Quiz 2

Convex Optimization, 10-725 Due Friday September 27, 2019

Name:

Andrew ID:

Each question is either in true/false format, or multiple choice. For multiple choice, just choose the single best option. In each case, make sure to fill in the box according to the answer you choose (true or false, or the multiple choice option) completely. All questions are worth 1 point.

1. Gradient descent on a convex function with Lipschitz gradient converges (with suitable step sizes) at the rate:

 $\Box \text{ a. } O(1/\epsilon^2);$ $\Box \text{ b. } O(1/\epsilon);$ $\Box \text{ c. } O(\log(1/\epsilon));$ $\Box \text{ d. } O(1/\sqrt{\epsilon}).$

2. Consider the backtracking loop:

repeat
$$t = \beta t$$

until $f(x + tv) \le f(x) + \alpha t \nabla f(x)^T v$,

where v is the descent direction. A larger value of α leads to fewer backtracking iterations until the backtracking exit condition is satisfied.

 \Box True

 \Box False

3. Applying Nesterov's acceleration to gradient descent still results in a descent method. □ True

 \Box False

- 4. If g(x) = f(Ax + b), where f is convex, then subgradients of g are defined by: \Box a. $\partial q(x) = \partial f(Ax + b)$;
 - $\Box \text{ b. } \partial g(x) = A^T \partial f(Ax + b);$

 \Box c. $\partial g(x) = A \partial f(Ax + b);$

 \Box d. g need not have subgradients, because it need not be convex.

- 5. The subdifferential of any function f is always a convex set.
 - \Box True \Box False
- 6. For any function f, a point x minimizes f if and only if $0 \in \partial f(x)$.
 - \Box False
- 7. For any differentiable function f, its subdifferential at a point x is the singleton $\{\nabla f(x)\}$.
 - □ True
 - \Box False
- 8. Applying the subgradient method requires knowledge of the full subdifferential of the function in question.
 - □ True
 - \Box False

- 9. For the problem of logistic regression with a ridge penalty (i.e., squared ℓ_2 penalty on the parameters), gradient descent and subgradient method, both with same fixed step size, will:
 - \Box a. converge at different rates, with gradient descent being faster;
 - \Box b. converge at different rates, with gradient descent being slower;
 - \Box c. converge at the same rate, because they're doing the exact same thing!
 - \Box d. it depends on the condition number of $X^T X$, with X being the matrix of predictors.
- 10. The subgradient method is a descent method.
 - \Box True
 - \Box False
- 11. The subgradient method achieves the optimal rate among nonsmooth first-order methods for minimizing convex functions that are Lipschitz.
 - \Box True
 - \Box False
- 12. Proximal gradient descent is most appealing when the prox is cheap, since convergence (in terms of the number of iterations) will be on par with first-order methods.
 - □ True
 - \Box False
- 13. The proximal operator of $h(x) = ||x||_1$ is given by:
 - \Box a. soft-thresholding;
 - \Box b. hard-thresholding;
 - \Box c. projection onto the ℓ_1 ball;
 - \Box d. not known.
- 14. For the lasso problem, proximal gradient descent, i.e., ISTA, will often converge:
 - \Box a. about on par with the subgradient method;
 - \Box b. faster than the subgradient method;
 - \Box c. slower than the subgradient method;

 \Box d. this is an unfair comparison because these two methods have very different computational costs per iteration.

15. For any convex function f and t > 0, the proximal operator of f,

$$\operatorname{prox}_{f,t}(x) = \underset{z}{\operatorname{argmin}} \ \frac{1}{2t} \|x - z\|_2^2 + f(z),$$

is well-defined (meaning the above minimization has a unique solution).

- \Box True
- \Box False
- 16. Stochastic methods are generally well-suited to an objective that is a sum of a large number of functions.
 □ True
 - \Box False
- 17. Taking larger mini-batches in stochastic gradient descent:
 - \Box a. reduces the variance, at no additional computational expense;
 - \Box b. reduces the variance, increases the computational cost of an iteration;
 - \Box c. reduces the bias, reduces the variance;
 - \Box d. does not change the variance, but improves communication costs.
- 18. For stochastic gradient descent, step sizes are commonly chosen by backtracking line search.
 - \Box True
 - \Box False
- 19. Stochastic gradient descent on a convex function that is Lipschitz, converges (with suitable step sizes) at the rate:

 \Box a. $O(1/\epsilon)$;

 $\label{eq:constraint} \begin{array}{l} \square \mbox{ b. } O(1/\sqrt{\epsilon}); \\ \square \mbox{ c. } O(1/\epsilon^2); \\ \square \mbox{ d. } O(\log(1/\epsilon)). \end{array}$

 $20. \ {\rm Stochastic \ gradient \ descent \ is \ a \ descent \ method.}$

 \Box True

 \Box False