

# Convex Optimization

## CMU-10725

### Penalty Methods

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**MACHINE LEARNING** DEPARTMENT



# Outline

- Penalty functions

# Books to Read

**David G. Luenberger, Yinyu Ye:** Linear and Nonlinear Programming

**Boyd and Vandenberghe:** Convex Optimization

# Penalty Methods

# Penalty Methods

$$\min_{x \in \mathcal{S}} f(x), \quad (P)$$

where  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is continuous, and  $\mathcal{S}$  is a constraint set in  $\mathbb{R}^n$

**Penalty program:** replace (P) with the unconstrained problem:

$$\min f(x) + cp(x)$$

where  $c > 0$

**Penalty**  $p : \mathbb{R}^n \rightarrow \mathbb{R}$ :

- (i)  $p$  is continuous,
- (ii)  $p(x) \geq 0$  for all  $x \in \mathbb{R}^n$ ,
- (iii)  $p(x) = 0$  if and only if  $x \in \mathcal{S}$

**Penalty term:** high cost for violation of the constraints

# Inequality Constraints

$$\min_{x \in \mathcal{S}} f(x) \quad \mathcal{S} = \{x : g_i(x) \leq 0, i = 1, 2, \dots, p\}$$

A useful penalty function in this case is:

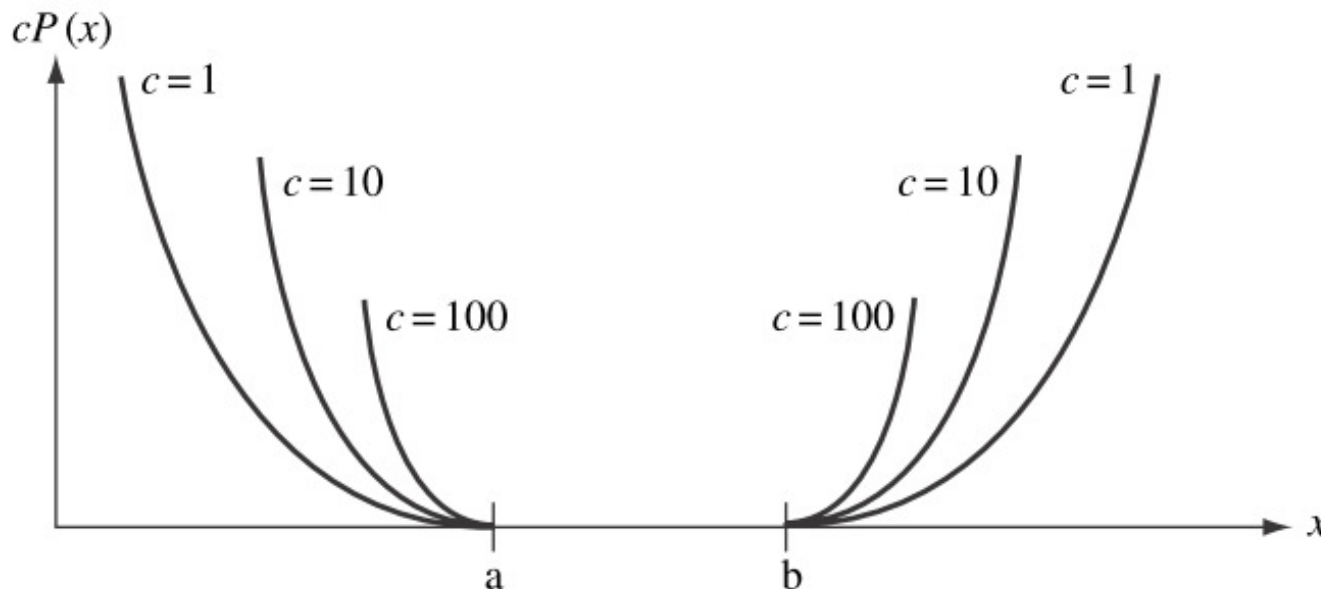
$$P(x) = \frac{1}{2} \sum_{i=1}^p (\max[0, g_i(x)])^2 \quad [\text{No penalty, iff } g(x) \leq 0]$$

**Example:**  $g_1(x) = x - b$ ,  $g_2(x) = x - a$

$$a \leq x, x \leq b$$

# Penalty Methods

**Penalty program:**  $\min f(x) + cp(x) \quad (P(c))$



For large  $c$  the minimum point of problem  $(P(c))$  is in a region where penalty  $p$  is small.

**We will prove:** as  $c \rightarrow \infty$  the solution point of the penalty problem will converge to a solution of the constrained problem  $(P)$ .

# Inequality and Equality Constraints

**Inequality and Equality constraints:**

$$\begin{array}{ll} \min_x & f(x) \\ \text{SUBJECT TO} & g_i(x) \leq 0 \quad i = 1 \dots m \\ & h_j(x) = 0 \quad j = 1 \dots k \end{array}$$

Rewrite them as:

$$\begin{array}{l} h_j(x) \leq 0 \\ -h_j(x) \leq 0 \end{array}$$



# Penalty Method

**Penalty parameter:**

$$\text{LET } 0 < C_1 < C_2 < \dots < C_k < C_{k+1} < \dots \rightarrow \infty$$

**Penalty program:**

$$q(C, x) \doteq f(x) + C p(x)$$

$$x_k = \underset{x \in \mathbb{R}^n}{\text{ARG MIN}} q(C_k, x) = \underset{x \in \mathbb{R}^n}{\text{ARG MIN}} f(x) + C_k p(x)$$

**Penalty Lemma:**

- ①  $q(C_k, x_k) \leq q(C_{k+1}, x_{k+1})$
- ②  $p(x_k) \geq p(x_{k+1})$
- ③  $f(x_k) \leq f(x_{k+1})$
- ④  $f(x^*) \geq q(C_k, x_k) \geq f(x_k)$

# Proof of Penalty Lemma (1)

① PROVE  $q(C_k, X_k) \leq q(C_{k+1}, X_{k+1})$

PROOF:

$$q(C_{k+1}, X_{k+1}) = f(X_{k+1}) + C_{k+1} P(X_{k+1}) \geq f(X_{k+1}) + C_k P(X_{k+1})$$

$\nearrow$   
 $C_{k+1} \geq C_k$

$$\geq f(X_k) + C_k P(X_k) = q(C_k, X_k)$$

$\uparrow$

$X_k$  IS OPTIMAL WITH  $C_k$



# Proof of Penalty Lemma (2)

② PROVE  $P(x_k) \geq P(x_{k+1})$

PROOF:

$$f(x_k) + c_k P(x_k) \leq f(x_{k+1}) + c_k P(x_{k+1}) \quad (*)_1$$

$\uparrow$   $x_k$  IS OPTIMAL WITH  $c_k$

$$f(x_{k+1}) + c_{k+1} P(x_{k+1}) \leq f(x_k) + c_{k+1} P(x_k) \quad (*)_2$$

$\uparrow$   $x_{k+1}$  IS OPTIMAL WITH  $c_{k+1}$

$(*)_1 + (*)_2 \Rightarrow$

$$c_k P(x_k) + c_{k+1} P(x_{k+1}) \leq c_k P(x_{k+1}) + c_{k+1} P(x_k)$$

$$\Rightarrow \underbrace{(c_{k+1} - c_k)}_0 P(x_{k+1}) \leq \underbrace{(c_{k+1} - c_k)}_0 P(x_k)$$

$$\Rightarrow P(x_{k+1}) \leq P(x_k) \quad \square$$

# Proof of Penalty Lemma (3)

PROVE  $f(x_k) \leq f(x_{k+1})$

PROOF:

$$f(x_{k+1}) + C_k P(x_{k+1}) \geq f(x_k) + C_k P(x_k)$$

↑  
 $x_k$  IS OPTIMAL WITH  $C_k$

$$\geq f(x_k) + C_k P(x_{k+1})$$

↑  
 $P(x_k) \geq P(x_{k+1})$

$$\Rightarrow f(x_{k+1}) \geq f(x_k) \quad \square$$

# Proof of Penalty Lemma (4)

LET  $x^* = \underset{x \in S}{\text{ARGMIN}} f(x)$

PROVE THAT

ALREADY PROVED IN LEMMA (1)

$$f(x^*) \geq \gamma(c_{k+1}, x_{k+1}) \geq \gamma(c_k, x_k) \geq f(x_k) \quad \forall k$$

WHERE  $\gamma(c, x) = f(x) + c p(x)$

$$x_{k+1} = \underset{x}{\text{ARGMIN}} f(x) + c_k p(x)$$

PROOF

$$f(x^*) = f(x^*) + c_k \underbrace{p(x^*)}_{=0 \text{ SINCE } x^* \in S} \geq \underbrace{\gamma(c_k, x_k)}_{\substack{f(x_k) + c_k p(x_k) \\ \downarrow \quad \downarrow \\ x_k \text{ IS OPTIMAL} \\ \text{WITH } c_k}} \geq f(x_k)$$



# Convergence of Penalty Method

**Theorem:** [Penalty convergence]

- SUPPOSE  $f, g, p$  ARE CONTINUOUS FUNCTIONS
- $x_k = \underset{x \in \mathbb{R}^n}{\text{ARG MIN}} f(x) + c_k p(x) \leftarrow$  PENALTY FUNCTION
- $0 < c_1 < c_2 < \dots < c_k < c_{k+1} < \dots \rightarrow \infty$
- $\bar{x}$  IS AN ARBITRARY LIMIT POINT OF  $\{x_k\}_{k=1}^{\infty}$

$\Rightarrow \bar{x}$  SOLVES (P)

$$(P) \begin{cases} \underset{x}{\text{MIN}} & f(x) \\ \text{s.t.} & g(x) \leq 0 \end{cases}$$

# Proof of Penalty Convergence

LIMIT POINT:  $\lim_{k \in \mathcal{K}} x_k = \bar{x} \quad [x_k \rightarrow \bar{x}]$

SINCE  $f$  IS CONTINUOUS  $\lim_{k \in \mathcal{K}} f(x_k) = f(\bar{x})$

$q^* \equiv \lim_{k \in \mathcal{K}} \underbrace{q(c_k, x_k)}_{f(x_k) + c_k p(x_k)} \leq f(x^*) \doteq f^* \quad x^*: \text{SOLUTION OF } (P)$   
 $\nwarrow$  LEMMA (4)

$\Rightarrow q^* = \lim_{k \in \mathcal{K}} f(x_k) + \lim_{k \in \mathcal{K}} c_k p(x_k) \leq f(x^*) \Rightarrow f(\bar{x}) \leq f(x^*)$

$\Rightarrow q^* - f(\bar{x}) = \lim_{k \in \mathcal{K}} c_k p(x_k) \stackrel{!}{=} 0 \Rightarrow \lim_{k \in \mathcal{K}} p(x_k) = 0$   
 $\downarrow$   $\downarrow$   $\downarrow$   
 $p$  IS CONTINUOUS  $\Rightarrow p(\lim_{k \in \mathcal{K}} x_k) = p(\bar{x}) = 0$

$\Rightarrow \bar{x} \in S$  [FEASIBLE]  $\left[ \begin{array}{l} f(\bar{x}) \leq f(x^*) \\ \bar{x} \in S \end{array} \Rightarrow f(\bar{x}) = f(x^*) \right] \quad \square$

# Penalty functions

## Often used penalty functions

Polynomial penalty:  $p(x) = \sum_{i=1}^m [\text{MAX}\{0, g_i(x)\}]^q \quad q \geq 1$

Linear penalty:  $q=1$  :  $p(x) = \sum_{i=1}^m \text{MAX}\{0, g_i(x)\}$

Quadratic penalty:  $q=2$  :  $p(x) = \sum_{i=1}^m [\text{MAX}\{0, g_i(x)\}]^2$

$$g_i^+(x) = \text{MAX}\{0, g_i(x)\}$$
$$g^+(x) = [g_1^+(x), \dots, g_m^+(x)]^T$$

$$p(x) = g^+(x)^T g^+(x) \quad \text{OR} \quad p(x) = g^+(x)^T \Gamma g^+(x)$$

where  $\Gamma > 0$



# Inequality and Equality constraints

## Problem (P)

$$\begin{aligned} P : \min_x f(x) \\ \text{s.t.} \quad & g(x) \leq 0 \\ & h(x) = 0 \\ & x \in \mathbb{R}^n \end{aligned}$$

## Definition [Penalty function]

$$\begin{aligned} P(x) &= 0 && \text{IF } g(x) \leq 0 \text{ AND } h(x) = 0 \\ P(x) &> 0 && \text{IF } g(x) > 0 \text{ OR } h(x) \neq 0 \end{aligned}$$

## Example [Penalty function]

$$P(x) = \sum_{i=1}^m [\max\{0, g_i(x)\}]^q + \sum_{i=1}^k |h_i(x)|^q \quad q \geq 1$$

# Derivative of the penalty function

**Penalty program:**  $x_h = \underset{x \in \mathbb{R}^n}{\text{ARGMIN}} f(x) + C_h P(x)$

**Penalty function:**  $g_i^+(x) = \max\{0, g_i(x)\}$   
 $g^+(x) = [g_1^+(x), \dots, g_m^+(x)]^T$   
 $P(x) = \gamma(g^+(x))$  WHERE  $\gamma: \mathbb{R}^m \rightarrow \mathbb{R}_+$   
 FOR EXAMPLE  $\gamma(y) = y^T y$

**Assumptions:**  $f \in C^1$  OBJECTIVE  
 $g \in C^1$  CONSTRAINTS  
 $P(\cdot) = \gamma(g^+(\cdot)) \in C^1$  PENALTY FUNCTION

**Derivatives:**  $\frac{\partial P(x)}{\partial x} = ?$   $g^+$  IS NOT DIFFERENTIABLE!

# Derivative of the penalty function

**Difficulties:** max is not differentiable

$$\frac{\partial p(x)}{\partial x} = \sum_{i=1}^m \frac{\partial \sigma(g_i^+(x))}{\partial g_i} \quad \frac{\partial g_i^+(x)}{\partial x}$$

$$\nabla g_i^+(x) = \frac{\partial g_i^+(x)}{\partial x} = \frac{\partial \max[0, g_i(x)]}{\partial x} = \begin{cases} \frac{\partial g_i(x)}{\partial x} & \text{if } g_i(x) > 0 \\ 0 & \text{if } g_i(x) < 0 \end{cases}$$

This is not perfectly correct, because  $\nabla g_i^+$  is NOT CONTINUOUS WHERE  $g_i(x) = 0$ !

**Solution:** IF  $g_i = 0 \Rightarrow \frac{\partial \sigma(0)}{\partial g_i} = 0$  THEN  $p(x)$  IS STILL DIFFERENTIABLE

**Example:**  $p(x) = \sum_{i=1}^m [g_i^+(x)]^q$   $q > 1$

$$\frac{\partial p(x)}{\partial x} = \sum_{i=1}^m q [g_i^+(x)]^{q-1} \frac{\partial g_i^+(x)}{\partial x}$$


# KKT in Penalty methods

**Penalty program:**  $x_2 = \underset{x \in \mathbb{R}^n}{\text{ARGMIN}} f(x) + C_2 P(x)$

**Penalty function:**  $P(x) = \sigma(g^+(x))$

**Derivatives:**  $\nabla P(x) = \sum_{i=1}^m \frac{\partial \sigma(g^+(x))}{\partial y_i} \nabla g_i^+(x) = \sum_{i=1}^m \frac{\partial \sigma(g^+(x))}{\partial y_i} \nabla g_i(x)$   
 NO NEED FOR  $\nabla g_i^+(x)$

**1<sup>st</sup> order condition in local minimum:**

$$\begin{aligned} 0 &= \nabla f(x_2) + C_2 \nabla P(x_2) \\ &= \nabla f(x_2) + C_2 \sum_{i=1}^m \underbrace{\frac{\partial \sigma(g^+(x_2))}{\partial y_i}}_{u_i^2 / C_2} \nabla g_i(x_2) \end{aligned}$$

$$= \nabla f(x_2) + u_i^2 \nabla g_i(x_2) = 0$$

← BEHAVES LIKE LAGRANGE MULTIPLIERS IN KKT!

# KKT and Penalty method multipliers

**Problem (P)**

$$p: \min_x f(x) \quad \text{s.t.} \quad g(x) \leq 0$$

**Penalty program:**

$$x_k = \underset{x \in \mathbb{R}^n}{\text{ARGMIN}} f(x) + C_k P(x)$$

$$u_k^i = C_k \frac{\partial T(g^+(x_k))}{\partial y_i}$$

$$\nabla f(x_k) + (u_k)^T \nabla g(x_k) = 0$$

**KKT multipliers:**  $u^*$  IN A LOCAL OPT SOLUTION  $x^*$  OF (P)

**Theorem:** Under some mild conditions IF  $x_k \rightarrow x^* \Rightarrow u_k \rightarrow u^*$