

**Plan** Limit Theory (Countable-state case primarily)

1. Recurrence and Transience
2. Invariant Distributions
3. Limit Theorems

*Next Time: General-state analogues, Extended Example*

Reading: G&S 6.4, 6.5, 6.6

Homework 4 on-line tomorrow (sorry)

Homework solutions on-line up to date

**Review Theorem 1.** *The Chapman-Kolmogorov Equations.*

Let  $n, m \geq 0$ . For a transition probability matrix  $P$ , we have:

$$P^{n+m} = P^n \cdot P^m, \quad (\text{that is, } P^{n+m}(s, s') = \sum_{u \in \mathcal{S}} P^n(s, u) P^m(u, s')). \quad (1)$$

For general transition kernels:

$$P^{n+m}(s, A) = \int_{\mathcal{S}} P^n(s, du) P^m(u, A). \quad (2)$$

**Review Theorem 2.** If  $X$  is Markov chain on countable state space  $\mathcal{S}$ , then we can write

$$\mathcal{S} = D \cup \bigcup_i C_i, \quad (3)$$

where the sets are disjoint and each  $C_i$  is an absorbing, communicating class for the chain  $X$ .

**Review Proposition 3.** If  $C \subset \mathcal{S}$  is an absorbing, communicating class for a Markov chain  $X$ , then there exists an irreducible Markov Chain  $X^C$  with state-space  $C$  and whose transition probability kernel is given by  $P_C(x, A) \equiv P(x, A \cap C)$  for  $x \in C$ .

**Review Definition 4.** For any state  $s \in \mathcal{S}$ , define the *period* of  $s$  by

$$d(s) = \gcd\{n \geq 1 \text{ such that } P^n(s, s) > 0\}. \quad (4)$$

This implies that  $P^n(s, s) = 0$  unless  $n = md(s)$  for some  $m \in \mathbb{Z}_+$ . An irreducible Markov Chain is said to be *aperiodic* if  $d \equiv 1$ .

**Review Theorem 5.** Let  $X$  be an irreducible, countable-state Markov chain with common period  $d$ . Then, there are disjoint sets  $U_1, \dots, U_d \subset \mathcal{S}$  such that

$$\mathcal{S} = \bigcup_{k=1}^d U_k, \quad (5)$$

and

$$P(x, U_{k+1}) = 1 \quad \text{for } x \in U_k, \quad k = 0, \dots, d-1 \pmod{d}. \quad (6)$$

The sets  $U_1, \dots, U_d$  are called *cyclic classes* of  $X$  because  $X$  cycles through them successively.

**Useful Random Variables 6.** Let  $X$  be a general-state Markov chain with state space  $\mathcal{S}$ . Let  $A \subset \mathcal{S}$ . Define

$$T_A = \inf \{n \geq 1 \text{ such that } X_n \in A\} \quad (7)$$

$$S_A = \inf \{n \geq 0 \text{ such that } X_n \in A\} \quad (8)$$

$$O_A = \sum_{n=1}^{\infty} 1\{X_n \in A\}. \quad (9)$$

These are called, respectively, the *first return time*, the *first hitting time*, and the *occupation time* of  $A$ . If  $X_n$  never returns to or hits  $A$ , we take  $T_A = \infty$  and  $S_A = \infty$  respectively. As we will see, these random variables provide a great deal of information about the behavior of the chain.

For  $A, B \subset \mathcal{S}$  and  $s \in \mathcal{S}$ , define

$$R(s, A) = \mathbb{P}_s\{T_A < \infty\} \quad (10)$$

$$M(s, A) = \mathbb{E}_s T_A \quad (11)$$

$$H(s, A) = \mathbb{P}_s\{S_A < \infty\} \quad (12)$$

$$O(s, A) = \mathbb{E}_s O_A \quad (13)$$

$$P_A^n(s, B) = \mathbb{P}_s\{X_n \in B, T_A \geq n\}. \quad (14)$$

These are the return time probabilities, hitting probabilities, expected occupation times for the set  $A$  and taboo probabilities for the set  $B$  avoiding  $A$ , when the chain starts in state  $s$ .

Note that

$$O(s, A) = \sum_{n=1}^{\infty} P_A^n(s, A) \quad (15)$$

$$R(s, A) = \sum_{n=1}^{\infty} P_A^n(s, A). \quad (16)$$

**Definition 7.** The random variables  $T_A$  and  $S_A$  in the last item are stopping times, meaning that  $\{T = n\} \in \sigma(X_0, \dots, X_n)$  for every  $n$ .

Let  $\mathcal{F}_n = \sigma(X_0, \dots, X_n)$  be the history of the chain up to time  $n$ . For a stopping time  $T$ , we can define the information in the chain up to time  $T$  – the history up to time  $T$  – as a  $\sigma$ -field  $\mathcal{F}_T$  defined as follows:

$$\mathcal{F}_T = \{A \in \mathcal{F} \text{ such that } A \cap \{T = n\} \in \mathcal{F}_n, \text{ for all } n \in \mathbb{Z}_{\oplus}\}. \quad (17)$$

**Theorem 8.** *The Strong Markov Property*

For any (discrete-time) Markov chain  $X$  and a bounded, measurable function  $h$  on sample paths,

$$\mathbb{E}(h(X_{T+1}, X_{T+2}, \dots) \mid \mathcal{F}_T) 1\{T < \infty\} = \mathbb{E}_{X_T}(h(X_1, X_2, \dots)) 1\{T < \infty\}, \quad (18)$$

where  $\mathbb{E}_{X_T}$  corresponds to a chain whose initial distribution on  $\mathcal{S}$  is the distribution of  $X_T$ . This is called the *Strong Markov Property*.

**Definition 9.** A set  $A \subset \mathcal{S}$  is called *uniformly transient* if there exists  $M < \infty$  such that  $O(s, A) \leq M$  for all  $s \in A$ .  $A$  is called *transient* if  $O(s, A) < \infty$  for all  $s \in A$ .  $A$  is called *recurrent* if  $O(s, A) = \infty$  for all  $s \in A$ .

In particular, for a state  $s \in \mathcal{S}$  of a *countable-state Markov chain*, we say that  $s$  is uniformly transient/transient/recurrent if  $\{s\}$  is.

**Theorem 10.** For an irreducible, countable-state Markov chain  $X$ , either  $O(s, s') < \infty$  for all  $s, s' \in \mathcal{S}$ , in which case we say that  $X$  is recurrent, or  $O(s, s') = \infty$  for all  $s, s' \in \mathcal{S}$  in which case we say that  $X$  is transient.

Proof. Then since for any  $u, v$ ,  $u \rightarrow s$  and  $s' \rightarrow v$ , we can find an  $\ell, m$  such that  $P^\ell(u, s) > 0$  and  $P^m(s', v) > 0$ . Hence,

$$\sum_n P^{\ell+m+n}(u, v) > P^\ell(u, s) \left[ \sum_n P^n(s, s') \right] P^m(s', v). \quad (19)$$

It follows that  $O(s, s') = \sum_{n=1}^{\infty} P^n(s, s') = \infty$  implies  $O(u, v) = \infty$  and  $O(u, v) < \infty$  implies  $O(s, s') < \infty$ . But both pairs of states were arbitrary, so the theorem is proved.

**Theorem 11.** Suppose  $X$  is a countable-state Markov chain on  $\mathcal{S}$ . For any  $s \in \mathcal{S}$ ,  $O(s, s) \equiv O(s, \{s\}) = \infty$  if and only if  $R(s, s) \equiv R(s, \{s\}) = 1$ .

Hence, if  $X$  is irreducible, either  $R(s, s') = 1$  for all  $s, s' \in \mathcal{S}$  or  $R(s, s) < 1$  for all  $s \in \mathcal{S}$ .

To prove this theorem, we'll use the same trick we used earlier in considering the return times of random walks. Notice that for any  $s \in \mathcal{S}$  and any  $n \geq 1$ ,

$$P^n(s, s) = \sum_{k=1}^n \mathbb{P}_s\{T_{\{s\}} = k\} P^{n-k}(s, s) = \sum_{k=0}^n \mathbb{P}_s\{T_{\{s\}} = k\} P^{n-k}(s, s), \quad (20)$$

where the latter follows because  $\mathbb{P}_s\{T_{\{s\}} = 0\} = 0$ .

Let  $G_s(z) = \sum_n P^n(s, s)z^n$  and  $R_s(z) = \sum_n \mathbb{P}_s\{T_{\{s\}} = n\} z^n$ . Then, we get

$$G_s(z) = 1 + G_s(z)R_s(z) \implies G_s(z) = \frac{1}{1 - R_s(z)}. \quad (21)$$

Because  $R_s(1) = \mathbb{P}_s\{T_{\{s\}} < \infty\}$  (or letting  $z \rightarrow 1$  to be careful about convergence), we get that

$$R(s, s) = 1 \iff O(s, s) = \infty. \quad (22)$$

By Theorem 10 and equation (22), we have either  $R(s, s) < 1$  for all  $s$  or  $R(s, s) = 1$  for all  $s$ . If the latter is true and  $R(s, s') < 1$ , then by irreducibility, we have  $O(s', s) > 0$  and thus, for some  $n$ ,  $P^n_{[s']}(s', s) > 0$ . This implies  $R(s', s') < 1$ , and the result follows by contradiction.

## Examples 12.

1. Random Walk
2. Bounded Random Walk
3. Binomial Runs
4. Renewal Process and Forward Recurrence Time Chain

**Definition 13.** For  $s \in \mathcal{S}$ , recall  $M(s, A) = \mathbb{E}_s T_A$ . For  $A = \{s\}$ ,  $M(s, A) \equiv M(s, s)$ . These are the expected return times to the set  $A$  and the state  $s$ .

**Definition 14.** Let  $X$  be a countable-state Markov chain on  $\mathcal{S}$ . If  $s \in \mathcal{S}$  is a recurrent state, we call it *positive recurrent* if  $M(s, s) < \infty$  and *null recurrent* if  $M(s, s) = \infty$ .

**Definition 15.** Let  $X$  be a countable-state Markov chain on  $\mathcal{S}$  with transition probabilities  $P$ . A ( $\sigma$ -finite) measure  $\pi$  is an invariant measure for the chain if  $\pi(s) \geq 0$  and

$$\pi(s') = \sum_s \pi(s) P(s, s'), \quad (23)$$

or in matrix terms

$$\boldsymbol{\pi} = \boldsymbol{\pi} \cdot P, \quad (24)$$

where we think of  $\boldsymbol{\pi}$  as a “row vector”.

An invariant measure  $\pi$  is an *invariant* or *stationary distribution*, if in addition it is a probability mass function on  $\mathcal{S}$ .

**Motivation 16.** The names “invariant” and “stationary” come from the above properties. The first stems from the fact that  $\pi$  does not change – is invariant – under the transition mechanism of the chain. The second comes from the fact that if the chain is started with initial distribution  $\pi$ , then the distribution of  $X_n$  is given by  $\pi \cdot P^n = \pi$ . That is, the distribution of  $X_n$  does not change with  $n$ .

**Definition 17.** If  $X$  is an irreducible, recurrent, countable-state Markov chain on  $\mathcal{S}$  and there exists a stationary distribution on  $\mathcal{S}$ , then  $X$  is said to be a positive recurrent. Otherwise,  $X$  is said to be null recurrent. Then, every state is, respectively, positive or null recurrent.

**Theorem 18.** If  $X$  is an irreducible, recurrent, countable-state Markov chain, then there exists an invariant *measure*  $\rho$  that is positive and unique up to constant multiples. The chain is positive recurrent if  $\sum_s \rho(s) < \infty$  and null recurrent if  $\sum_s \rho(s) = \infty$ .

**Theorem 19.** If an irreducible, countable-state Markov chain has a stationary distribution  $\pi$ , then it is unique and  $\pi_s = 1/M(s, s)$ .

**Remarks 20.** 1. Note that if  $X$  admits a stationary distribution but is transient then  $P^n(s, s') \rightarrow 0$  as  $n \rightarrow \infty$ , so

$$\pi_{s'} = \sum_s \pi_s P(s, s') \leq \sum_{s \in S_0} \pi_s P(s, s') + \sum_{s \notin S_0} \pi_s \quad (25)$$

$$\rightarrow \sum_{s \notin S_0} \pi_s \rightarrow 0, \quad (26)$$

for any finite  $S_0 \subset \mathcal{S}$  with the last limit being as  $S_0 \uparrow \mathcal{S}$ . This is a contradiction, so  $X$  must be recurrent.

2. See the proofs in G&S section 6.4.

To translate, define  $q(s, s') = \sum_n P_{!s}^n(s, s')$  for the taboo probabilities  $P_{!s}^n(s, s')$ . Notice that  $M(s, s) = \sum_{s'} q(s, s')$ . G&S use  $\rho_{s'}(s) \equiv q(s, s')$  and  $f_{s, s'}(n) \equiv \mathbb{P}_s\{T_{s'} = n\}$ .

**Examples 21.**

- Doubly Stochastic, Finite Random Walk
- Canonical Random Walk
- Embedded MC for G/M/1 Queue