

Observe:

$$\begin{bmatrix} \nabla^2 f(x) & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} v \\ w \end{bmatrix} = - \begin{bmatrix} \nabla f(x) \\ Ax - b \end{bmatrix}$$

\Leftrightarrow

$$\begin{bmatrix} \nabla^2 f(x) & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} v \\ w \end{bmatrix} = - \begin{bmatrix} \nabla f(x) + A^T y \\ Ax - b \end{bmatrix}$$

Special case: when $Ax = b$, get

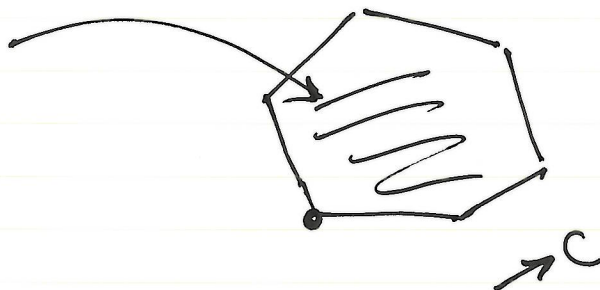
$$\begin{bmatrix} \nabla^2 f(x) & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} v \\ w \end{bmatrix} = - \begin{bmatrix} \nabla f(x) \\ 0 \end{bmatrix}$$

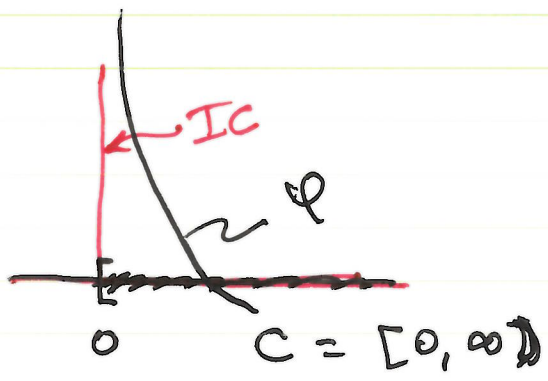
Special case: LP

$$\min_x c^T x$$

$$Dx \leq e$$

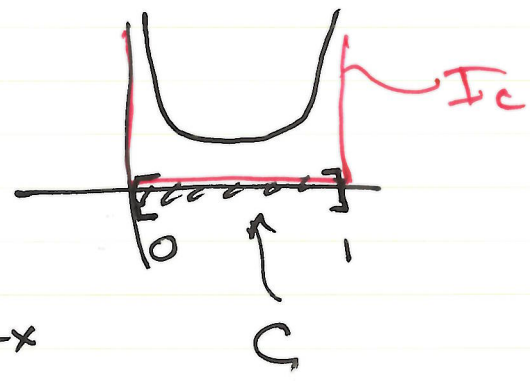
$\{x: Dx \leq e\}$





barrier: $-\log(x) = \varphi(x)$

More interesting ptc



barrier: $-\log(x) - \log(1-x)$



Example

$$\varphi(x) = - \sum_{i=1}^n \log x_i \iff h(x) = -x_i$$

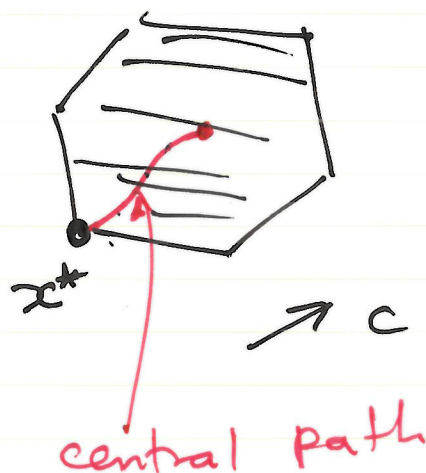
$$\nabla \varphi(x) = - \begin{bmatrix} 1/x_1 \\ \vdots \\ 1/x_n \end{bmatrix} = -X^{-1} \mathbf{1}$$

$$X = \text{Diag}(x)$$

$$\nabla^2 \varphi(x) = \begin{bmatrix} 1/x_1^2 & & \\ & \dots & \\ & & 1/x_n^2 \end{bmatrix} = X^{-2}$$

LPmin $c^T x$

$$Dx \leq e$$



Observe: KKT condns for barrier problem

Put \bullet $u_i(t) := -\frac{1}{t h_i(x^*(t))}$, $v := \frac{1}{t} w$

Rewrite as follows

$$\left. \begin{aligned} \nabla f(x^*(t)) + \sum_{i=1}^m u_i(t) \nabla h_i(x^*(t)) + A^T v &= 0 \\ A x^*(t) &= b, \quad u_i(t) h_i(x^*(t)) = -\frac{1}{t} \\ h_i(x^*(t)) &< 0 \\ u_i(t) &> 0 \end{aligned} \right\}$$

Duality gap derivation

$$\begin{aligned}
 & f(x^*(t)) - f(x^*) + \sum_{i=1}^m u_i(t) (h_i(x^*(t)) - h_i(x^*)) \\
 & \leq \left\langle \underbrace{\nabla f(x^*(t)) + \sum_{i=1}^m u_i(t) \nabla h_i(x^*(t))}_{-A^T v}, x^*(t) - x^* \right\rangle
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow f(x^*(t)) - f(x^*) & \leq \frac{M}{t} + \underbrace{\sum_{i=1}^m u_i(t) h_i(x^*(t))}_{\leq 0} \\
 & \leq \frac{M}{t} .
 \end{aligned}$$

An example of a SCB :

$$\phi(x) = - \sum \log x_i$$

$$\lambda(x)^2 = n$$