

$$A \in \mathbb{R}^{r \times n}$$

$$Ax^*(t) = b \quad h_i(x^*(t)) < 0 \quad i=1, \dots, m$$

$$\nabla f(x^*(t)) + \sum_{i=1}^m \underbrace{\frac{-1}{h_i(x^*(t))t}}_{u_i^*(t)} \nabla h_i(x^*(t)) + A^T \underbrace{\frac{w}{t}}_{v^*(t)} = 0$$

for some $w \in \mathbb{R}^r$

define $(u^*(t), v^*(t))$ by:

$$u_i^*(t) = \frac{-1}{th_i(x^*(t))} \quad v_i^*(t) = \frac{w}{t}$$

claim: $(u^*(t), v^*(t))$ are feasible for original problem

$$\begin{aligned} \min_x & f(x) \\ \text{st} & h_i(x) \leq 0 \quad i=1, \dots, m \\ & Ax = b \end{aligned}$$

• Sign check: $u_i^*(t) = \frac{-1}{th_i(x^*(t))} \geq 0$ all i

• domain check:

$$g(u, v) = \min_x L(x, u, v)$$

domain of g is all points (u, v) , $u \geq 0$, such that $\min_x L(x, u, v) > -\infty$

$L(x, u^*(t), v^*(t))$ minimized at $x = x^*(t)$

✓ comes from centrality condition

$$(A + aa^T)x = b$$

$$\min \frac{1}{2}x^T Q x + c^T x \quad \text{s.t.} \quad Ax = b$$

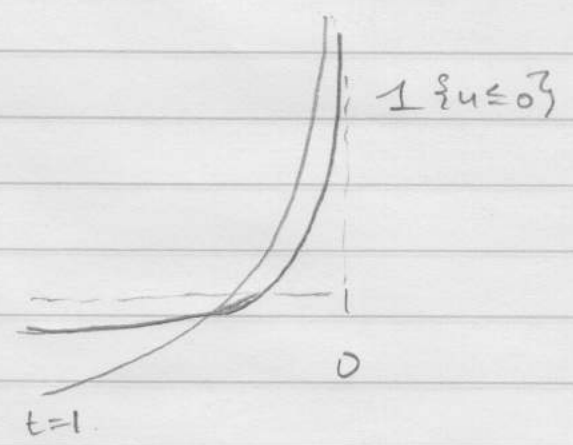
$$\begin{bmatrix} Q & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} x \\ \nu \end{bmatrix} = \begin{bmatrix} -c \\ b \end{bmatrix}$$

$$\min f(x) \quad \text{s.t.} \quad Ax = b$$

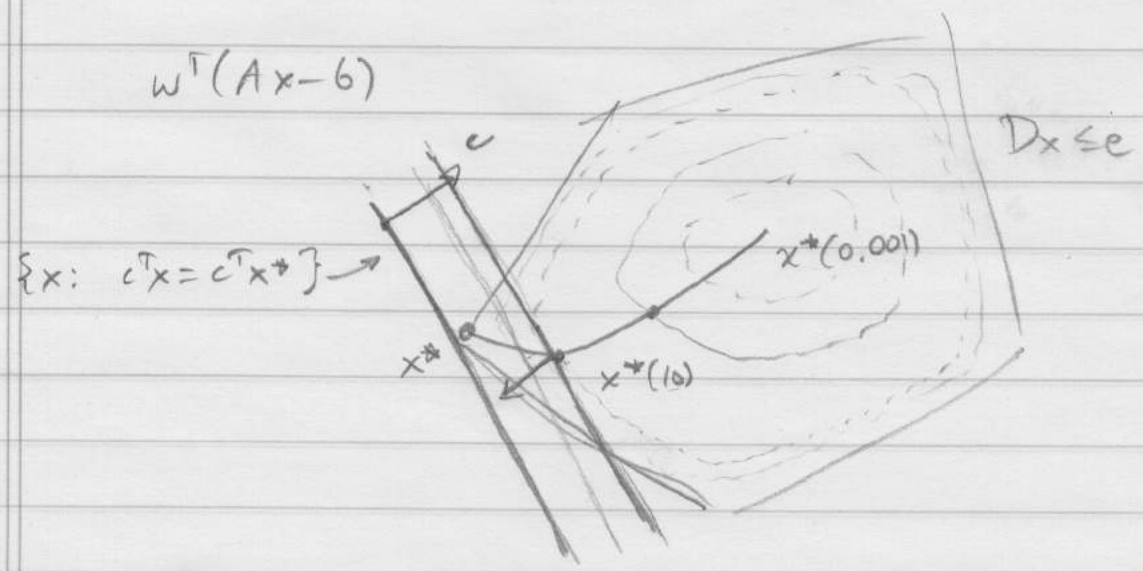
$$\min f(x) \quad \text{s.t.} \quad Ax = b$$

$$h_i(x) \leq 0 \quad i=1, \dots, m$$

$$-\frac{1}{t} \log(-w)$$



$$w^T(Ax - b)$$



$$\min_{\beta} L(\beta) + \lambda R(\beta)$$

solve over λ .

$$L(\beta) = \|y - X\beta\|_2^2$$

$$R(\beta) = \|\beta\|_2^2$$

$$\min_{\beta} \|y - X\beta\|_2^2$$

$$\|\beta\|_2^2 \leq t$$