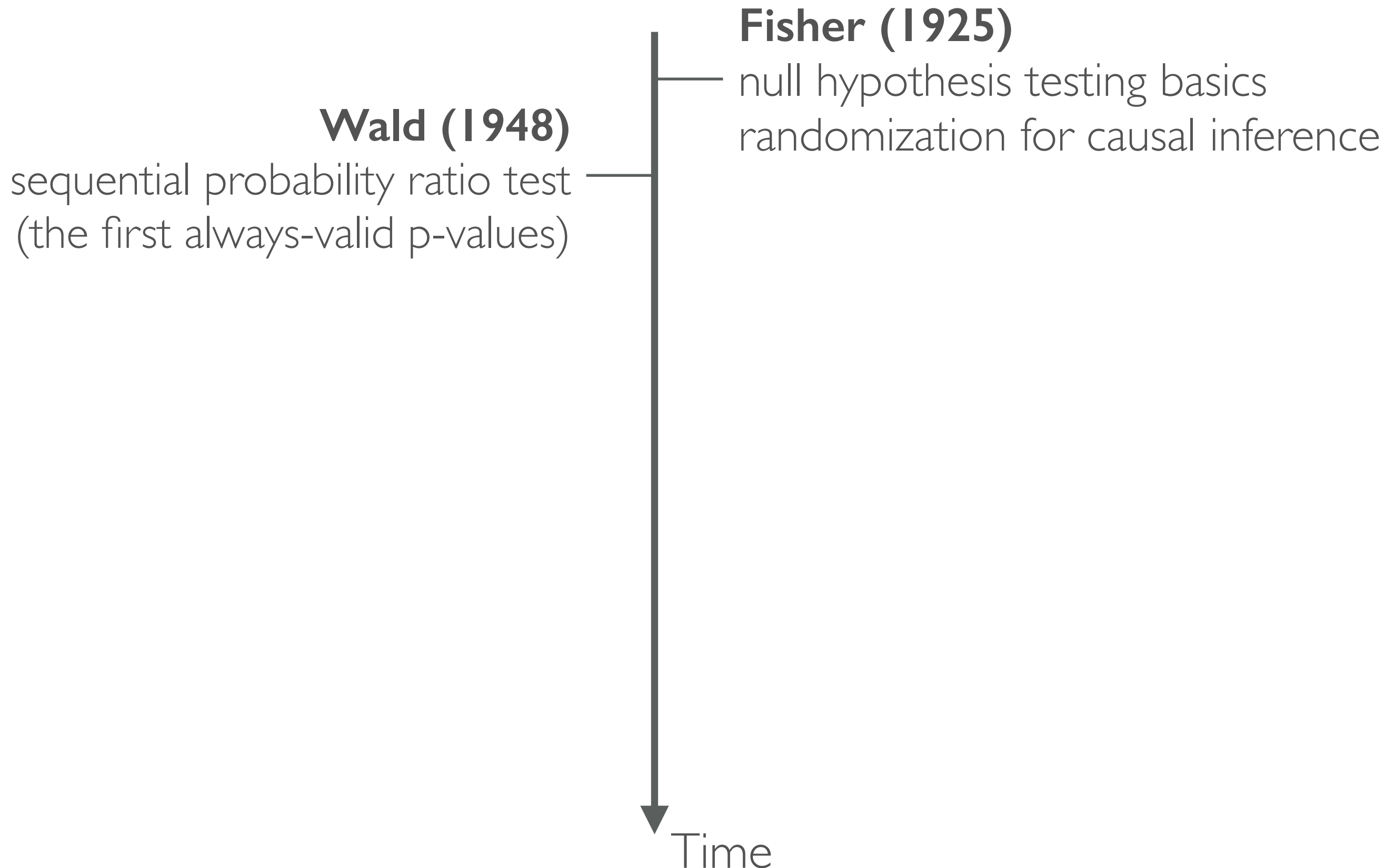
## **Fisher (1925)**

— null hypothesis testing basics  
randomization for causal inference

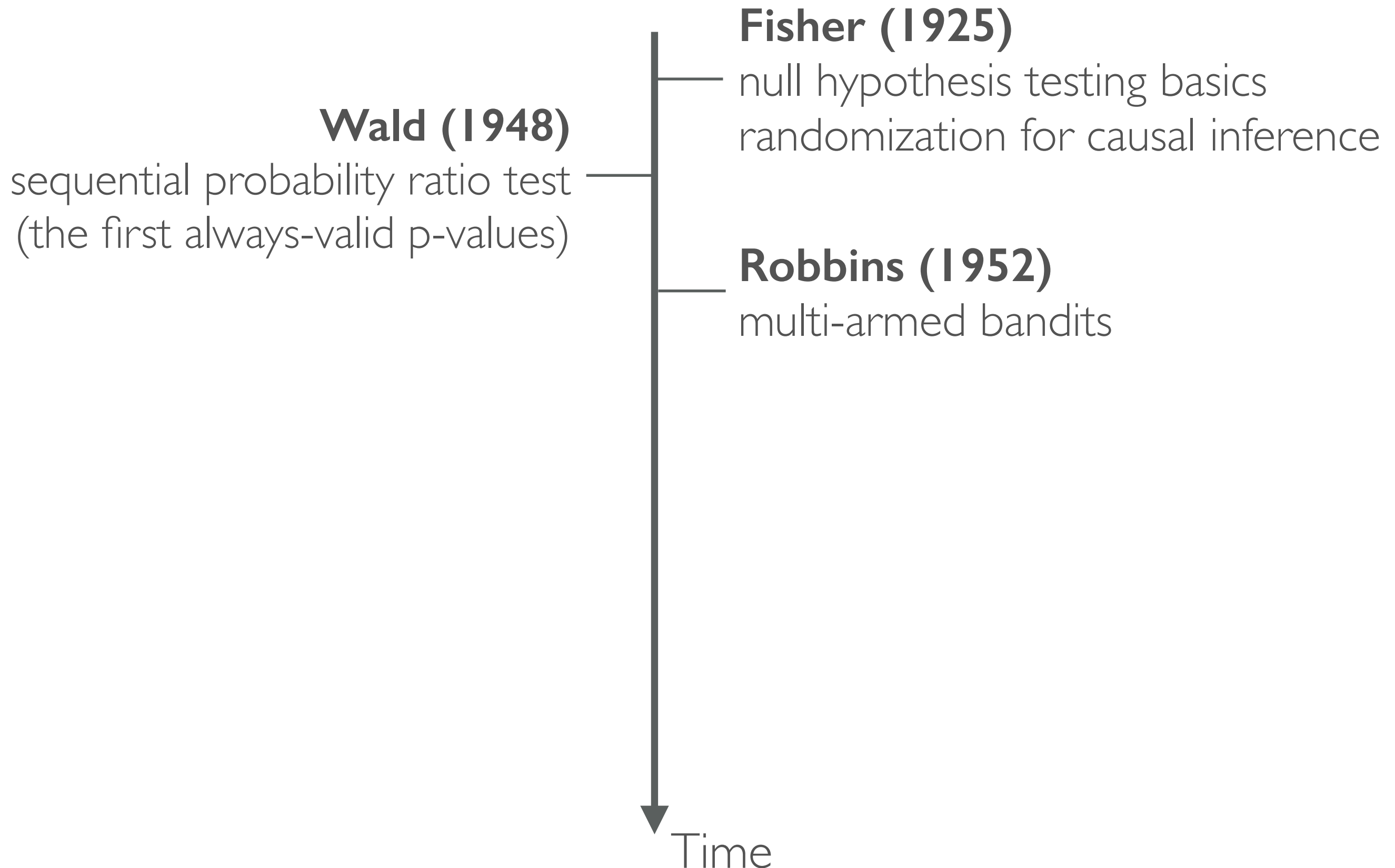


Time

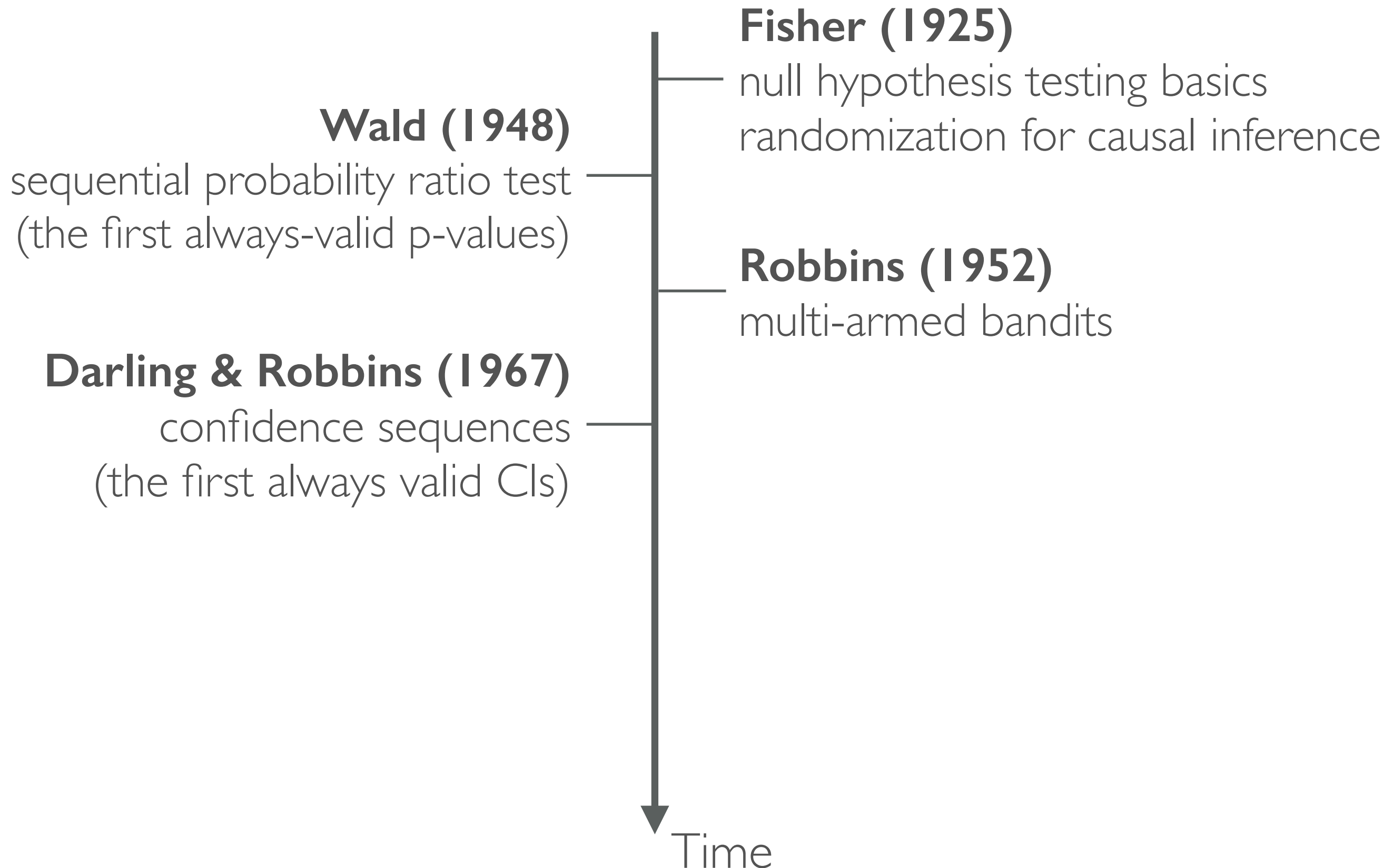
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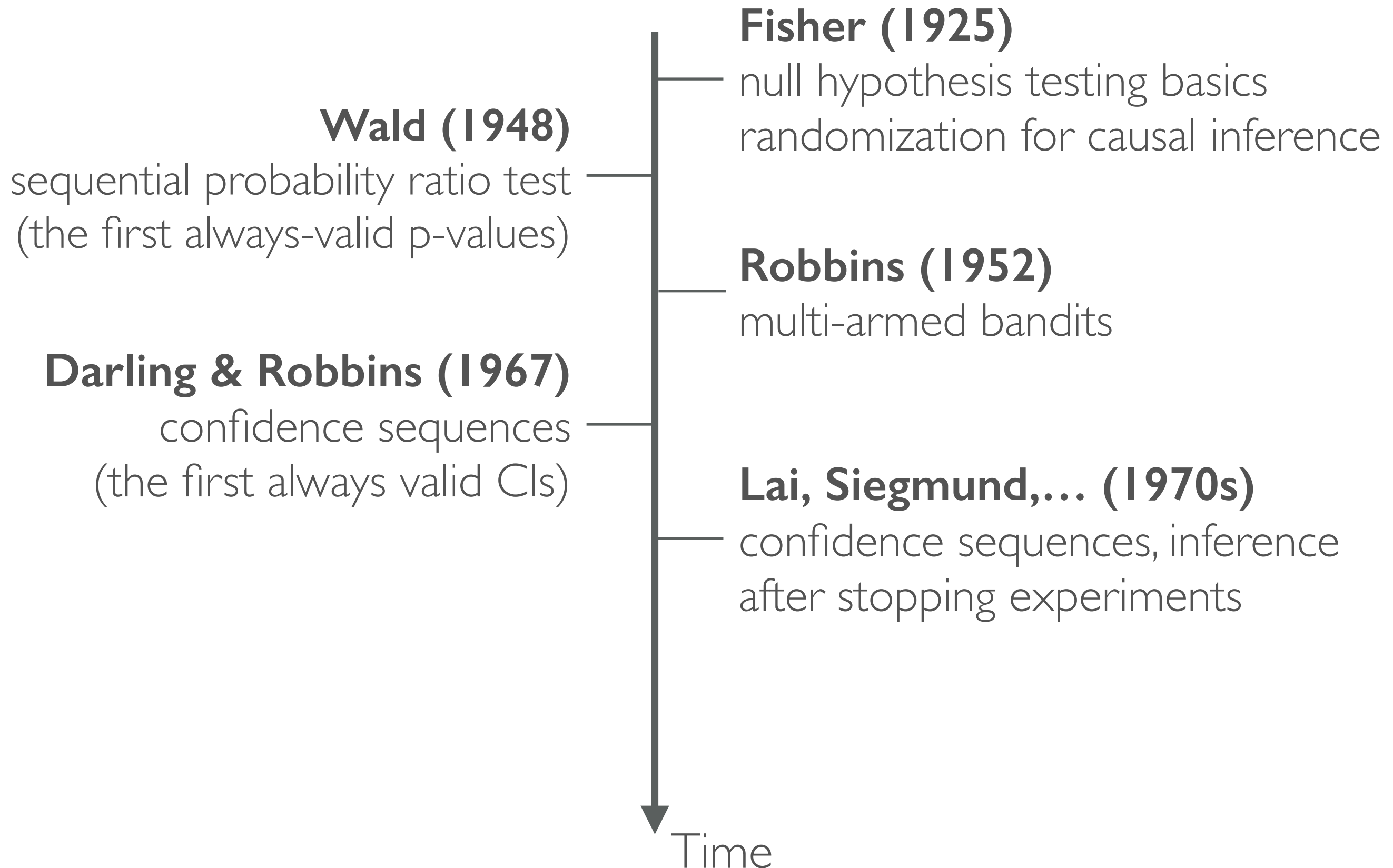
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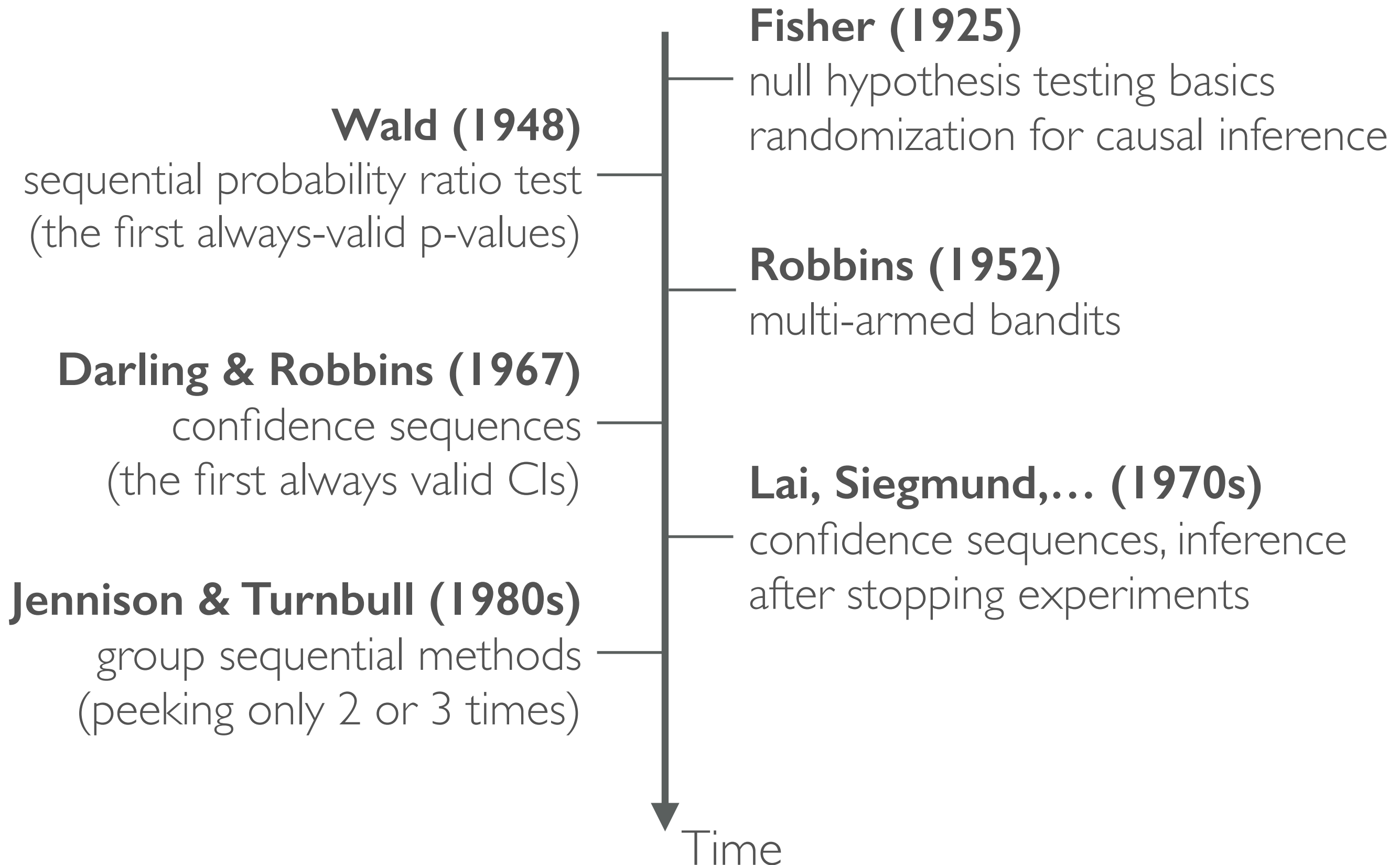
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# A selective history (outer process)



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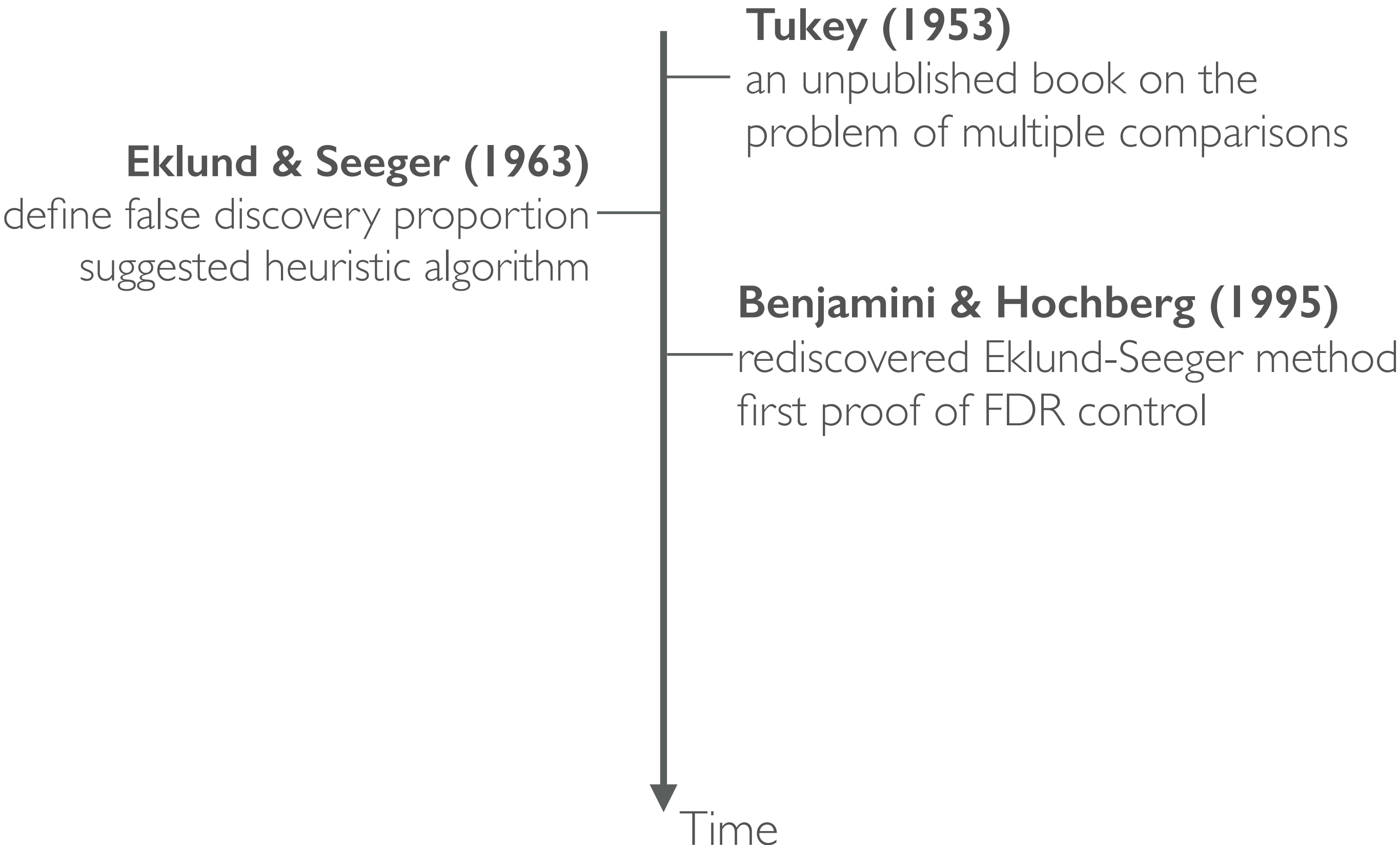
**Eklund & Seeger (1963)**

define false discovery proportion  
suggested heuristic algorithm

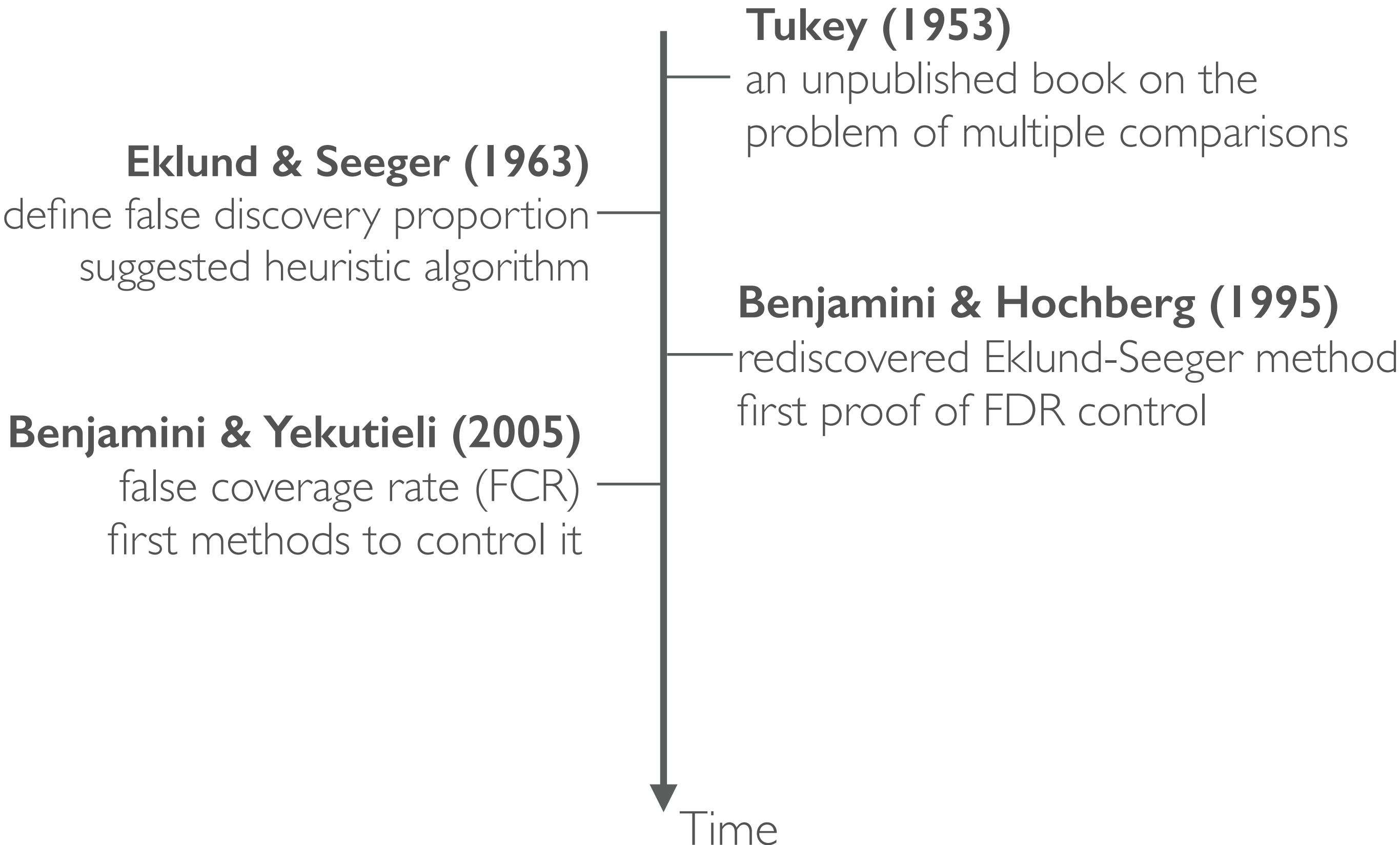


Time

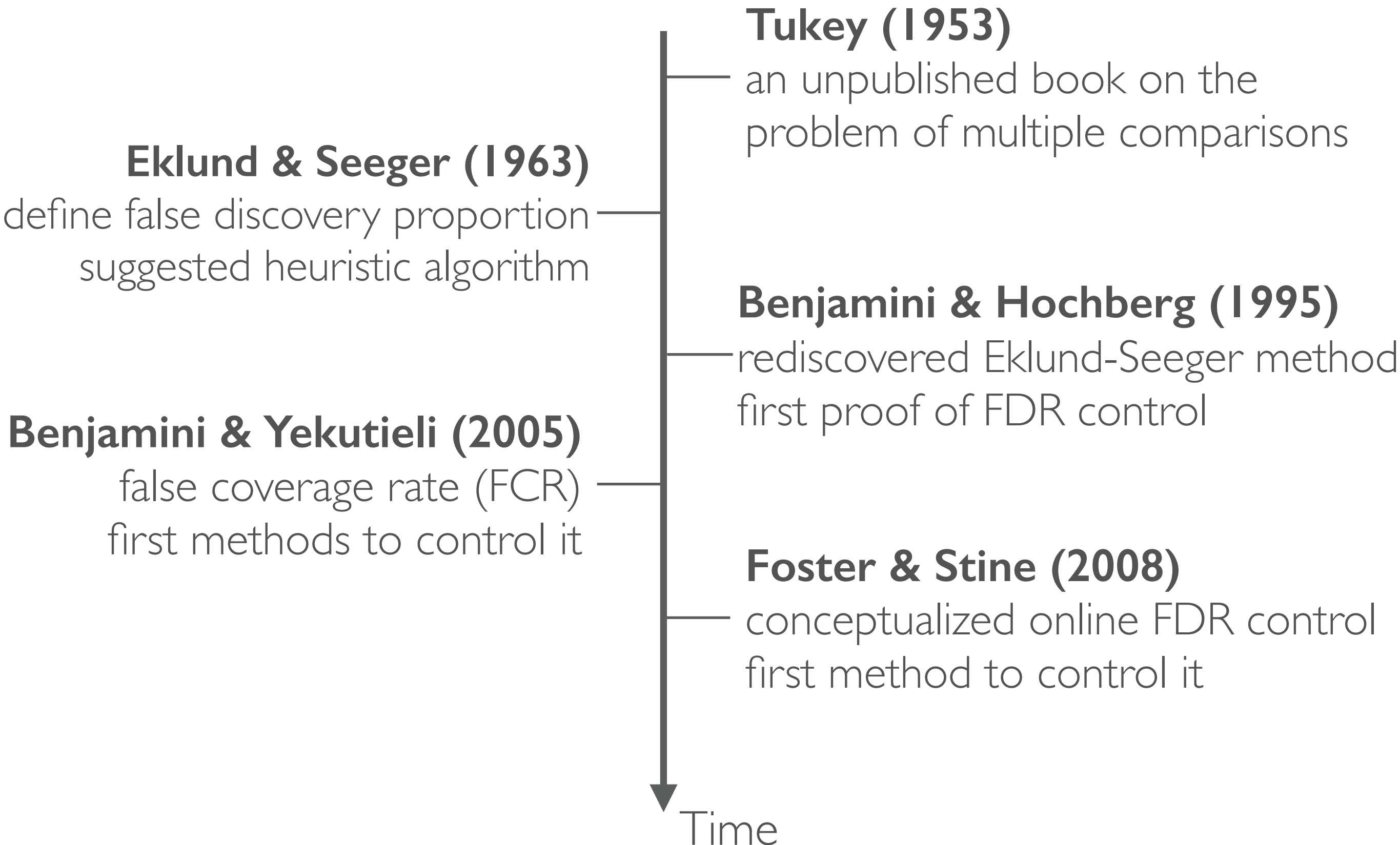
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- **How to think about doubly-sequential experimentation**
  - A. Using anytime CIs with online FCR control
  - B. Using anytime p-values with online FDR control
  - C. Handling asynchronous tests with local dependence



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- **Open problems:**
  - A. Incentives/errors within hierarchical organizations
  - B. Utilizing contextual information for testing
  - C. Designing systems that fail loudly

# SOFTWARE

- Within a single experiment:
  - Python package called “**confseq**”
  - Maintained by Steve Howard (Berkeley)
  - Frequent updates + wrappers for months to come
- Across experiments:
  - R package called “**onlineFDR**”
  - Maintained by David Robertson (Cambridge)
  - Frequent updates + wrappers for months to come

References and links at

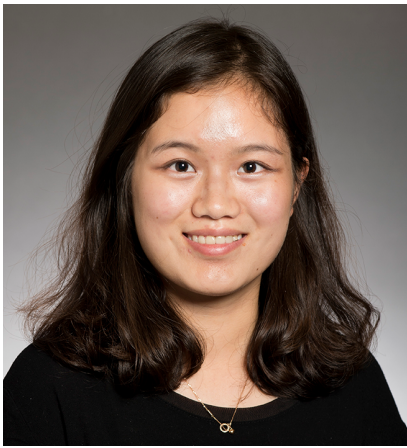
[www.stat.cmu.edu/~aramdas/kdd19/](http://www.stat.cmu.edu/~aramdas/kdd19/)



# Collaborators from this talk



Steve  
Howard



Jinjin  
Tian



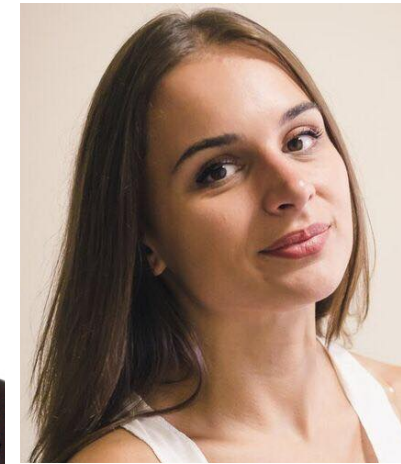
Asaf  
Weinstein



Eugene  
Katsevich



Akshay  
Balsubramani



Tijana  
Zrnic



David  
Robertson



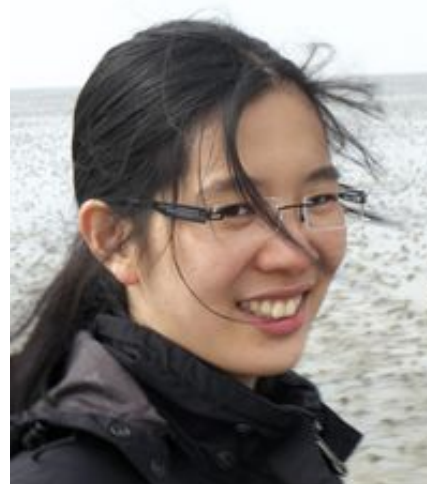
Jasjeet  
Sekhon



Jon  
McAuliffe



Kevin  
Jamieson



Fanny  
Yang



Martin  
Wainwright



Michael  
Jordan



# Foundations of large-scale “doubly-sequential” experimentation

(KDD tutorial in Anchorage, on 4 Aug 2019)



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**Funding welcomed!**

[www.stat.cmu.edu/~aramdas/kdd19/](http://www.stat.cmu.edu/~aramdas/kdd19/)

**Thank you! Questions?**