

Chaos, Complexity, and Inference (36-462)

Lecture 10: Cellular Automata

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Some things you can read:

Poundstone (1984) is what got me interested in the subject;
Toffoli and Margolus (1987) is the best introduction to CA modeling

code examples are for obsolete mid-1980s hardware

principles apply

Boccara (2004) has nice chapter on CAs

Chopard and Droz (1998); Ilachinski (2001): easier to read the more physics you know

Important paper collections: Burks (1970); Gutowitz (1991);
Griffeath and Moore (2003)

Cellular Automata

Completely discrete, spatially-extended dynamical systems

Time: discrete

Space: divided into discrete **cells**

Each cell is in one of a finite number of **states**, a.k.a. colors

Global **configuration**: the states of all cells at one time

Every cell has a **neighborhood**

includes cell itself

von Neumann neighborhood: cardinal directions (NSEW)

Moore neighborhood: diagonals too

possibly of range > 1

The dynamics

Local rule: Given the states of the neighborhood at time t , what is the state of the cell at $t + 1$?

simultaneous vs. random-order updating

Local rule implies a *global* rule for the configuration

Rules can be stochastic!

Globally, always have a Markov chain

Locally, have a **dynamic Markov random field**

Diffusion-Limited Aggregation

Particles appear at outer boundary, move in random walks

some trickery needed to get a random walk in a CA

Particles which hit the crystal freeze and become more crystal

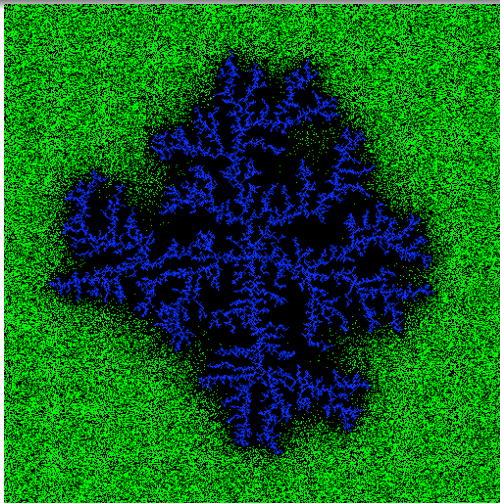
Models aggregation, freezing

Qualitative dynamics:

- smooth boundaries on crystal are unstable
protrusions capture more particles
 \therefore protrusions grow, become spikes
- spikes create their own flat boundaries
- spikes-on-spikes = branching trees, **dendritic growth**
Gets swamped if inflow of particles is fast enough



from Wikipedia



me, me, me!



Andy Goldsworthy

Lattice Gases

(Doolen, 1989, 1991; Rothman and Zaleski, 1997)

Models of fluid flow

Fluid consists of discrete particles moving with discrete velocities

State of each cell is number of particles with different velocities there (possibly none)

“atoms and void”

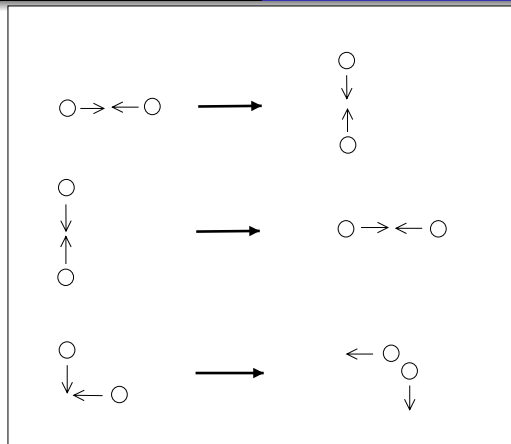
Collision rules implement basic physics

conservation of mass

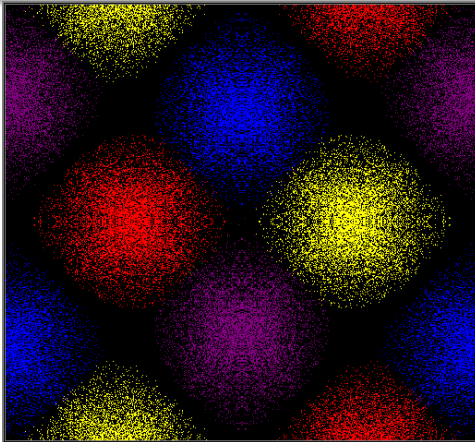
conservation of energy

conservation of momentum

Hydrodynamics emerges from local collisions, averaging over a large scale



Collision rules for “HPP” lattice gas (Hardy *et al.*, 1976), gets some hydrodynamics right but isn’t isotropic (rotationally symmetric) — need a non-rectangular lattice (Frisch *et al.*, 1986)



Diffusion in the HPP rule. Particles were initially clustered in tight blocks with random velocities. Particle color shows cluster of origin. The lattice wraps around at the boundaries. Source: <http://psoup.math.wisc.edu/archive/recipe61.html>

Majority Vote

“Majority vote”: change to match the majority of the neighborhood (including self)

Magnetism, strains of organisms, conventions, ...

Start from near-50-50 initial conditions

Quickly: solid-color regions form

More slowly: they unbend; “motion by mean curvature”

opposite of irregularity-amplifying DLA

Variants:

- higher or lower thresholds
- probability of flipping depending on proportion of neighbors
- copy a random neighbor (“voter model”)

Difference between finite-size behavior and infinite-size limit

Game of Life

2D, binary, Moore neighborhood

< 2 neighbors on: turn off

= 2 neighbors on: stay the same

= 3 neighbors on: turn on

> 3 neighbors on: turn off

some common life patterns: gliders, blinkers, beehives, ...

build a computer: use glider streams to represent bits, then

build logic gates

build a universal computer by attaching memory

Can build machines which construct new configurations according to plans

These can reproduce themselves and copy their plans:
mechanical (if mathematical) self-reproduction

This is actually the historical origin of cellular automata (von Neumann, 1966; Burks, 1970)

Poundstone (1984) is a wonderful account

Learning CA rules

Known neighborhood, deterministic rule: wait and see.

Known neighborhood, stochastic rule: counting (as with Markov chain)

Unknown neighborhood: search over neighborhoods to maximize mutual information between neighbors' states and new state (Richards *et al.*, 1990)

Huge number of neighborhoods, use fancy optimization techniques

Could also try: minimize conditional MI between new state and rest of configuration given neighborhood

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