Fast Stochastic Methods

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Last time: conditional gradient method

For the problem

$$\min_x f(x) \text{ subject to } x \in C$$

where $f$ is convex, smooth and $C$ is a convex set, the conditional gradient (Frank-Wolfe) method chooses an initial $x^{(0)}$ and repeats for $k = 1, 2, 3, \ldots$

$$s^{(k-1)} \in \arg\min_{s \in C} \nabla f(x^{(k-1)})^T s$$

$$x^{(k)} = (1 - \gamma_k)x^{(k-1)} + \gamma_k s^{(k-1)}$$

Here $\gamma_k$ is a step size, either prespecified (as in $\gamma_k = 2/(k + 1)$) or chosen by line search

For many problems, linear minimization over $C$ is simpler or more efficient than projection onto $C$, hence the appeal of Frank-Wolfe
Stochastic gradient descent

Consider sum of functions

$$\min_x \frac{1}{n} \sum_{i=1}^{n} f_i(x)$$

Gradient descent applied to this problem would repeat

$$x^{(k)} = x^{(k-1)} - t_k \cdot \frac{1}{n} \sum_{i=1}^{n} \nabla f_i(x^{(k-1)}), \quad k = 1, 2, 3, \ldots$$

In comparison, stochastic gradient descent (or incremental gradient descent) repeats

$$x^{(k)} = x^{(k-1)} - t_k \cdot \nabla f_{i_k}(x^{(k-1)}), \quad k = 1, 2, 3, \ldots$$

where $i_k \in \{1, \ldots n\}$ is some chosen index at iteration $k$
Notes:

- Typically we make a (uniform) random choice $i_k \in \{1, \ldots n\}$
- Also common: mini-batch stochastic gradient descent, where we choose a random subset $I_k \subset \{1, \ldots n\}$, of size $b \ll n$, and update according to

$$x^{(k)} = x^{(k-1)} - t_k \cdot \frac{1}{b} \sum_{i \in I_k} \nabla f_i(x^{(k-1)}), \quad k = 1, 2, 3, \ldots$$

- In both cases, we are approximating the full gradient by a noisy estimate, and our noisy estimate is unbiased

$$\mathbb{E}[\nabla f_{i_k}(x)] = \nabla f(x)$$

$$\mathbb{E}\left[\frac{1}{b} \sum_{i \in I_k} \nabla f_i(x)\right] = \nabla f(x)$$

The mini-batch reduces the variance by a factor $1/b$, but is also $b$ times more expensive!
Example: regularized logistic regression

Given labels $y_i \in \{0, 1\}$, features $x_i \in \mathbb{R}^p$, $i = 1, \ldots, n$. Consider logistic regression with ridge regularization:

$$
\min_{\beta \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^{n} \left( -y_i x_i^T \beta + \log(1 + e^{x_i^T \beta}) \right) + \frac{\lambda}{2} \| \beta \|_2^2
$$

Write the criterion as

$$
f(\beta) = \frac{1}{n} \sum_{i=1}^{n} f_i(\beta), \quad f_i(\beta) = -y_i x_i^T \beta + \log(1 + e^{x_i^T \beta}) + \frac{\lambda}{2} \| \beta \|_2^2
$$

The gradient computation $\nabla f(\beta) = \sum_{i=1}^{n} \left( y_i - p_i(\beta) \right) x_i + \lambda \beta$ is doable when $n$ is moderate, but not when $n$ is huge. Note that:

- One batch update costs $O(np)$
- One stochastic update costs $O(p)$
- One mini-batch update costs $O(bp)$
Example with $n = 10,000$, $p = 20$, all methods employ fixed step sizes (diminishing step sizes give roughly similar results):
What's happening? Iterations make better progress as mini-batch size $b$ gets bigger. But now let’s parametrize by flops:
Convergence rates

Recall that, under suitable step sizes, when $f$ is convex and has a Lipschitz gradient, full gradient (FG) descent satisfies

$$f(x^{(k)}) - f^* = O(1/k)$$

What about stochastic gradient (SG) descent? Under diminishing step sizes, when $f$ is convex (plus other conditions)

$$\mathbb{E}[f(x^{(k)})] - f^* = O(1/\sqrt{k})$$

Finally, what about mini-batch stochastic gradient? Again, under diminishing step sizes, for $f$ convex (plus other conditions)

$$\mathbb{E}[f(x^{(k)})] - f^* = O(1/\sqrt{bk} + 1/k)$$

But each iteration here $b$ times more expensive ... and (for small $b$), in terms of flops, this is the same rate
Back to our ridge logistic regression example, we gain important insight by looking at suboptimality gap (on log scale):
Recall that, under suitable step sizes, when \( f \) is strongly convex with a Lipschitz gradient, gradient descent satisfies

\[
f(x^{(k)}) - f^* = O(\rho^k)
\]

where \( \rho < 1 \). But, under diminishing step sizes, when \( f \) is strongly convex (plus other conditions), stochastic gradient descent gives

\[
\mathbb{E}[f(x^{(k)})] - f^* = O(1/k)
\]

So stochastic methods do not enjoy the linear convergence rate of gradient descent under strong convexity.

For a while, this was believed to be inevitable, as Nemirovski and others had established matching lower bounds ... but these applied to stochastic minimization of criterions, \( f(x) = \int F(x, \xi) \, d\xi \). Can we do better for finite sums?
Outline

Rest of today:

- Stochastic average gradient (SAG)
- SAGA (does this stand for something?)
- Many, many others
Stochastic average gradient (SAG) or SAG (Schmidt, Le Roux, Bach 2013) is a breakthrough method in stochastic optimization. Idea is fairly simple:

- Maintain table, containing gradient $g_i$ of $f_i$, $i = 1, \ldots n$
- Initialize $x^{(0)}$, and $g_i^{(0)} = x^{(0)}$, $i = 1, \ldots n$
- At steps $k = 1, 2, 3, \ldots$, pick a random $i_k \in \{1, \ldots n\}$ and then let

$$g_{i_k}^{(k)} = \nabla f_i(x^{(k-1)}) \quad \text{(most recent gradient of } f_i)$$

Set all other $g_i^{(k)} = g_i^{(k-1)}$, $i \neq i_k$, i.e., these stay the same
- Update

$$x^{(k)} = x^{(k-1)} - t_k \cdot \frac{1}{n} \sum_{i=1}^{n} g_i^{(k)}$$
Notes:

- Key of SAG is to allow each $f_i, i = 1, \ldots, n$ to communicate a part of the gradient estimate at each step
- This basic idea can be traced back to incremental aggregated gradient (Blatt, Hero, Gauchman, 2006)
- SAG gradient estimates are no longer unbiased, but they have greatly reduced variance
- Isn’t it expensive to average all these gradients? (Especially if $n$ is huge?) This is basically just as efficient as stochastic gradient descent, as long we’re clever:

$$x^{(k)} = x^{(k-1)} - t_k \cdot \left( \frac{g_{i_k}^{(k)}}{n} - \frac{g_{i_k}^{(k-1)}}{n} + \frac{1}{n} \sum_{i=1}^{n} g_i^{(k-1)} \right)$$

\begin{align*}
\text{old table average} & \quad \text{new table average}
\end{align*}
SAG convergence analysis

Assume that \( f(x) = \frac{1}{n} \sum_{i=1}^{n} f_i(x) \), where each \( f_i \) is differentiable, and \( \nabla f_i \) is Lipschitz with constant \( L \).

Denote \( \bar{x}(k) = \frac{1}{k} \sum_{\ell=0}^{k-1} x(\ell) \), the average iterate after \( k - 1 \) steps.

**Theorem (Schmidt, Le Roux, Bach):** SAG, with a fixed step size \( t = 1/(16L) \), and the initialization

\[
g_i^{(0)} = \nabla f_i(x^{(0)}) - \nabla f(x^{(0)}), \quad i = 1, \ldots, n
\]

satisfies

\[
\mathbb{E}[f(\bar{x}^{(k)})] - f^* \leq \frac{48n}{k} (f(x^{(0)}) - f^*) + \frac{128L}{k} \|x^{(0)} - x^*\|_2^2
\]

where the expectation is taken over the random choice of index at each iteration.
Notes:

- Result stated in terms of the average iterate $\bar{x}^{(k)}$, but also can be shown to hold for best iterate $x^{(k)}_{\text{best}}$ seen so far
- This is $O(1/k)$ convergence rate for SAG. Compare to $O(1/k)$ rate for FG, and $O(1/\sqrt{k})$ rate for SG
- But, the constants are different! Bounds after $k$ steps:

  \[
  \text{SAG} : \quad \frac{48n}{k} (f(x^{(0)}) - f^*) + \frac{128L}{k} \|x^{(0)} - x^*\|_2^2 \\
  \text{FG} : \quad \frac{L}{2k} \|x^{(0)} - x^*\|_2^2 \\
  \text{SG}^* : \quad \frac{L\sqrt{5}}{\sqrt{2k}} \|x^{(0)} - x^*\|_2 \quad (*\text{not a real bound, loose translation})
  \]

- So first term in SAG bound suffers from factor of $n$; authors suggest smarter initialization to make $f(x^{(0)}) - f^*$ small (e.g., they suggest using result of $n$ SG steps)
Convergence analysis under strong convexity

Assume further that each $f_i$ is strongly convex with parameter $m$

**Theorem (Schmidt, Le Roux, Bach):** SAG, with a step size $t = 1/(16L)$ and the same initialization as before, satisfies

$$\mathbb{E}[f(x^{(k)})] - f^* \leq \left(1 - \min\left\{ \frac{m}{16L}, \frac{1}{8n} \right\} \right)^k \cdot \left(\frac{3}{2}(f(x^{(0)}) - f^*) + \frac{4L}{n} \|x^{(0)} - x^*\|_2^2\right)$$

More notes:

- This is **linear** convergence rate $O(\rho^k)$ for SAG. Compare this to $O(\rho^k)$ for FG, and only $O(1/k)$ for SG
- Like FG, we say SAG is **adaptive to strong convexity** (achieves better rate with same settings)
- Proofs of these results **not easy**: 15 pages, computed-aided!
Back to our ridge logistic regression example, SG versus SAG, over 30 reruns of these randomized algorithms:
• SAG does well, but did not work out of the box; required a specific setup
• Took one full cycle of SG (one pass over the data) to get $\beta^{(0)}$, and then started SG and SAG both from $\beta^{(0)}$. This warm start helped a lot
• SAG initialized at $g_i^{(0)} = \nabla f_i(\beta^{(0)})$, $i = 1, \ldots, n$, computed during initial SG cycle. Centering these gradients was much worse (and so was initializing them at 0)
• Tuning the fixed step sizes for SAG was very finicky; here now hand-tuned to be about as large as possible before it diverges
• Authors of SAG conveyed that this algorithm will work the best, relative to SG, for ill-conditioned problems (the current problem not being ill-conditioned at all)
Experiments from Schmidt, Le Roux, Bach (each plot is a different problem setting):
SAGA (Defazio, Bach, Lacoste-Julien, 2014) is another recent stochastic method, similar in spirit to SAG. Idea is again simple:

- Maintain table, containing gradient $g_i$ of $f_i$, $i = 1, \ldots n$
- Initialize $x^{(0)}$, and $g_i^{(0)} = x^{(0)}$, $i = 1, \ldots n$
- At steps $k = 1, 2, 3, \ldots$, pick a random $i_k \in \{1, \ldots n\}$ and then let

$$g_{i_k}^{(k)} = \nabla f_i(x^{(k-1)}) \quad \text{(most recent gradient of } f_i)$$

Set all other $g_i^{(k)} = g_i^{(k-1)}$, $i \neq i_k$, i.e., these stay the same

- Update

$$x^{(k)} = x^{(k-1)} - t_k \cdot \left( g_{i_k}^{(k)} - g_{i_k}^{(k-1)} + \frac{1}{n} \sum_{i=1}^{n} g_i^{(k-1)} \right)$$
Notes:

- SAGA gradient estimate \( g^{(k)}_i - g^{(k-1)}_i + \frac{1}{n} \sum_{i=1}^{n} g^{(k-1)}_i \), versus SAG gradient estimate \( \frac{1}{n} g^{(k)}_i - \frac{1}{n} g^{(k-1)}_i + \frac{1}{n} \sum_{i=1}^{n} g^{(k-1)}_i \).

- Recall, SAG estimate is biased; remarkably, SAGA estimate is unbiased! Simple explanation, following a variance reduction principle: consider a family of estimators

\[
\theta_\alpha = \alpha (X - Y) + \mathbb{E}(Y)
\]

for \( \mathbb{E}(X) \), where \( \alpha \in [0, 1] \), and \( X, Y \) are presumed to be correlated. We have

\[
\mathbb{E}(\theta_\alpha) = \alpha \mathbb{E}(X) + (1 - \alpha) \mathbb{E}(Y)
\]

\[
\text{Var}(\theta_\alpha) = \alpha^2 \left( \text{Var}(X) + \text{Var}(Y) - 2 \text{Cov}(X, Y) \right)
\]

SAGA uses \( \alpha = 1 \) (unbiased), SAG uses \( \alpha = 1/n \) (biased).
• SAGA basically matches strong convergence rates of SAG (for both Lipschitz gradients, and strongly convex cases), but the proofs here much simpler

• Another strength of SAGA is that it can extend to composite problems of the form

$$\min_x \frac{1}{n} \sum_{i=1}^{m} f_i(x) + h(x)$$

where each $f_i$ is smooth and convex, and $h$ is convex and nonsmooth but has a known prox. The updates are now

$$x^{(k)} = \text{prox}_{h, t_k} \left( x^{(k-1)} - t_k \cdot \left( g_i^{(k)} - g_i^{(k-1)} + \frac{1}{n} \sum_{i=1}^{n} g_i^{(k-1)} \right) \right)$$

• It is not known whether SAG is generally convergent under such a scheme
Back to our ridge logistic regression example, now adding SAGA to the mix:
• SAGA does well, but again it required somewhat specific setup
• As before, took one full cycle of SG (one pass over the data) to get $\beta^{(0)}$, and then started SG, SAG, SAGA all from $\beta^{(0)}$. This **warm start helped** a lot
• SAGA initialized at $g_i^{(0)} = \nabla f_i(\beta^{(0)})$, $i = 1, \ldots n$, computed during initial SG cycle. Centering these gradients was much worse (and so was initializing them at 0)
• Tuning the fixed step sizes for SAGA was fine; seemingly on par with tuning for SG, and more robust than tuning for SAG
• Interestingly, the SAGA criterion curves look like SG curves (realizations being jagged and highly variable); SAG looks very different, and this really emphasizes the fact that its updates have **much lower variance**
Many, many others

A lot of recent work revisiting stochastic optimization:

- **SDCA** (Shalev-Schwartz, Zhang, 2013): applies coordinate ascent to the dual of ridge regularized problems, and uses randomly selected coordinates. Effective primal updates are similar to SAG/SAGA
- **SVRG** (Johnson, Zhang, 2013): like SAG/SAGA, but does not store a full table of gradients, just an average, and updates this occasionally
- There’s also **S2GD** (Konecny, Richtarik, 2014), **MISO** (Mairal, 2013), **Finito** (Defazio, Caetano, Domke, 2014), etc.
- Both the SAG and SAGA papers give very nice reviews and discuss connections
The vector \( \bar{x} \) is unbiased \( \mathbb{E}(\bar{x}) = x \). By varying the direction sample \( Y \), one can get bias \( \mathbb{E}(\bar{x}) = f(Y) \neq x \). The standard variance reduction approach uses the following estimator for minimizing finite sums (see (5) below).

The SVRG update (6) is obtained by using \( \bar{x} \) and \( Y \) as.

In [5], the authors make the observation that the variance of the standard stochastic gradient (SGD) for minimizing finite sums is unbiased \( \mathbb{E}(\bar{x}) = x \). One advantage of SVRG over SAGA is that it does not require a memory buffer to store old gradients.

The SVRG method [8] has the same update as SVRG, just differing in how the number of inner loop iterations is chosen. We use SVRG henceforth to refer to both methods.

By using an unbiased update in SAGA, we are able to obtain a simple and tight theory, with better constants than SAG, as well as theoretical rates for the use of proximal operators.

Leaves three possibilities: (i) algorithms we currently have are not optimal; (ii) lower bounds can be tightened; or (iii) upper bounds can be tightened.

Are we approaching optimality with these methods? Agarwal and Bottou (2014) recently proved nonmatching lower bounds for minimizing finite sums.

Very active area of research, this will likely be sorted out soon.

(From Defazio, Bach, Lacoste-Julien, 2014)
References and further reading

• R. Johnson and T. Zhang (2013), “Accelerating stochastic gradient descent using predictive variance reduction”
• A. Nemirosvki and A. Juditsky and G. Lan and A. Shapiro (2009), “Robust stochastic optimization approach to stochastic programming”
• M. Schmidt and N. Le Roux and F. Bach (2013), “Minimizing finite sums with the stochastic average gradient”
• S. Shalev-Shwartz and T. Zhang (2013), “Stochastic dual coordinate ascent methods for regularized loss minimization”